

Encoding Curved Tetrahedra in Face Holonomies

Hal Haggard

Bard College

Collaborations with Eugenio Bianchi, Muxin Han, Wojciech Kamiński, and

Aldo Riello

June 15th, 2015

Quantum Gravity Seminar

Nottingham University

math-ph/1506.03053, gr-qc/1412.7546

“Even a tiny cosmological constant casts a long shadow”

A. Ashtekar



$$\Lambda = 2.90 \times 10^{-122} \ell_P^{-2}$$

The kinematical structure of discrete geometries is strongly impacted by Λ



Symmetries have a richer structure
with $\Lambda \rightsquigarrow$ new ideas & insights

Loop Quantum Gravity

Knot Theory

Chern-Simons
Theory

Quantum Curves

Moduli Space of
Flat Connections

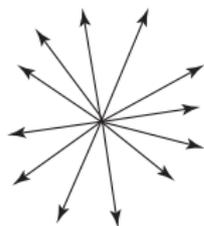
Curved Polyhedra

Quasi-Poisson
Spaces

Is space discrete like a mosaic?



In 1897 H. Minkowski proved



$$\vec{A}_1 + \cdots + \vec{A}_N = 0, \quad \text{with}$$

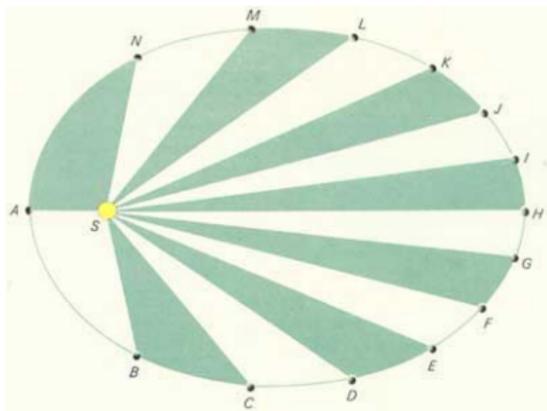
$$\vec{A}_i = A_i \hat{n}_i, \quad \begin{array}{l} A_i = \text{area face } i \\ \hat{n}_i = \perp \text{ to face } i \end{array}$$

Physical proof for one direction:

$$\vec{A}_1 + \cdots + \vec{A}_N = 0 \quad \leftarrow$$



Baez and Barrett combined this with Kepler's elegant realization:



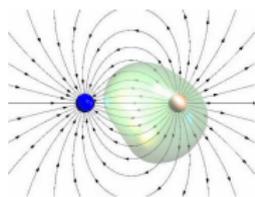
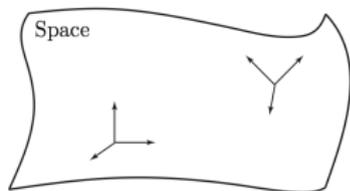
Angular momentum can be used to encode areas

If $F(\vec{A})$ and $G(\vec{A})$ then:

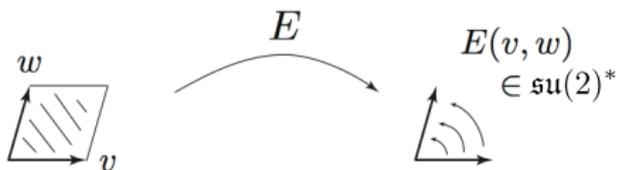
$$\{F, G\} = \left(\vec{A} \times \frac{\partial F}{\partial \vec{A}} \right) \cdot \frac{\partial G}{\partial \vec{A}}$$

$$\text{(e.g. } \{A_x, A_y\} = (\vec{A} \times \hat{x}) \cdot \hat{y} = (\hat{x} \times \hat{y}) \cdot \vec{A} = A_z)$$

Minkowski's theorem is a discrete version of the two roles of the gravitational Gauß law...



$$E_{ibc} = \epsilon_{ijk} e_b^j e_c^k \quad (b, c = 1, 2, 3) \quad (i, j, k = 1, 2, 3)$$



... the constraint ...

$$\oint E = 0$$

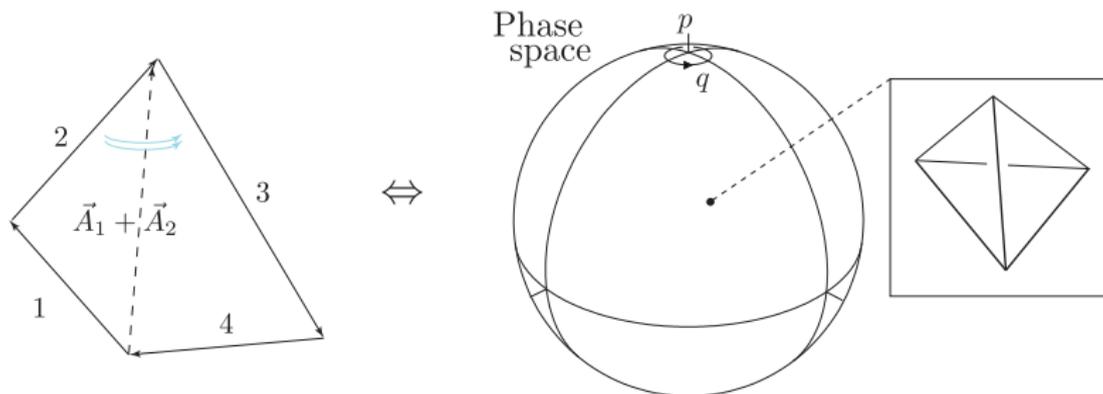
$$\vec{A}_1 + \dots + \vec{A}_N = 0$$

... and the generator of gauge

local choice of frame

diagonal rotation of all the vecs

99 years after Minkowski, in 1996, M. Kapovich and J. J. Millson found a phase space for polygons with fixed edge lengths

