
Show all appropriate work.

1. Problems from the book: (Again, a scan of the problems are attached to the end of this pdf.)
 - (a) Section 1.3: 5, 6, 14.
 - (b) Section 2.1: 4, 5, 12, 16, 29.
 - (c) Section 2.2: 21.

Solution Solve the (linear triangular) system $Ax = b$ from top to bottom:

$$\begin{array}{l} \text{first } x_1 = b_1 \\ \text{then } x_2 = b_1 + b_2 \\ \text{then } x_3 = b_2 + b_3 \end{array} \quad \text{This says that } x = A^{-1}b = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

This is good practice to see the columns of the inverse matrix multiplying $b_1, b_2,$ and b_3 . The first column of A^{-1} is the solution for $b = (1, 0, 0)$. The second column is the solution for $b = (0, 1, 0)$. The third column x of A^{-1} is the solution for $Ax = b = (0, 0, 1)$.

The three columns of A are still independent. They don't lie in a plane. The combinations of those three columns, using the right weights x_1, x_2, x_3 , can produce any three-dimensional vector $b = (b_1, b_2, b_3)$. Those weights come from $x = A^{-1}b$.

1.3 B This E is an **elimination matrix**. E has a subtraction, E^{-1} has an addition.

$$Ex = b \quad \begin{bmatrix} 1 & 0 \\ -\ell & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad E = \begin{bmatrix} 1 & 0 \\ -\ell & 1 \end{bmatrix}$$

The first equation is $x_1 = b_1$. The second equation is $x_2 - \ell x_1 = b_2$. The inverse will add $\ell x_1 = \ell b_1$, because the elimination matrix *subtracted* ℓx_1 :

$$x = E^{-1}b \quad \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ \ell b_1 + b_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \ell & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad E^{-1} = \begin{bmatrix} 1 & 0 \\ \ell & 1 \end{bmatrix}$$

1.3 C Change C from a cyclic difference to a **centered difference** producing $x_3 - x_1$:

$$Cx = b \quad \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_2 - 0 \\ x_3 - x_1 \\ 0 - x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}. \quad (15)$$

Show that $Cx = b$ can only be solved when $b_1 + b_3 = 0$. That is a plane of vectors b in three-dimensional space. Each column of C is in the plane, the matrix has no inverse. So this plane contains all combinations of those columns (which are all the vectors Cx).

Solution The first component of $b = Cx$ is x_2 , and the last component of b is $-x_2$. So we always have $b_1 + b_3 = 0$, for every choice of x .

If you draw the column vectors in C , the first and third columns fall on the same line. In fact (column 1) = -(column 3). So the three columns will lie in a plane, and C is *not* an invertible matrix. We cannot solve $Cx = b$ unless $b_1 + b_3 = 0$.

I included the zeros so you could see that this matrix produces "centered differences". Row i of Cx is x_{i+1} (right of center) minus x_{i-1} (left of center). Here is the 4 by 4 centered difference matrix:

$$Cx = b \quad \begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_2 - 0 \\ x_3 - x_1 \\ x_4 - x_2 \\ 0 - x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \quad (16)$$

Surprisingly this matrix is now invertible! The first and last rows give x_2 and x_3 . Then the middle rows give x_1 and x_4 . It is possible to write down the inverse matrix C^{-1} . But 5 by 5 will be singular (*not invertible*) again ...

Problem Set 1.3

- 1 Find the linear combination $2s_1 + 3s_2 + 4s_3 = b$. Then write b as a matrix-vector multiplication Sx . Compute the dot products (row of S) $\cdot x$:

$$s_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad s_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad s_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{go into the columns of } S.$$

- 2 Solve these equations $Sy = b$ with s_1, s_2, s_3 in the columns of S :

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 9 \end{bmatrix}.$$

The sum of the first n odd numbers is _____.

- 3 Solve these three equations for y_1, y_2, y_3 in terms of B_1, B_2, B_3 :

$$Sy = B \quad \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} B_1 \\ B_2 \\ B_3 \end{bmatrix}.$$

Write the solution y as a matrix $A = S^{-1}$ times the vector B . Are the columns of S independent or dependent?

