

## Today's Outline

I Survey Results

II Brief Recap of Geodesics

III Central Force Problem

by  $\xi$  a killing vector

with corresponding cons. law

$$+ \xi \cdot u = \text{const.}$$

- Geodesics can be used to construct the coords of a locally inertial frame with

$$g_{\alpha\beta}(x_p) = \eta_{\alpha\beta} \quad \frac{\partial g^{\alpha\beta}}{\partial x^\gamma} \Big|_{x=x_p} = 0.$$

Called Riemann normal coords.

## Lecture 12

Feb 28<sup>th</sup>, 2012

I Survey Results

see slides

P1/4

## II Brief Recap of Geodesics

- Arrived at Geodesic Eqn through a variational principle:

$$\frac{du^\kappa}{d\tau} + \Gamma_{\mu\nu}^\kappa u^\mu u^\nu = 0$$

$\Gamma$  are the Christoffel symbols.

- Easier to solve the GE when there are symmetries characterized

## III Central Force Problem

### Schwarzschild Geometry

In this lecture, and the next two, we begin our exploration of the Schwarzschild geometry:

$$ds^2 = - \left(1 - \frac{2GM}{c^2 r}\right) (cdt)^2 + \left(1 - \frac{2GM}{c^2 r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$$

This metric describes the geometry of a spherically symmetric source of curvature.

In G.R. mass is a subtle concept; recall our example of a barrel of masses from the first lecture. Note that if  $\frac{GM}{c^2 r}$  is small we can expand the first term to get

$$\text{Second} \quad ds^2 = dt^2 + \sin^2\theta d\phi^2 \\ ds^2 = -\left(1 - \frac{2GM}{c^2 r}\right)(dt)^2 + \left(1 + \frac{2GM}{c^2 r}\right)dr^2 + r^2 d\theta^2$$

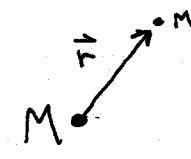
Very similar to

$$ds^2 = -\left(1 + \frac{2\Phi}{c^2}\right)(dt)^2 + \left(1 - \frac{2\Phi}{c^2}\right)(dx^2 + dy^2 + dz^2)$$

and suggests the identification  $\Phi = -\frac{GM}{r}$

relativistic physics.

### Central Force Problem

  $V(r)$  potential energy only depends on  $r = |\vec{r}|$ .

Because of conservation of angular mom.

$\vec{L} = \vec{r} \times \vec{p}$ , motion is confined to a plane.

So, we'll use polar coords in this plane

$$(r, \phi) : v_r = \dot{r}, v_\phi = r\dot{\phi} \quad (\bullet = \frac{d}{dt} \text{ non-red})$$

$$\Rightarrow v^2 = v_r^2 + v_\phi^2 = \dot{r}^2 + r^2\dot{\phi}^2$$

and interpretation of  $M^{-P/4}$  as the mass of the spherically sym. body. These turn out to be correct at lowest order.

As promised we will explore this geometry by examining its geodesics. Before doing this it will be very useful to remind ourselves of how central forces work in non-

### Conservation of Energy:

$$E = K.E. + P.E. = \frac{1}{2}m\dot{r}^2 + V(r) \\ = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\phi}^2) + V(r)$$

### Conservation of ang. mom.:

$$L = mr^2\dot{\phi}$$

$$\text{Eliminate } \dot{\phi} : \dot{\phi} = \frac{L}{mr^2}$$

$$\Rightarrow E = \frac{1}{2}m\dot{r}^2 + \frac{1}{2}mr^2 \frac{L^2}{m^2r^4} + V(r)$$

$$\boxed{E = \frac{1}{2}m\dot{r}^2 + \frac{L^2}{2mr^2} + V(r)}$$

We only want the shape of the orbit;  
use  $\phi$  (instead of  $t$ ) as the indep. variable:

$$\dot{r} = \frac{dr}{dt} = \frac{dr}{d\phi} \frac{d\phi}{dt} = \frac{L}{mr^2} \frac{dr}{d\phi}$$

