

Today's Outline:

I. Last Lecture

II. Quantitative Treatment of tides

Lecture 17

October 7th, 2011

I. Last Lecture

P1/4

(Completed discussion of central forces.)

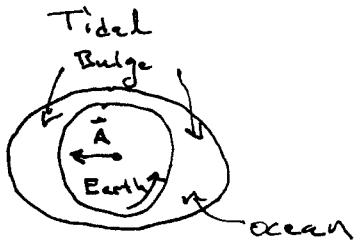
In a linearly accelerated frame we found the modified Newton's law (acc. \vec{A})

$$m\ddot{\vec{r}} = \vec{F} - m\vec{A}$$

We began discussion of tides: the earth is an accelerated frame (due to moon's pull) and this

combined with gravitational pull of the moon is the primary cause of the tides.

○
Moon

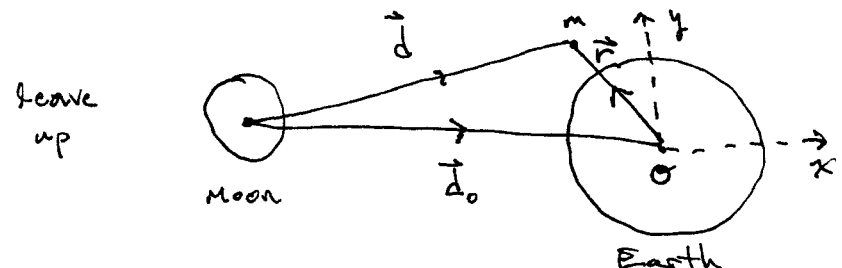


w/ Earth's accel, why there are two high tides each day.

The gravitational pull of the moon is greater on the side closer to the moon and weaker on the opposite side. This, ^{is} ~~is~~ along

The acceleration \vec{A} 's magnitude and direction are determined by treating the Earth and moon as point masses concentrated at their respective centers

II Quantitative Treatment of Tides



- The forces on m :
- (1) Earth's gravity: $m\vec{g}$
 - (2) Moon's gravity: $-GM_m m \hat{d} / d^2$ ($M_m = \text{Moon's mass}$)
 - (3) Net non-gravitational force: \vec{F}_{ng}

And the Earth is a noninertial frame with acceleration,

$$\vec{A} = - \frac{GM_m}{d_0^2} \hat{d}_0$$

We can use our noninertial frame law

$$m\vec{r}'' = \vec{F} - m\vec{A}$$

To find the height of the tides we'll leverage a nice argument: the tidal bulge is an equipotential surface.

Mathematical prerequisite: ~~A level set of f is a set on which f takes a constant value~~

Level set: $f = \text{const.}$
of f

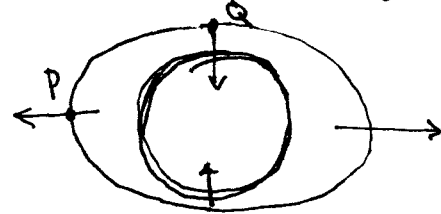
If $g = g(x)$ then $dg = \frac{dg}{dx} dx$,

P2/4

$$\Rightarrow m\vec{r}'' = (m\vec{g} - GM_m m \frac{\hat{d}}{d^2} + \vec{F}_{ng}) + GM_m m \frac{\hat{d}_0}{d_0^2}$$

$$\Rightarrow m\vec{r}'' = m\vec{g} - \underbrace{GM_m m \left(\frac{\hat{d}}{d^2} - \frac{\hat{d}_0}{d_0^2} \right)}_{\equiv \vec{F}_{tid}} + \vec{F}_{ng}$$

The direction of \vec{F}_{tid} is interplay of \hat{d}_0 and \hat{d} , d^2 and d_0^2 :



while if $f = f(x, y, z)$ then

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$

$$= \vec{\nabla} f \cdot d\vec{r}$$

Now consider a level set

$$f(x, y, z) = c \quad (\text{a const.})$$

If we choose a displacement within this surface then $d\vec{r}$ is tangent to $f=c$ and, certainly, $df=0$. Then,

$$df = 0 = \vec{\nabla} f \cdot d\vec{r}$$

This means that $\vec{\nabla}f$ is normal (i.e. perpendicular) to $f=c$. Example:

$$f(x,y,z) = x^2 + y^2 + z^2, \quad \vec{\nabla}f = 2(x,y,z) \propto \hat{r} \checkmark$$