- 4 Find a combination $x_1w_1 + x_2w_2 + x_3w_3$ that gives the zero vector:

$$w_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad w_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad w_3 = \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix}.$$

Those vectors are (independent) (dependent). The three vectors lie in a _____. The matrix W with those columns is *not invertible*.

- 5 The rows of that matrix W produce three vectors (I write them as columns):

$$r_1 = \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix} \quad r_2 = \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix} \quad r_3 = \begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix}.$$

Linear algebra says that these vectors must also lie in a plane. There must be many combinations with $y_1r_1 + y_2r_2 + y_3r_3 = \mathbf{0}$. Find two sets of y 's.

- 6 Which values of c give dependent columns (combination equals zero)?

$$\begin{bmatrix} 1 & 3 & 5 \\ 1 & 2 & 4 \\ 1 & 1 & c \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & c \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad \begin{bmatrix} c & c & c \\ 2 & 1 & 5 \\ 3 & 3 & 6 \end{bmatrix}$$

- 7 If the columns combine into $Ax = 0$ then each row has $r \cdot x = 0$:

$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{By rows} \quad \begin{bmatrix} r_1 \cdot x \\ r_2 \cdot x \\ r_3 \cdot x \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

The three rows also lie in a plane. Why is that plane perpendicular to x ?

- 8 Moving to a 4 by 4 difference equation $Ax = b$, find the four components x_1, x_2, x_3, x_4 . Then write this solution as $x = Sb$ to find the inverse matrix $S = A^{-1}$:

$$Ax = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} = b.$$

- 9 What is the *cyclic* 4 by 4 difference matrix C ? It will have 1 and -1 in each row. Find all solutions $x = (x_1, x_2, x_3, x_4)$ to $Cx = 0$. The four columns of C lie in a "three-dimensional hyperplane" inside four-dimensional space.
- 10 A *forward* difference matrix Δ is *upper* triangular:

$$\Delta z = \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} = \begin{bmatrix} z_2 - z_1 \\ z_3 - z_2 \\ 0 - z_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = b.$$

Find z_1, z_2, z_3 from b_1, b_2, b_3 . What is the inverse matrix in $z = \Delta^{-1}b$?

- 11 Show that the forward differences $(t+1)^2 - t^2$ are $2t+1 = \text{odd numbers}$. As in calculus, the difference $(t+1)^n - t^n$ will begin with the derivative of t^n , which is _____.
- 12 The last lines of the Worked Example say that the 4 by 4 centered difference matrix in (16) is invertible. Solve $Cx = (b_1, b_2, b_3, b_4)$ to find its inverse in $x = C^{-1}b$.

Challenge Problems

- 13 The very last words say that the 5 by 5 centered difference matrix is *not* invertible. Write down the 5 equations $Cx = b$. Find a combination of left sides that gives zero. What combination of b_1, b_2, b_3, b_4, b_5 must be zero? (The 5 columns lie on a "4-dimensional hyperplane" in 5-dimensional space.)
- 14 If (a, b) is a multiple of (c, d) with $abcd \neq 0$, show that (a, c) is a multiple of (b, d) . This is surprisingly important; two columns are falling on one line. You could use numbers first to see how a, b, c, d are related. The question will lead to:

The matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ has dependent columns when it has dependent rows.

Chapter 2

Solving Linear Equations

2.1 Vectors and Linear Equations

The central problem of linear algebra is to solve a system of equations. Those equations are linear, which means that the unknowns are only multiplied by numbers—we never see x times y . Our first linear system is certainly not big. But you will see how far it leads:

$$\begin{array}{l} \text{Two equations} \\ \text{Two unknowns} \end{array} \quad \begin{array}{l} x - 2y = 1 \\ 3x + 2y = 11 \end{array} \quad (1)$$

We begin *a row at a time*. The first equation $x - 2y = 1$ produces a straight line in the xy plane. The point $x = 1, y = 0$ is on the line because it solves that equation. The point $x = 3, y = 1$ is also on the line because $3 - 2 = 1$. If we choose $x = 101$ we find $y = 50$.