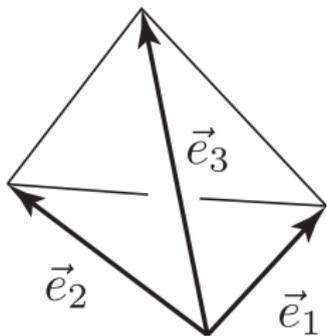


These non-planar polygons are equivalent to fixed area polyhedra

- $p = |\vec{A}_1 + \vec{A}_2|$, rotates \vec{A}_1 and \vec{A}_2 leaving others fixed
- $q =$ Angle of rotation generated by p :

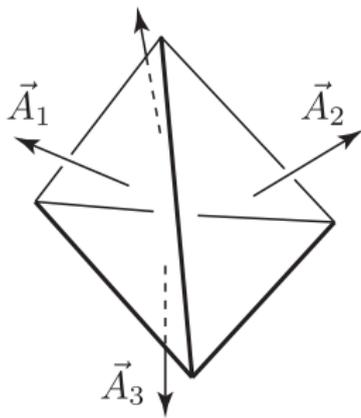
$$\{q, p\} = 1$$

Remarkably, the volume of the tetrahedron is easily expressed in terms of these variables



$$V = \frac{1}{6} \vec{e}_1 \cdot (\vec{e}_2 \times \vec{e}_3)$$

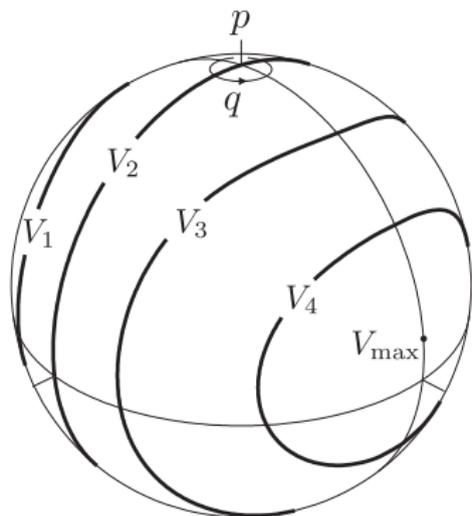
Fun to discover that, with e.g.
 $\vec{A}_2 = \frac{1}{2} \vec{e}_1 \times \vec{e}_3$ etc.,



$$V^2 = \frac{2}{9} \vec{A}_1 \cdot (\vec{A}_2 \times \vec{A}_3)$$

With this phase space, take the volume as a Hamiltonian

$$H = V = \frac{\sqrt{2}}{3} \sqrt{|\vec{A}_1 \cdot (\vec{A}_2 \times \vec{A}_3)|}$$



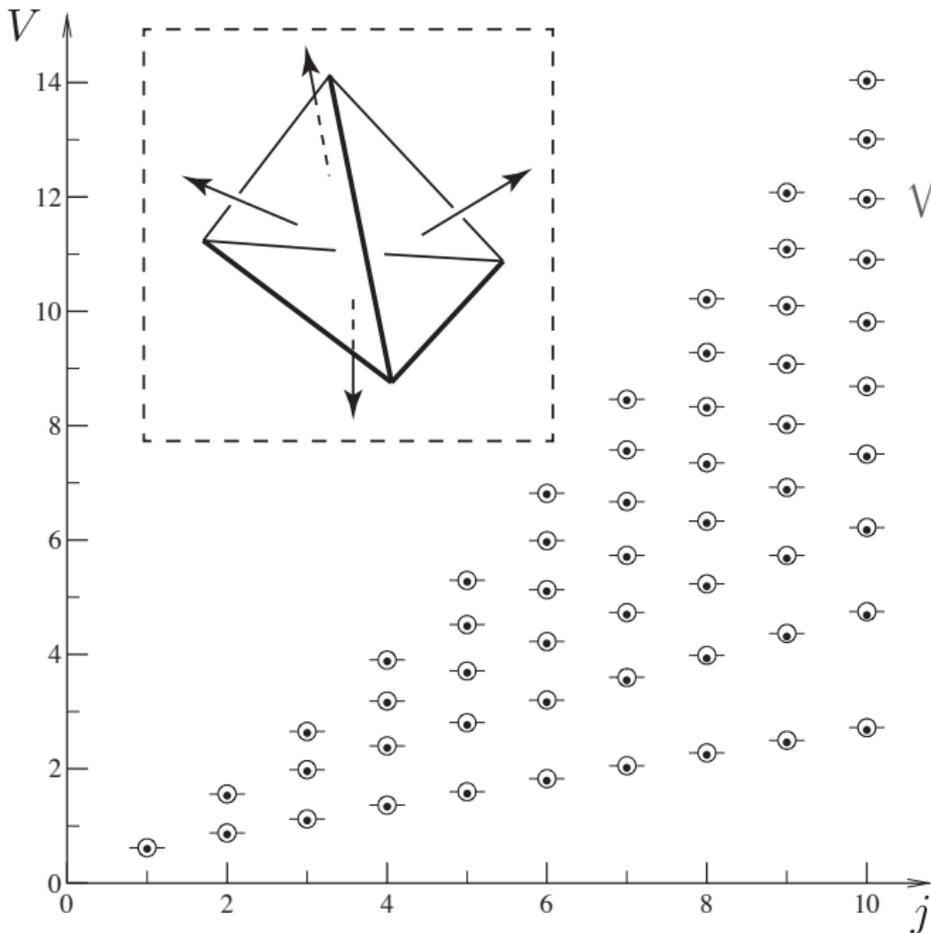
We can now quantize the system semiclassically

