

# Today's Outline

Lecture 27

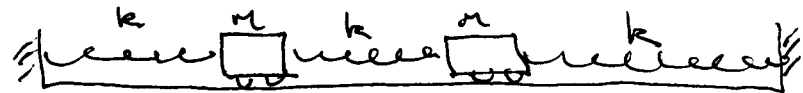
I Last lecture

P1/4

I. Last Lecture

November 2<sup>nd</sup>, 2011

Found E.O.M for our toy model and then specialized to



and found

$$\begin{pmatrix} \overleftarrow{K} - \omega^2 \overleftarrow{M} \end{pmatrix} \vec{a} = 0$$

with

$$\overleftarrow{M} = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix}, \quad \overleftarrow{K} = \begin{pmatrix} 2k & -k \\ -k & 2k \end{pmatrix}$$

and  
 $\vec{Z}(t) = \vec{a} e^{i\omega t} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{i\omega t}$  ← complex constants

our trial solution. This led to the generalized eigenvalue equation

$$\det(\overleftarrow{K} - \omega^2 \overleftarrow{M}) = 0$$

and the two solutions

$$\omega_1 = \sqrt{\frac{k}{m}} \quad \text{and} \quad \omega_2 = \sqrt{\frac{3k}{m}}$$

↑ "sloshing mode"

II Normal modes for our specialized toy model

$$\begin{pmatrix} \overleftarrow{K} - \omega_1^2 \overleftarrow{M} \end{pmatrix} \vec{a} = \begin{pmatrix} k & -k \\ -k & k \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0$$

$$\Rightarrow \left. \begin{matrix} a_1 - a_2 = 0 \\ -a_1 + a_2 = 0 \end{matrix} \right\} \Rightarrow a_1 = a_2$$

This means the mode is determined by a single complex number,

$$a_1 = a_2 = A e^{-i\phi}$$

call ↑  
choose it      a just amp. x phase  
form of any complex #.

Now that we've set  $a_1 = a_2 = Ae^{-i\delta}$  our trial solution becomes

$$\vec{Z}(t) = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{i\omega_1 t} = \begin{pmatrix} A \\ A \end{pmatrix} e^{i(\omega_1 t - \delta)}$$

and the physical solution is,

$$\vec{x}(t) = \text{Re}(\vec{Z}(t)) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} A \\ A \end{pmatrix} \cos(\omega_1 t - \delta)$$

or

$$\begin{aligned} x_1(t) &= A \cos(\omega_1 t - \delta) \\ x_2(t) &= A \cos(\omega_1 t - \delta) \end{aligned} \quad \left[ \begin{array}{l} \text{Stroking} \\ \text{mode} \end{array} \right]$$

At any given moment the carts have opposite amplitudes; we call this the "breathing mode".

All of this was based on the standard guess and the physical assumption that the carts oscillate at the same frequency.

These equations are linear and we can add our solutions to get:

This confirms our prediction about P2/4 the stroking and the irrelevance of the middle spring.

2<sup>nd</sup> mode:  $\omega_2 = \sqrt{3k/m}$

$$(\vec{K} - \omega_2^2 \vec{M}) \vec{a} = \begin{pmatrix} -k & -k \\ -k & -k \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 0$$

$$\Rightarrow a_1 + a_2 = 0 \Rightarrow a_1 = -a_2 = Ae^{-i\delta}$$

$$\Rightarrow \vec{x}(t) = \begin{pmatrix} A \\ -A \end{pmatrix} \cos(\omega_2 t - \delta)$$

$$\vec{x}(t) = A_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos(\omega_1 t - \delta_1) + A_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos(\omega_2 t - \delta_2)$$

But wait, this solution has four arbitrary constants,  $\frac{1}{2}$

$\Rightarrow$  It's the general solution!

(two 2<sup>nd</sup> order linear ODEs  $\Rightarrow$  4 arbitrary constants). As

always we determine  $A_1, A_2, \delta_1$  and  $\delta_2$  from the initial conditions  $x_1(0), \dot{x}_1(0), x_2(0), \dot{x}_2(0)$ .