The slope of this particular line is $\frac{1}{2}$, because y increases by 1 when x changes by 2. But slopes are important in calculus and this is linear algebra!

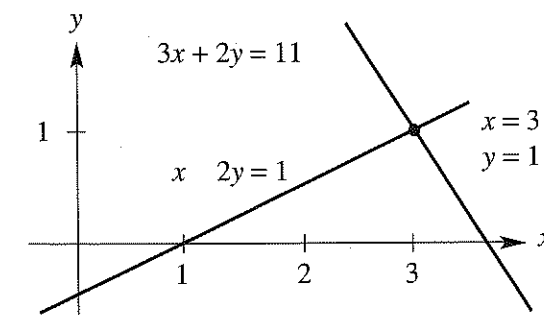


Figure 2.1: Row picture: The point $(3, 1)$ where the lines meet is the solution.

Figure 2.1 shows that line $x - 2y = 1$. The second line in this "row picture" comes from the second equation $3x + 2y = 11$. You can't miss the intersection point where the

- (2) The dot product of each column of A with $y = (1, 1, -1)$ is zero. On the right side, $y \cdot b = (1, 1, -1) \cdot (4, 5, 8) = 1$ is not zero. So a solution is impossible.
- (3) There is a solution when b is a combination of the columns. These three choices of b have solutions $x^* = (1, 0, 0)$ and $x^{**} = (1, 1, 1)$ and $x^{***} = (0, 0, 0)$:

$$b^* = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \text{first column} \quad b^{**} = \begin{bmatrix} 9 \\ 0 \\ 9 \end{bmatrix} = \text{sum of columns} \quad b^{***} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Problem Set 2.1

Problems 1–8 are about the row and column pictures of $Ax = b$.

- 1 With $A = I$ (the identity matrix) draw the planes in the row picture. Three sides of a box meet at the solution $x = (x, y, z) = (2, 3, 4)$:

$$\begin{aligned} 1x + 0y + 0z &= 2 \\ 0x + 1y + 0z &= 3 \\ 0x + 0y + 1z &= 4 \end{aligned} \quad \text{or} \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

Draw the vectors in the column picture. Two times column 1 plus three times column 2 plus four times column 3 equals the right side b .

- 2 If the equations in Problem 1 are multiplied by 2, 3, 4 they become $DX = B$:

$$\begin{aligned} 2x + 0y + 0z &= 4 \\ 0x + 3y + 0z &= 9 \\ 0x + 0y + 4z &= 16 \end{aligned} \quad \text{or} \quad DX = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 9 \\ 16 \end{bmatrix} = B$$

Why is the row picture the same? Is the solution X the same as x ? What is changed in the column picture—the columns or the right combination to give B ?

- 3 If equation 1 is added to equation 2, which of these are changed: the planes in the row picture, the vectors in the column picture, the coefficient matrix, the solution? The new equations in Problem 1 would be $x = 2$, $x + y = 5$, $z = 4$.
- 4 Find a point with $z = 2$ on the intersection line of the planes $x + y + 3z = 6$ and $x - y + z = 4$. Find the point with $z = 0$. Find a third point halfway between.
- 5 The first of these equations plus the second equals the third:

$$\begin{aligned} x + y + z &= 2 \\ x + 2y + z &= 3 \\ 2x + 3y + 2z &= 5. \end{aligned}$$

The first two planes meet along a line. The third plane contains that line, because if x, y, z satisfy the first two equations then they also _____. The equations have infinitely many solutions (the whole line L). Find three solutions on L .