Require Bohr-Sommerfeld quantization condition,

$$S = \oint_{\gamma} pdq = \left(n + \frac{1}{2}\right)h.$$

Area of orbits given in terms of complete elliptic integrals,

$$S(V) = \left(aK(m) + \sum_{i=1}^4 b_i \Pi(\alpha_i^2, m) \right) V$$



$$A_1 = j + 1/2$$

$$A_2 = j + 1/2$$

$$A_3 = j + 1/2$$

$$A_4 = j + 3/2$$

○ = Numerical

● = Bohr-Som

[PRL 107, 011301]

Table

j_1 j_2 j_3 j_4	Loop gravity	Bohr-Sommerfeld	Accuracy
6 6 6 7	1.828	1.795	1.8%
	3.204	3.162	1.3%
	4.225	4.190	0.8%
	5.133	5.105	0.5%
	5.989	5.967	0.4%
	6.817	6.799	0.3%
$\frac{11}{2}$ $\frac{13}{2}$ $\frac{13}{2}$ $\frac{13}{2}$	1.828	1.795	1.8%
	3.204	3.162	1.3%
	4.225	4.190	0.8%
	5.133	5.105	0.5%
	5.989	5.967	0.4%
	6.817	6.799	0.3%

Is space discrete like a mosaic? It may be, but...



...this should be understood as a spectral discreteness.

One

Is space discrete
like a mosaic?



Two

The shadow of the
cosmological constant



Three

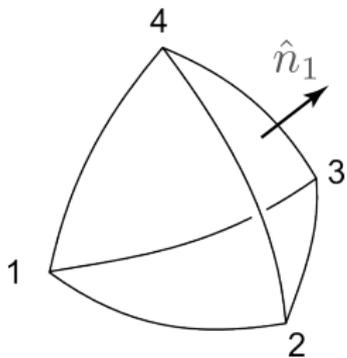
Curved spinfoams

A spherical tetrahedron is 4 points of S^3 connected by geodesics

Each face is a triangular portion of a **great** 2-sphere

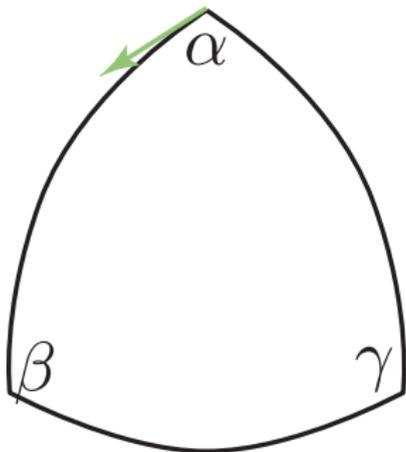


◆ Great spheres are flatly embedded in S^3 (i.e. $K_{ij} = 0$)

