

Today's Outline

- I. Last Lecture
- II. Free-fall with \vec{F}_{cor}
- III. Foucault's pendulum

Lecture 20
October 14th, 2011

I. Last Lecture P1/4

We carefully worked out:

- the direction of the centrifugal force
- the impact of \vec{F}_{cf} on \vec{g} .
- The direction of the Coriolis force (in both the Northern and the Southern hemispheres).

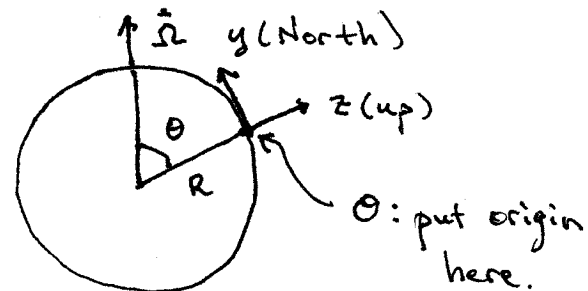
II Free-fall again

$$m\ddot{\vec{r}} = m\vec{g}_0 + \vec{F}_{\text{cf}} + \vec{F}_{\text{cor}}$$
$$= m\vec{g} + 2m\dot{\vec{r}} \times \vec{\Omega}$$

$$\Rightarrow \ddot{\vec{r}} = \vec{g} + 2\dot{\vec{r}} \times \vec{\Omega}$$

Notice that this equation only depends on $\ddot{\vec{r}}$ and $\dot{\vec{r}}$ \Rightarrow we can arbitrarily shift our origin (see figure):

Cross-section of Earth:



In these coords

$$\dot{\vec{r}} = (\dot{x}, \dot{y}, \dot{z}) \quad \text{and}$$

$$\vec{\Omega} = (0, \Omega \sin \theta, \Omega \cos \theta), \quad \text{so that}$$

$$\dot{\vec{r}} \times \vec{\Omega} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \dot{x} & \dot{y} & \dot{z} \\ 0 & \Omega \sin \theta & \Omega \cos \theta \end{vmatrix} = (\dot{y} \Omega \cos \theta - \dot{z} \Omega \sin \theta, -\dot{x} \Omega \cos \theta, \dot{x} \Omega \sin \theta)$$

The E.O.M. is then

$$\ddot{x} = 2\Omega(\dot{y}\cos\theta - \dot{z}\sin\theta)$$

$$\ddot{y} = -2\Omega\dot{x}\cos\theta$$

$$\ddot{z} = -g + 2\Omega\dot{x}\sin\theta$$

which is a set of coupled differential equations. Not easy to solve, so we will make a series of approximations!

First $\Omega \ll 1$, so let's take $\Omega \approx 0$

$$\Rightarrow \ddot{x} = 0 \quad \ddot{y} = 0 \quad \text{and} \quad \ddot{z} = -g$$

First order is then

$$x(t) = \frac{1}{3}\Omega g t^3 \sin\theta \quad y=0 \quad z = h - \frac{1}{2}gt^2$$

This reasonably has only $\Omega^0 = 1$ and $\Omega^1 = \Omega$ in it. We could continue in this manner to get as many powers of Ω as we wanted. How big is this effect?

Drop a pebble down a 100 meter mine shaft at the equator and

with solution,

Pg/4

$$x=0 \quad y=0 \quad z = h - \frac{1}{2}gt^2$$

assuming $z(0) = h$, $\dot{z}(0) = 0$. This is called the ~~zeroth~~ ^{zeroth} order approximation because

it only has $\Omega^0 = 1$ in it. To get the first order we put the zeroth order ^{R.H.S of the} back into the [^]E.O.M. to find

$$\ddot{x} = 2\Omega g t \sin\theta, \quad \ddot{y} = 0, \quad \ddot{z} = -g$$

$$\Rightarrow \dot{x}(t) = \Omega g t^2 \sin\theta + \dot{x}_0^0 \Rightarrow x(t) = \frac{1}{3}\Omega g t^3 \sin\theta + x_0^0$$

$$\text{we have } z = h - \frac{1}{2}gt^2 \Rightarrow t = \sqrt{\frac{2h}{g}}$$

while

$$x = \frac{1}{3}\Omega g \left(\frac{2h}{g}\right)^{3/2} \approx 2.2 \text{ cm,}$$

generally a small effect.