- 6 Move the third plane in Problem 5 to a parallel plane $2x + 3y + 2z = 9$. Now the three equations have no solution—why not? The first two planes meet along the line L , but the third plane doesn't _____ that line.
- 7 In Problem 5 the columns are $(1, 1, 2)$ and $(1, 2, 3)$ and $(1, 1, 2)$. This is a "singular case" because the third column is _____. Find two combinations of the columns that give $b = (2, 3, 5)$. This is only possible for $b = (4, 6, c)$ if $c =$ _____.
- 8 Normally 4 "planes" in 4-dimensional space meet at a _____. Normally 4 column vectors in 4-dimensional space can combine to produce b . What combination of $(1, 0, 0, 0)$, $(1, 1, 0, 0)$, $(1, 1, 1, 0)$, $(1, 1, 1, 1)$ produces $b = (3, 3, 3, 2)$? What 4 equations for x, y, z, t are you solving?

Problems 9–14 are about multiplying matrices and vectors.

- 9 Compute each Ax by dot products of the rows with the column vector:

$$(a) \begin{bmatrix} 1 & 2 & 4 \\ -2 & 3 & 1 \\ -4 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} \quad (b) \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}$$

- 10 Compute each Ax in Problem 9 as a combination of the columns:

$$9(a) \text{ becomes } Ax = 2 \begin{bmatrix} 1 \\ -2 \\ -4 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} \\ \\ \end{bmatrix}.$$

How many separate multiplications for Ax , when the matrix is "3 by 3"?

- 11 Find the two components of Ax by rows or by columns:

$$\begin{bmatrix} 2 & 3 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 2 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 3 & 6 \\ 6 & 12 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}.$$

- 12 Multiply A times x to find three components of Ax :

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 2 & 1 & 3 \\ 1 & 2 & 3 \\ 3 & 3 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 2 & 1 \\ 1 & 2 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

- 13 (a) A matrix with m rows and n columns multiplies a vector with _____ components to produce a vector with _____ components.
- (b) The planes from the m equations $Ax = b$ are in _____-dimensional space. The combination of the columns of A is in _____-dimensional space.

- 14 Write $2x + 3y + z + 5t = 8$ as a matrix A (how many rows?) multiplying the column vector $x = (x, y, z, t)$ to produce b . The solutions x fill a plane or "hyperplane" in 4-dimensional space. *The plane is 3-dimensional with no 4D volume.*

Problems 15–22 ask for matrices that act in special ways on vectors.

- 15 (a) What is the 2 by 2 identity matrix? I times $\begin{bmatrix} x \\ y \end{bmatrix}$ equals $\begin{bmatrix} x \\ y \end{bmatrix}$.
 (b) What is the 2 by 2 exchange matrix? P times $\begin{bmatrix} x \\ y \end{bmatrix}$ equals $\begin{bmatrix} y \\ x \end{bmatrix}$.
- 16 (a) What 2 by 2 matrix R rotates every vector by 90° ? R times $\begin{bmatrix} x \\ y \end{bmatrix}$ is $\begin{bmatrix} -y \\ x \end{bmatrix}$.
 (b) What 2 by 2 matrix R^2 rotates every vector by 180° ?
- 17 Find the matrix P that multiplies (x, y, z) to give (y, z, x) . Find the matrix Q that multiplies (y, z, x) to bring back (x, y, z) .
- 18 What 2 by 2 matrix E subtracts the first component from the second component? What 3 by 3 matrix does the same?

$$E \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix} \quad \text{and} \quad E \begin{bmatrix} 3 \\ 5 \\ 7 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ 7 \end{bmatrix}.$$

- 19 What 3 by 3 matrix E multiplies (x, y, z) to give $(x, y, z + x)$? What matrix E^{-1} multiplies (x, y, z) to give $(x, y, z - x)$? If you multiply $(3, 4, 5)$ by E and then multiply by E^{-1} , the two results are (____) and (____).
- 20 What 2 by 2 matrix P_1 projects the vector (x, y) onto the x axis to produce $(x, 0)$? What matrix P_2 projects onto the y axis to produce $(0, y)$? If you multiply $(5, 7)$ by P_1 and then multiply by P_2 , you get (____) and (____).
- 21 What 2 by 2 matrix R rotates every vector through 45° ? The vector $(1, 0)$ goes to $(\sqrt{2}/2, \sqrt{2}/2)$. The vector $(0, 1)$ goes to $(-\sqrt{2}/2, \sqrt{2}/2)$. Those determine the matrix. Draw these particular vectors in the xy plane and find R .
- 22 Write the dot product of $(1, 4, 5)$ and (x, y, z) as a matrix multiplication Ax . The matrix A has one row. The solutions to $Ax = 0$ lie on a _____ perpendicular to the vector _____. The columns of A are only in _____-dimensional space.
- 23 In MATLAB notation, write the commands that define this matrix A and the column vectors x and b . What command would test whether or not $Ax = b$?