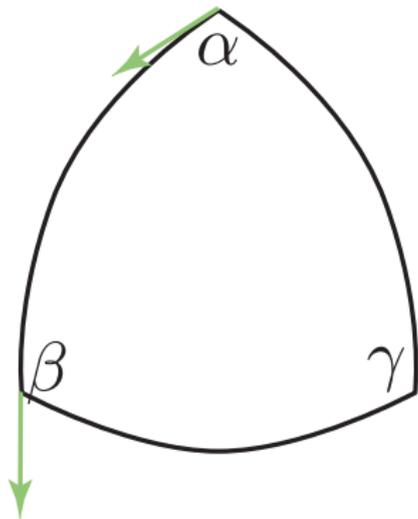


The normal to a face is well-defined and invariant under parallel transport

The holonomy around a curved triangle is the area of the triangle

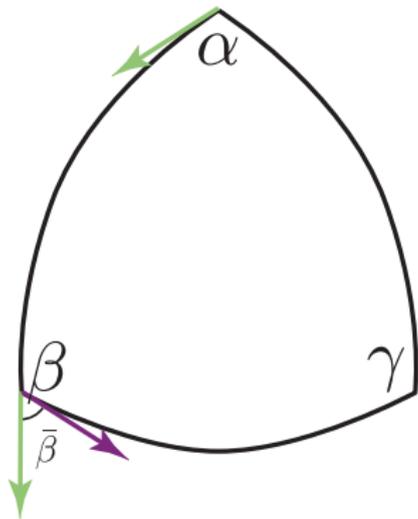


The holonomy around a curved triangle is the area of the triangle



Parallel transport of the
tangent vector is easy

The holonomy around a curved triangle is the area of the triangle



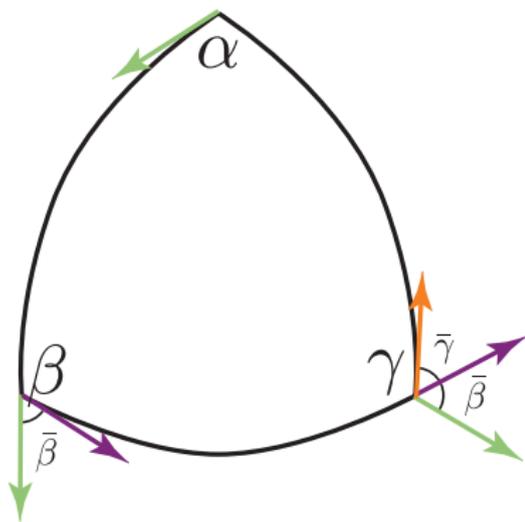
Pick up next tangent vector

and use the complement

$$\bar{\beta} = \pi - \beta$$

Transport preserves this angle

The holonomy around a curved triangle is the area of the triangle

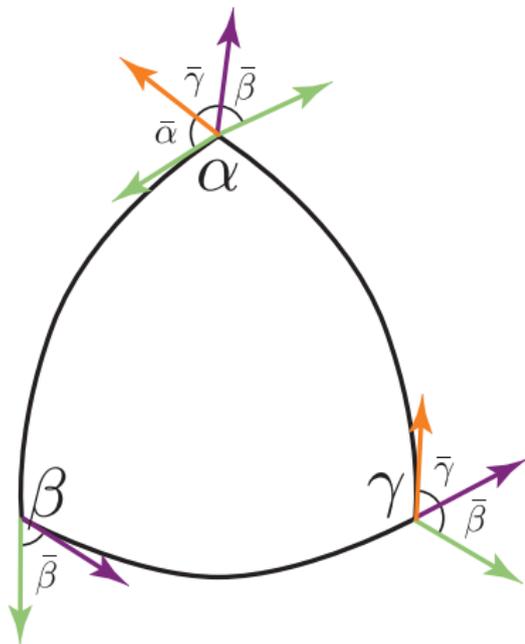


Repeat

$$\bar{\beta} = \pi - \beta$$

$$\bar{\gamma} = \pi - \gamma$$

The holonomy around a curved triangle is the area of the triangle



$$\bar{\alpha} = \pi - \alpha$$

$$\bar{\beta} = \pi - \beta$$

$$\bar{\gamma} = \pi - \gamma$$

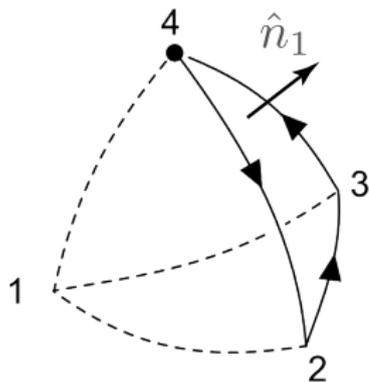
The full holonomy is a counterclockwise rotation about the normal with angle

$$\begin{aligned} a &= 2\pi - \bar{\alpha} - \bar{\beta} - \bar{\gamma} \\ &= \alpha + \beta + \gamma - \pi, \end{aligned}$$

the area of the spherical triangle!

In our work we have proved that

$$O_4 O_3 O_2 O_1 = \mathbb{1}$$



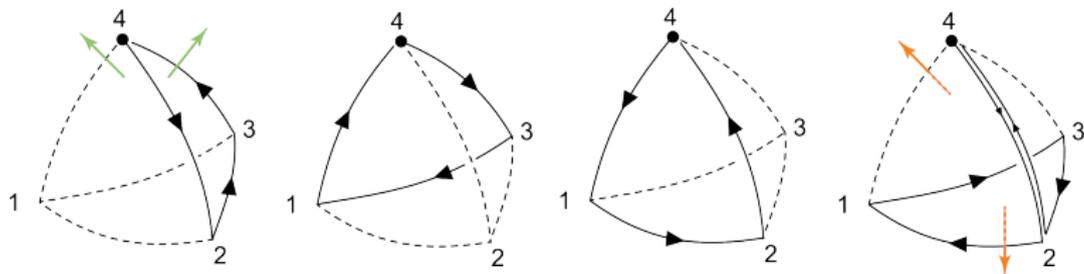
Here

$$O = \exp\left(\frac{a}{r^2} \hat{n} \cdot \vec{J}\right), \quad O \in SO(3)$$

The closure relation is the automatic homotopy constraint. One immediate check: for $r \rightarrow \infty$

$$O_4 O_3 O_2 O_1 = \mathbb{1} + r^{-2}(a_1 \hat{n}_1 + a_2 \hat{n}_2 + a_3 \hat{n}_3 + a_4 \hat{n}_4) \cdot \vec{J} + \dots = \mathbb{1}$$

Define simple paths to determine a geometrically meaningful curved Gram matrix.



The geometrical dot product $\hat{n}_1 \cdot \hat{n}_3$ is well defined at vertex 4,
but we have to rotate \hat{n}_4 to give $\hat{n}_2 \cdot \hat{n}_4$ meaning at 4.

The Gram matrix is

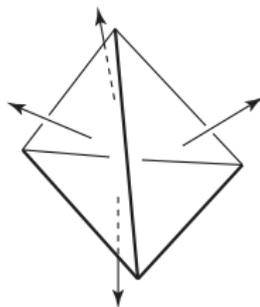
$$\text{Gram} = \begin{pmatrix} 1 & \hat{n}_1 \cdot \hat{n}_2 & \hat{n}_1 \cdot \hat{n}_3 & \hat{n}_1 \cdot \hat{n}_4 \\ * & 1 & \hat{n}_2 \cdot \hat{n}_3 & \hat{n}_2 \cdot \mathbf{O}_1 \hat{n}_4 \\ * & * & 1 & \hat{n}_3 \cdot \hat{n}_4 \\ \text{sym} & * & * & 1 \end{pmatrix}.$$

The holonomies directly determine the sign of the curvature through Gram.

$$\begin{cases} \det \text{Gram} > 0 & \text{spherical geometry} \\ \det \text{Gram} < 0 & \text{hyperbolic geometry} \end{cases}$$

Consider a flat
(Euclidean) tetrahedron

Its four vectors are
linearly dependent
 $\rightsquigarrow \det \text{Gram} = 0$.