Normal coordinates: When we began we

found

$$m \ddot{x}_1 = -(\cancel{2k} + k_2) x_1 + k x_2$$

$$m \ddot{x}_2 = k x_1 - 2k x_2$$

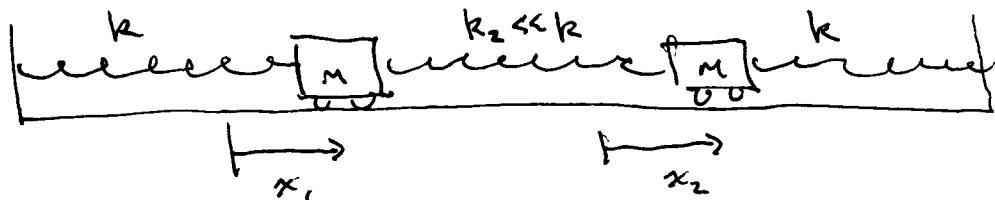
Are there coordinates in which these two equations decouple? Yes, and they are called "normal coordinates":

$$\xi_1 = \frac{1}{2}(x_1 + x_2)$$

$$\xi_2 = \frac{1}{2}(x_1 - x_2)$$

### III Weak Coupling

This is a different specialization of our original toy model:



We have  $\vec{M} = \text{diag}(m, m)$  and

$$\vec{K} = \begin{pmatrix} k+k_2 & -k_2 \\ -k_2 & k+k_2 \end{pmatrix} \quad \left( \vec{K} - \omega^2 \vec{M} \right) = \begin{pmatrix} k+k_2 - \omega^2 m & -k_2 \\ -k_2 & k+k_2 - \omega^2 m \end{pmatrix}$$

In normal coordinates our P3/4  
two modes simplify

$$\left. \begin{aligned} \xi_1(t) &= A \cos(\omega_1 t - \delta) \\ \xi_2(t) &= 0 \end{aligned} \right\} \text{sloshing}$$

and

$$\left. \begin{aligned} \xi_1(t) &= 0 \\ \xi_2(t) &= A \cos(\omega_2 t - \delta) \end{aligned} \right\} \text{breathing}$$

Again the general solution is a combination but now the frequencies don't mix.

Then

$$\det(\vec{K} - \omega^2 \vec{M}) \stackrel{\text{skip some algebra}}{=} (k - m\omega^2)(k + 2k_2 - m\omega^2)$$

$$\Rightarrow \omega_1 = \sqrt{\frac{k}{m}} \quad \text{and} \quad \omega_2 = \sqrt{\frac{k + 2k_2}{m}}$$

You won't be surprised to hear that the modes are the same: sloshing and breathing. But,

there's still some

interesting new physics.

For weak coupling  $\omega_2$  is only slightly larger than  $\omega_1$  ( $k_2$  is small). Let

$$\omega_0 = \frac{\omega_1 + \omega_2}{2}$$

and define

$$\omega_1 = \omega_0 - \epsilon \quad \text{and} \quad \omega_2 = \omega_0 + \epsilon$$

i.e.  $\epsilon = \frac{\omega_2 - \omega_1}{2}$ . Lets also pick initial

conditions s.t.  $A_1 = A_2 = A/2$  and  $\delta_1 = \delta_2 = 0$

then

$$x_1(t) = A \cos(\epsilon t) \cos \omega_0 t$$

$$x_2(t) = A \sin(\epsilon t) \sin \omega_0 t$$

These are enveloped oscillations P4/4 at frequency  $\omega_0$ , with the envelope period  $2\pi/\epsilon$ . This is beating!

What's doing the beating? It's the two normal coordinates

$$\xi_1(t) = \frac{1}{2} A \cos[(\omega_0 - \epsilon)t] = \frac{1}{2} A \cos(\omega_1 t)$$

$$\xi_2(t) = \frac{1}{2} A \cos[(\omega_0 + \epsilon)t] = \frac{1}{2} A \cos(\omega_2 t).$$