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad x = \begin{bmatrix} 5 \\ -2 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 7 \end{bmatrix}$$

- 24 The MATLAB commands $A = \text{eye}(3)$ and $v = [3:5]'$ produce the 3 by 3 identity matrix and the column vector $(3, 4, 5)$. What are the outputs from $A*v$ and $v'*v$? (Computer not needed!) If you ask for $v*A$, what happens?

- 25 If you multiply the 4 by 4 all-ones matrix $A = \text{ones}(4)$ and the column $v = \text{ones}(4, 1)$, what is $A*v$? (Computer not needed.) If you multiply $B = \text{eye}(4) + \text{ones}(4)$ times $w = \text{zeros}(4, 1) + 2*\text{ones}(4, 1)$, what is $B*w$?

Questions 26–28 review the row and column pictures in 2, 3, and 4 dimensions.

- 26 Draw the row and column pictures for the equations $x - 2y = 0$, $x + y = 6$.
- 27 For two linear equations in three unknowns x, y, z , the row picture will show (2 or 3) (lines or planes) in (2 or 3)-dimensional space. The column picture is in (2 or 3)-dimensional space. The solutions normally lie on a _____.
- 28 For four linear equations in two unknowns x and y , the row picture shows four _____. The column picture is in _____-dimensional space. The equations have no solution unless the vector on the right side is a combination of _____.
- 29 Start with the vector $u_0 = (1, 0)$. Multiply again and again by the same "Markov matrix" $A = [.8 \ .3; .2 \ .7]$. The next three vectors are u_1, u_2, u_3 :

$$u_1 = \begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} .8 \\ .2 \end{bmatrix} \quad u_2 = Au_1 = \text{_____} \quad u_3 = Au_2 = \text{_____}.$$

What property do you notice for all four vectors u_0, u_1, u_2, u_3 ?

Challenge Problems

- 30 Continue Problem 29 from $u_0 = (1, 0)$ to u_7 , and also from $v_0 = (0, 1)$ to v_7 . What do you notice about u_7 and v_7 ? Here are two MATLAB codes, with while and for. They plot u_0 to u_7 and v_0 to v_7 . You can use other languages:

```
u = [1 ; 0]; A = [.8 .3 ; .2 .7];
x = u; k = [0 : 7];
while size(x,2) <= 7
    u = A*u; x = [x u];
end
plot(k, x)
```

```
v = [0 ; 1]; A = [.8 .3 ; .2 .7];
x = v; k = [0 : 7];
for j = 1 : 7
    v = A*v; x = [x v];
end
plot(k, x)
```

The u 's and v 's are approaching a steady state vector s . Guess that vector and check that $As = s$. If you start with s , you stay with s .

- 31 Invent a 3 by 3 **magic matrix** M_3 with entries $1, 2, \dots, 9$. All rows and columns and diagonals add to 15. The first row could be $8, 3, 4$. What is M_3 times $(1, 1, 1)$? What is M_4 times $(1, 1, 1, 1)$ if a 4 by 4 magic matrix has entries $1, \dots, 16$?
- 32 Suppose u and v are the first two columns of a 3 by 3 matrix A . Which third column w would make this matrix singular? Describe a typical column picture of $Ax = b$ in that singular case, and a typical row picture (for a random b).

- 18 Construct a 3 by 3 example that has 9 different coefficients on the left side, but rows 2 and 3 become zero in elimination. How many solutions to your system with $b = (1, 10, 100)$ and how many with $b = (0, 0, 0)$?