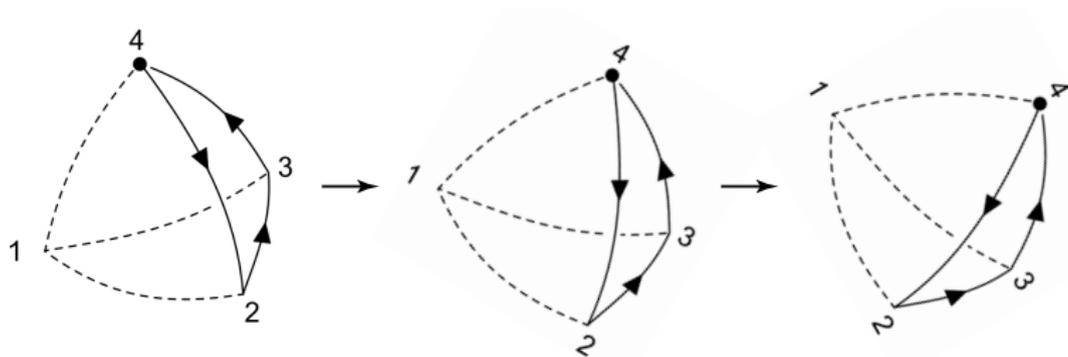


The general claim follows from a special case and continuity in the curvature.

There is no need for another group.

Lift the set $\{O_\ell\}$ to a set $\{H_\ell\} \subset SU(2)$.

The new closure, $H_4H_3H_2H_1 = \mathbb{1}$, is a curved Gauß constraint and should again play its role as generator of gauge transformations.

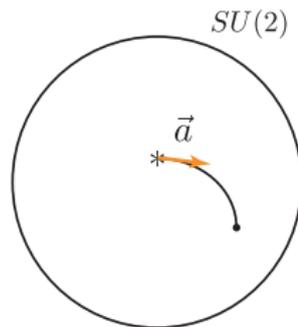


- ▶ To achieve this we must have group-valued momenta
 ↪ in this manner the theory of quasi-Poisson spaces enters

A quasi-Poisson space has a Poisson bivector, i.e. a Poisson bracket, that violates the Jacobi identity in a specific way

If we parametrize $SU(2)$ using the fundamental representation, then the holonomies around faces are

$$H = e^{-i \frac{\vec{a} \cdot \vec{\sigma}}{2r^2}}$$

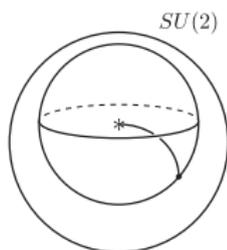


With this parametrization we can construct the quasi-Poisson brackets for the fluxes \vec{a}

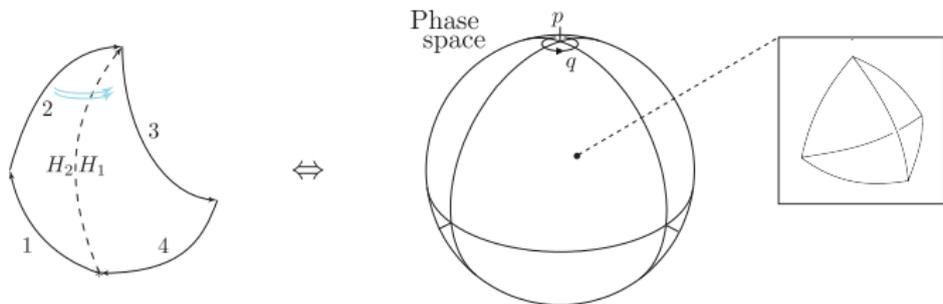
$$\{a^i, a^j\}_{qP} = \frac{a}{2r^2} \cot \frac{a}{2r^2} \epsilon_k^{ij} a^k \xrightarrow{r \rightarrow \infty} \epsilon_k^{ij} a^k.$$

This Poisson structure naturally foliates $SU(2)$ into leaves, these are the conjugacy classes of $SU(2)$

Fixing the area of a face gives a geodesic that sweeps out a 2-sphere in $SU(2) \cong S^3$.



Forming the fusion product of 4 of these phase spaces and reducing by the Gauß constraint gives



$$\omega_H = r^2 \sin \frac{a}{r^2} d^2\Omega \quad \text{and} \quad \mathcal{L}_H = 2r^2 \sin \frac{a}{2r^2} d^2\Omega.$$

One

Is space discrete
like a mosaic?



Two

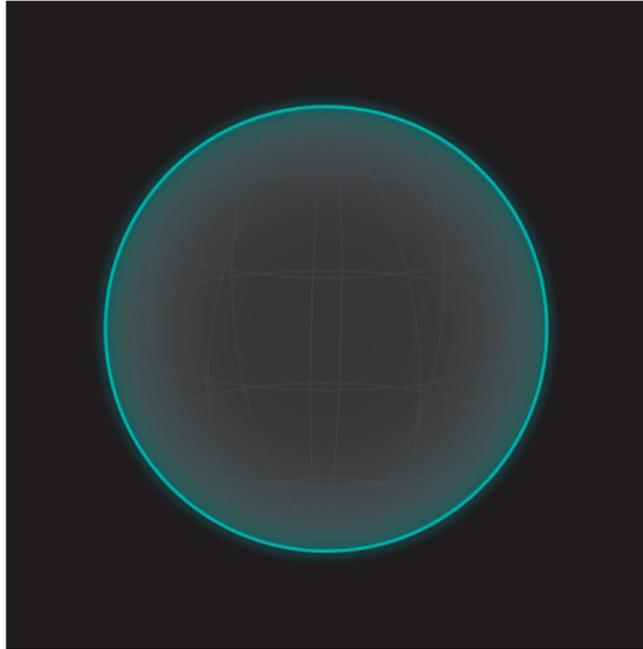
The shadow of the
cosmological constant



Three

Curved spinfoams

What is the physics of a finite region of a quantum spacetime?