This example illustrates:

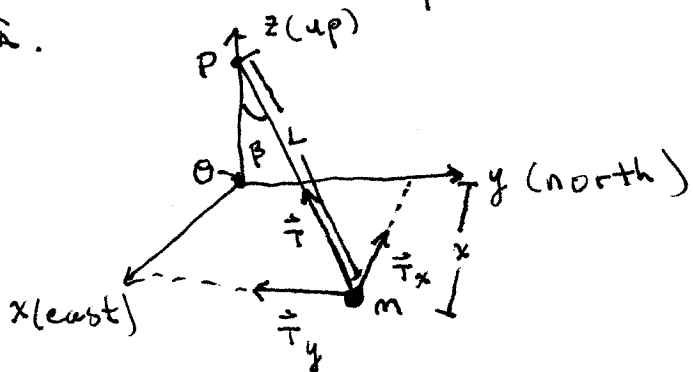
- how to calculate cross-products (a reminder)

and

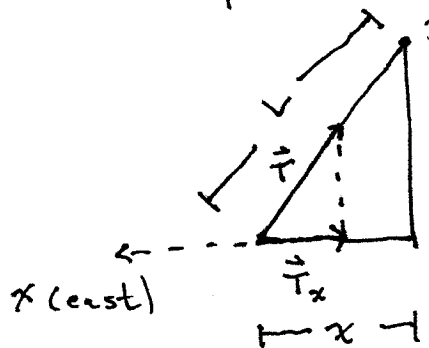
- One approach to solving coupled differential equations.

III Foucault's pendulum

Foucault's pendulum is a spherical pendulum (like your HW problem) with a massive bob and a long wire. The pendulum is suspended from a pivot P. ~~fixed to the Earth.~~



Now let's look at our figure in the plane spanned by \hat{T}_x and \hat{T} :



By similar triangles we have

$$\frac{T_x}{T} = -\frac{x}{L}$$

minus sign means T_x points in neg. x -direction.

The E.O.M. for the pendulum P3/4 is

$$m\ddot{\vec{r}} = \vec{T} + m\vec{g}_0 + \vec{F}_c + 2m\dot{\vec{r}} \times \vec{\Omega}$$

$$= \vec{T} + m\vec{g} + 2m\dot{\vec{r}} \times \vec{\Omega}$$

Consider case where β is small so that

$$T_z = T \cos \beta \approx T$$

For small β we also have \dot{z} and \ddot{z} small and the z -component of the E.O.M. becomes,

$$0 = T_z - mg \Rightarrow T_z \approx T \approx mg.$$

Similarly $T_y = -T y/L = -mgy/L$

Putting it together our E.O.M are

$$\ddot{x} = -gx/L + 2\dot{y}\Omega \cos \theta$$

$$\ddot{y} = -gy/L - 2\dot{x}\Omega \cos \theta$$

Noting that $g/L = \omega_0^2$ and $\Omega \cos \theta = \Omega_z$ we have

$$\ddot{x} - 2\Omega_z \dot{y} + \omega_0^2 x = 0$$

$$\ddot{y} + 2\Omega_z \dot{x} + \omega_0^2 y = 0$$

Another set of coupled equations!

These are almost harmonic oscillator equations. We'll use another new technique to solve them. Let

$$\eta = x + iy$$

and multiply the \dot{y} equation by $i = \sqrt{-1}$ and add it to the \dot{x} equation, to find

$$\ddot{\eta} + 2i\Omega_z \dot{\eta} + \omega_0^2 \eta = 0$$

This is a 2nd order, linear, homogeneous diff. eq. We can go back to our

Recall $\Omega_z \ll \omega_0$ and so

$$\lambda \approx -i \left(\Omega_z \pm \omega_0 \right)$$

Our general solution is then

$$\begin{aligned} \eta(t) &= C_1 e^{-i(\Omega_z - \omega_0)t} + C_2 e^{-i(\Omega_z + \omega_0)t} \\ &= e^{-i\Omega_z t} \left[C_1 e^{i\omega_0 t} + C_2 e^{-i\omega_0 t} \right] \end{aligned}$$

To set C_1 and C_2 we need initial conditions, let's choose: $x(0) = A$ $y(0) = 0$

Standard guess:

P4/4

$$\eta(t) = e^{\lambda t}$$

(Note: notation differs from book but agrees with lecture 1.)

$$\Rightarrow \lambda^2 + 2i\Omega_z \lambda + \omega_0^2 = 0$$

$$\Rightarrow \lambda = \frac{-2i\Omega_z \pm \sqrt{-4\Omega_z^2 - 4\omega_0^2}}{2}$$

$$= -i \left(\Omega_z \pm \sqrt{\Omega_z^2 + \omega_0^2} \right)$$

(so book's $\alpha = \text{our } i\lambda$).

$v_{x0} = v_{y0} = 0$ then $\eta(0) = A$ and

$\dot{\eta}(0) = 0$ but

$$\eta(0) = C_1 + C_2$$

$$\begin{aligned} \dot{\eta}(0) &= -i(\Omega_z - \omega_0)C_1 - i(\Omega_z + \omega_0)C_2 \\ &\approx i\omega_0 C_1 - i\omega_0 C_2 \end{aligned}$$

Then, $C_1 + C_2 = A$ $C_1 - C_2 = 0$

$$\Rightarrow C_1 = C_2 = A/2.$$

and

$$\eta(t) = x + iy = A e^{-i\Omega_z t} \cos(\omega_0 t)$$

rotates plane of oscillation

↑ usual pendulum motion