- 19 Which number q makes this system singular and which right side t gives it infinitely many solutions? Find the solution that has $z = 1$.

$$\begin{aligned}x + 4y - 2z &= 1 \\x + 7y - 6z &= 6 \\3y + qz &= t.\end{aligned}$$

- 20 Three planes can fail to have an intersection point, even if no planes are parallel. The system is singular if row 3 of A is a _____ of the first two rows. Find a third equation that can't be solved together with $x + y + z = 0$ and $x - 2y - z = 1$.

- 21 Find the pivots and the solution for both systems ($Ax = b$ and $Kx = b$):

$$\begin{array}{rcl}2x + y & = & 0 \\x + 2y + z & = & 0 \\y + 2z + t & = & 0 \\z + 2t & = & 5\end{array} \qquad \begin{array}{rcl}2x - y & = & 0 \\-x + 2y - z & = & 0 \\-y + 2z - t & = & 0 \\-z + 2t & = & 5.\end{array}$$

- 22 If you extend Problem 21 following the 1, 2, 1 pattern or the -1, 2, -1 pattern, what is the fifth pivot? What is the n th pivot? K is my favorite matrix.
- 23 If elimination leads to $x + y = 1$ and $2y = 3$, find three possible original problems.
- 24 For which two numbers a will elimination fail on $A = \begin{bmatrix} a & 2 \\ a & a \end{bmatrix}$?
- 25 For which three numbers a will elimination fail to give three pivots?

$$A = \begin{bmatrix} a & 2 & 3 \\ a & a & 4 \\ a & a & a \end{bmatrix} \text{ is singular for three values of } a.$$

- 26 Look for a matrix that has row sums 4 and 8, and column sums 2 and s :

$$\text{Matrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \qquad \begin{array}{l} a + b = 4 \quad a + c = 2 \\ c + d = 8 \quad b + d = s \end{array}$$

The four equations are solvable only if $s = \underline{\hspace{2cm}}$. Then find two different matrices that have the correct row and column sums. *Extra credit:* Write down the 4 by 4 system $Ax = b$ with $x = (a, b, c, d)$ and make A triangular by elimination.

- 27 Elimination in the usual order gives what matrix U and what solution to this "lower triangular" system? We are really solving by *forward substitution*:

$$\begin{aligned}3x &= 3 \\6x + 2y &= 8 \\9x - 2y + z &= 9.\end{aligned}$$

- 28 Create a MATLAB command $A(2, :) = \dots$ for the new row 2, to subtract 3 times row 1 from the existing row 2 if the matrix A is already known.

Challenge Problems

- 29 Find experimentally the average 1st and 2nd and 3rd pivot sizes from MATLAB's $[L, U] = \text{lu}(\text{rand}(3))$. The average size $\text{abs}(U(1, 1))$ is above $\frac{1}{2}$ because lu picks the largest available pivot in column 1. Here $A = \text{rand}(3)$ has random entries between 0 and 1.
- 30 If the last corner entry is $A(5, 5) = 11$ and the last pivot of A is $U(5, 5) = 4$, what different entry $A(5, 5)$ would have made A singular?
- 31 Suppose elimination takes A to U without row exchanges. Then row j of U is a combination of which rows of A ? If $Ax = 0$, is $Ux = 0$? If $Ax = b$, is $Ux = b$? If A starts out lower triangular, what is the upper triangular U ?
- 32 Start with 100 equations $Ax = 0$ for 100 unknowns $x = (x_1, \dots, x_{100})$. Suppose elimination reduces the 100th equation to $0 = 0$, so the system is "singular".
- Elimination takes linear combinations of the rows. So this singular system has the singular property: Some linear combination of the 100 rows is _____.
 - Singular systems $Ax = 0$ have infinitely many solutions. This means that some linear combination of the 100 columns is _____.
 - Invent a 100 by 100 singular matrix with no zero entries.
 - For your matrix, describe in words the row picture and the column picture of $Ax = 0$. Not necessary to draw 100-dimensional space.