At the level of a single building block, the EPRL amplitude of the 3d spin-network boundary state ψ_Γ is

$$Z_{\text{EPRL}}(\psi_\Gamma) := \int \mathcal{D}B \mathcal{D}\mathcal{A} e^{\frac{i}{2\ell_P^2} \int B \wedge \mathcal{F}[A]} (f_\gamma \psi_\Gamma)(G[\mathcal{A}]) = (f_\gamma \psi_\Gamma)(\mathbb{1})$$

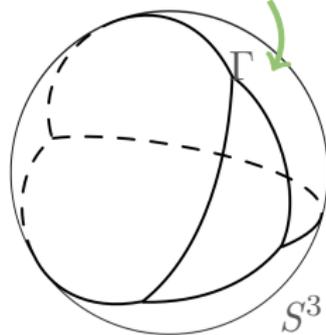
$\text{SL}(2, \mathbb{C})$
spin connection

B is the 'bivector' field
[$B = \star e \wedge e$ on geometric states]

f_γ is the Dupuis-Livine map,
it embeds ψ into spacetime

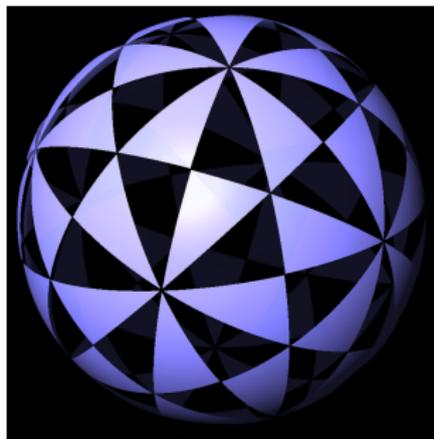
holonomy
of \mathcal{A}

dual to 4-simplex boundary



*[one dimensional lower drawing]

Philosophy for Λ Regge: construct a manifold out of *homogeneously curved* building blocks & $(d - 2)$ -dimensional defects



At the quantum level, the homogenous curvature is implemented via $BF - \frac{\Lambda}{6}BB$ dynamics, and defects are created as in the flat case

$$\Lambda\text{-GR} = BF - \frac{\Lambda}{6}BB + \text{geometricity constraints}$$

For boundary connection functionals, Λ BF in the bulk is equivalent to CS on the boundary

$$\begin{aligned}
 Z(\psi_\Gamma) &:= \int \mathcal{D}B \mathcal{D}\mathcal{A} e^{\frac{i}{2\ell_P^2} \int B \wedge \mathcal{F}[\mathcal{A}] - \frac{\Lambda}{6} B \wedge B} (f_\gamma \psi_\Gamma)(G[\mathcal{A}]) \\
 &= \int \mathcal{D}\mathcal{A} e^{\frac{3i}{4\Lambda \ell_P^2} \int \mathcal{F}[\mathcal{A}] \wedge \mathcal{F}[\mathcal{A}]} (f_\gamma \psi_\Gamma)(G[\mathcal{A}]) \\
 &= \int \mathcal{D}\mathcal{A} e^{\frac{3\pi i}{\Lambda \ell_P^2} \text{CS}[\mathcal{A}]} (f_\gamma \psi_\Gamma)(G[\mathcal{A}]),
 \end{aligned}$$

where the Chern-Simons functional is

$$\text{CS}[\mathcal{A}] := \frac{1}{4\pi} \oint_{S^3} d\mathcal{A} \wedge \mathcal{A} + \frac{2}{3} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A}$$

Twisting the previous construction by using the γ -Holst action gives

$$Z_{\Lambda\text{EPRL}}(\psi_\Gamma) := \int \mathcal{D}A \mathcal{D}\bar{A} e^{i\frac{h}{2}\text{CS}[A] + i\frac{\bar{h}}{2}\text{CS}[\bar{A}]} (f_\gamma \psi_\Gamma)(G[A, \bar{A}])$$

where (A, \bar{A}) are the self- and antiself-dual parts of \mathcal{A}
and $h := \frac{12\pi}{\Lambda \ell_P^2} \left(\frac{1}{\gamma} + i \right)$ is the **complex** CS level

Note

$Z_{\Lambda\text{EPRL}}$ involves only quantities living on the boundary

$\Lambda\text{EPRL} = \text{SL}(2, \mathbb{C})$ -CS evaluation of a specific Wilson graph operator

$$h := \frac{12\pi}{\Lambda \ell_P^2} \left(\frac{1}{\gamma} + i \right)$$

Two immediate consequences:

The CS level h is complex, \rightsquigarrow no (known) quantum group structure associated to the graph evaluation

Fairbairn & Meusburger, Han

Invariance of the amplitude under large gauge transformations
 $\mathcal{A} \mapsto \mathcal{A}^g$ implies $\Re(h) \in \mathbb{Z}$, i.e.

$$\frac{12\pi}{|\Lambda|} \equiv 4\pi R_\Lambda^2 \in \gamma \ell_P^2 \mathbb{N}$$

Kodama, Randono, Smolin, Wieland

$$h := \frac{12\pi}{\Lambda \ell_P^2} \left(\frac{1}{\gamma} + i \right)$$

Three interesting limits:

Vanishing cosmological constant $\Lambda \rightarrow 0$:

$h \rightarrow \infty$, & CS is projected onto its classical solutions \rightsquigarrow flat EPRL

q -deformed Lorentzian Barrett-Crane amplitude:

when $\gamma \rightarrow \infty$, the EPRL graph operator \rightarrow Barrett & Crane's,
while h becomes $\in i\mathbb{R}$, giving $q = \exp(-\ell_P^2/R_\Lambda^2)$

Noui & Roche

Semiclassical Λ Regge limit: more about this on next slide

The semiclassical Λ Regge limit is

$$h := \frac{12\pi}{\Lambda \ell_P^2} \left(\frac{1}{\gamma} + i \right)$$

$$\ell_P \rightarrow 0, \quad j \rightarrow \infty, \quad \text{with} \quad a_{\text{phys}} \equiv \gamma \ell_P^2 j = \text{cnst}$$

$\ell_P \rightarrow 0$ means $h \rightarrow \infty$, which corresponds to CS classical flat limit,

however

$j \rightarrow \infty$ makes the Wilson graph operator stand out and act as a distributional source for (A, \overline{A}) ,

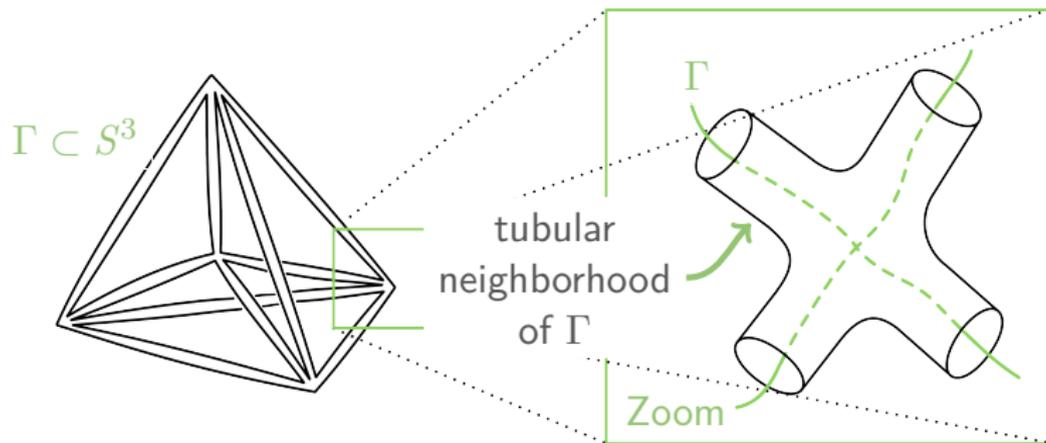
thus avoiding flatness

Semiclassical limit =

study of flat connections on the graph complement $S^3 \setminus \Gamma$

The graph complement $S^3 \setminus \Gamma$ is obtained by removing a tubular neighborhood of Γ from S^3

Here and below Γ is the graph dual to the 4-simplex boundary

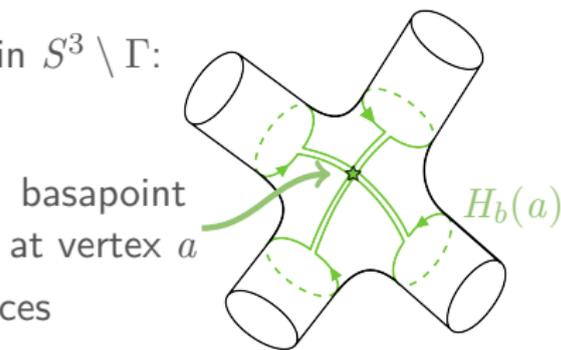


The boundary of $S^3 \setminus \Gamma$ is a genus 6 surface

There are two types of holonomies in $S^3 \setminus \Gamma$:

- ▶ transverse $H_b(a)$
- ▶ longitudinal G_{ba}

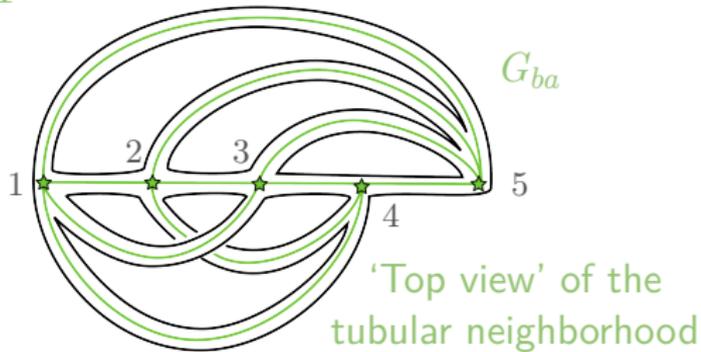
where a, b, \dots label the graph vertices



Zoom on vertex a

We need to specify the exact paths,
called a **choice of framing** for Γ

longitudinal paths
run on the
'top' of the tubes

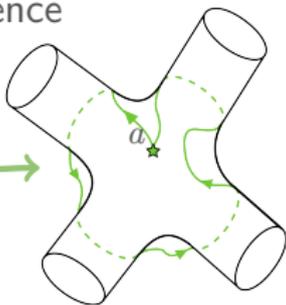


Equations of motion

The connection on the graph complement is flat, hence holonomies along contractible paths are trivial:

closures

$$\prod_b H_b(a) = \mathbb{1}$$



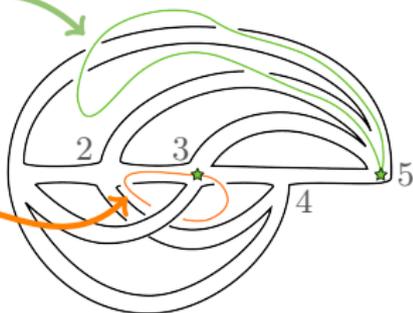
parallel transports

$$G_{ba} H_b(a) G_{ab} = H_a(b)^{-1}$$



around 5 out of the 6 independent 'faces'

$$G_{ac} G_{cb} G_{ba} = \mathbb{1}$$



while, around the last independent 'face':

$$G_{34} G_{42} G_{23} = H_1(3)$$

The CS phase space is $\mathcal{P} = \mathcal{M}_{\text{flat}}(\Sigma, SL(2, C))$