An equipotential is just a level set of the potential energy function. We're going to argue that $\vec{\nabla}U$ is normal to the tidal bulge and hence that the tidal bulge is an equipotential. (Note; reverse of mathematical argument just given)

Write in terms of potentials:

$$m\vec{g} = -\vec{\nabla}U_{eg} \quad \vec{F}_{tid} = -\vec{\nabla}U_{tid}$$

↑
potential of
Earth's grav. pull

$$U_{tid} = -GM_m m \left(\frac{1}{d} + \frac{x}{d_0^2} \right)$$

and

$$U = U_{eg} + U_{tid}$$

Then $m\vec{g} + \vec{F}_{tid} = -\vec{\nabla}U$ is

Consider a water droplet, it is subject to (in our Earth frame): $m\vec{g}$, \vec{F}_{tid} , and \vec{F}_p , the pressure of the surrounding water.

Water can't exert a shear force $\Rightarrow \vec{F}_p$ is normal to surface of water. But our droplet is in equilibrium and so

$$m\vec{g} + \vec{F}_{tid} \text{ is also normal to the water surface.}$$

normal to the surface of the water and indeed it must be an equipotential.

This means that

$$U(Q) = U(P)$$

$$\Rightarrow U_{tid}(Q) - U_{tid}(P) = U_{eg}(P) - U_{eg}(Q) = mgh$$

where h is the height of the tidal bulge. What about $U_{tid}(Q)$ and $U_{tid}(P)$?

For Q: $d = \sqrt{d_0^2 + r^2}$ and $r \approx R_e$,
 the radius of the Earth. So

$$\begin{aligned}
 U_{tid}(Q) &= -GM_{mm} \left(\frac{1}{\sqrt{d_0^2 + R_e^2}} + 0 \right) \\
 &= -\frac{GM_{mm}}{d_0} \left(1 + \frac{R_e^2}{d_0^2} \right)^{-1/2} \\
 &\approx -\frac{GM_{mm}}{d_0} \left(1 - \frac{R_e^2}{2d_0^2} \right)
 \end{aligned}$$

and

$$\begin{aligned}
 U_{tid}(P) &= -GM_{mm} \left(\frac{1}{d_0 - R_e} - \frac{R_e}{d_0^2} \right) \\
 &= -\frac{GM_{mm}}{d_0} \left(\frac{1}{1 - R_e/d_0} - \frac{R_e}{d_0} \right) \\
 &\approx -\frac{GM_{mm}}{d_0} \left(1 + \frac{R_e}{d_0} + \frac{R_e^2}{d_0^2} - \frac{R_e}{d_0} \right) \\
 &= -\frac{GM_{mm}}{d_0} \left(1 + \frac{R_e^2}{d_0^2} \right)
 \end{aligned}$$

For P: $d \approx d_0 - R_e$ $x \approx -R_e$

Putting it together

$$\begin{aligned}
 &-\frac{GM_{mm}}{d_0} \left(1 - \frac{R_e^2}{2d_0^2} \right) + \frac{GM_{mm}}{d_0} \left(1 + \frac{R_e^2}{d_0^2} \right) \\
 &= \frac{3GM_{mm}R_e^2}{2d_0^3} = mgh
 \end{aligned}$$

$$\Rightarrow h = \frac{3M_m R_e^4}{2M_e d_0^3}$$

$$\Rightarrow h = 54 \text{ cm [moon alone]}$$

Now, $g = GM_e/R_e^2$ and so

$$\frac{3GM_m R_e^2}{2d_0^3} = \frac{GM_e}{R_e^2} h$$

Sun also contributes, exact same analysis
 with sun's mass and distances yields

$$h = 25 \text{ cm [sun alone].}$$