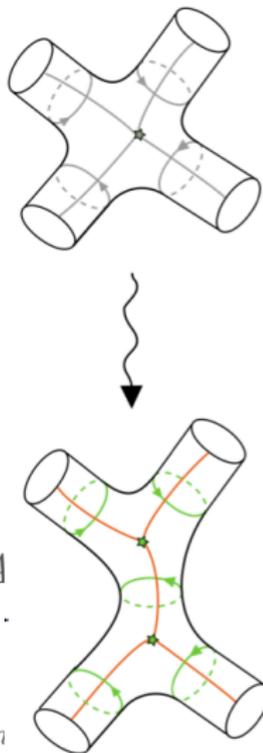
Natural complex coordinates are obtained via a trivalent decomposition of the graph and considering:

$$H_m \sim \begin{pmatrix} x_m & \\ & x_m^{-1} \end{pmatrix} \quad \text{and} \quad G_m \sim \begin{pmatrix} y_m & \\ & y_m^{-1} \end{pmatrix}$$

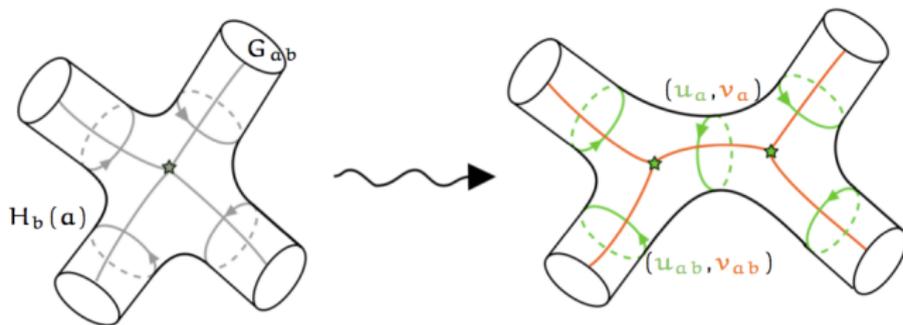
hence $u_m := \log x_m$ and $v_m := -2\pi \log y_m$

The Atiyah-Bott symplectic structure $\frac{\hbar}{4\pi} \int_{\partial M} \text{Tr} \delta A \wedge \delta A$ induces the canonical Poisson brackets

$$\{u_m, v_n\} = \delta_{m,n} \quad \text{and} \quad \{\bar{u}_m, \bar{v}_n\} = \delta_{m,n}$$



To implement the WKB approximation for simplicial geometries, we relate (u, v) to geometrical quantities



The 4-simplex reconstruction theorem shows that

$$u_{ab} = -i \frac{\Lambda}{6} a_{ab} + 2\pi i n_{ab}$$

$$v_{ab} = \frac{h}{4\pi} \Theta_{ab} + i \frac{h}{4\pi} \phi_{ab} + i \frac{h}{2} m_{ab}$$

where $n_{ab}, m_{ab} \in \mathbb{Z}$ are lifting ambiguities.

Also, at each 4-vertex, (u_a, v_a) encodes shape of tet a with face areas $\{a_{ab}\}_b$; \exists parity related solution with: $(\tilde{v}_a, \tilde{v}_{ab}) = (v_a, -v_{ab})$

The WKB approximation for simplicial geometries is

$$Z(u, \bar{u}|M) \sim Z^\alpha e^{\frac{i}{\hbar} \Re(\frac{\Lambda \hbar}{12\pi i})(\Sigma a_{ab} \Theta_{ab} - \Lambda V_4^\Lambda)} + \frac{i}{\hbar} \Im(\frac{\Lambda \hbar}{6}) \Sigma m'_{ab} a \\ + Z^{\tilde{\alpha}} e^{-\frac{i}{\hbar} \dots}$$

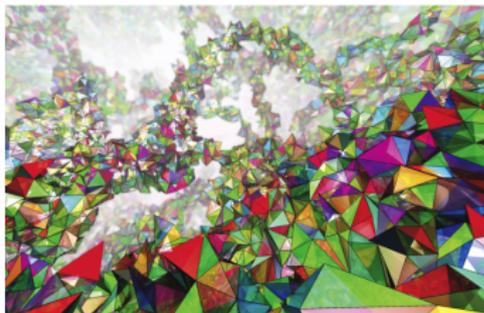
◆ the **Regge action** of simplicial General Relativity with a cosmological constant

[Regge 1961; Barrett, Foxon 1994; Bahr, Dittrich 2010]

■ the two branches of **opposite parity** (\sim 3d QG, mini-superspace QC)

● arbitrary term depending on the **choice of lift** $v := \log y + 2\pi im$

■ Established a classical foundation on which to build the quantization of spacetimes with a cosmological constant.



◆ Conjecture: the curved Minkowski theorem holds in general \rightsquigarrow study of flat connections on Riemann surfaces closely related to study of discrete, curved polyhedra.

♣ Provide an enriched context for understanding the role of quantum groups in cosmological spacetimes.