Change to  $u \equiv 1/r$  ( $r = \frac{1}{u}$ )  $\rightarrow u(\phi)$

$$\frac{dr}{d\phi} = \frac{dr}{du} \frac{du}{d\phi} = -\frac{1}{u^2} \frac{du}{d\phi}$$

$$\dot{r} = \frac{L}{m} u^2 \left( -\frac{1}{u^2} \frac{du}{d\phi} \right) = -\frac{L}{m} \frac{du}{d\phi}$$

$+$ : coming in for increasing  $\phi$

$-$ : going out for increasing  $\phi$

### The Kepler Problem:

$$V(r) = -\frac{GMm}{r} = -GMmu$$

$$\frac{du}{d\phi} = \sqrt{\frac{2mE}{L^2} + \frac{2GMm^2}{L^2} u - u^2} = \sqrt{I(u)}$$

$$I(u) = \frac{2mE}{L^2} + \frac{2GMm^2}{L^2} u - u^2$$

Intro notation  $u' = \frac{du}{d\phi}$ ,

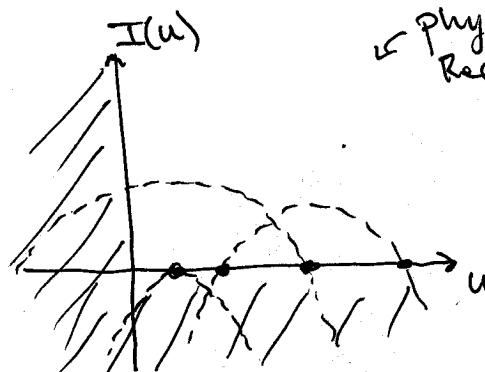
$$E = \frac{1}{2} m \frac{L^2}{m^2} u'^2 + \frac{L^2 u^2}{2m} + V$$

$$= \frac{L^2}{2m} (u'^2 + u^2) + V$$

$$\Rightarrow \boxed{u'^2 = \frac{2m}{L^2} (E - V) - u^2}$$

or

$$u' = \pm \sqrt{\frac{2m}{L^2} (E - V) - u^2}$$



physical  
Region  $u = \frac{1}{r} > 0$  (physically)

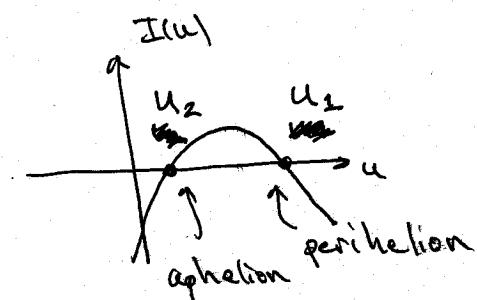
$I(u) > 0$ , because

$$\frac{du}{d\phi} = \sqrt{I}$$

### Two Cases:

$$u_2 > 0$$

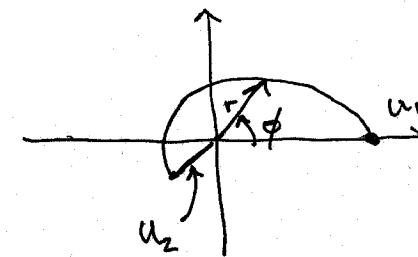
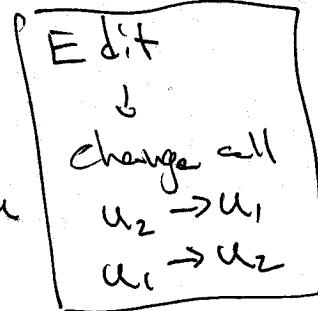
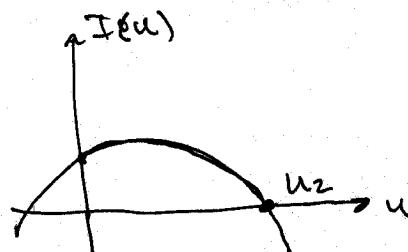
orbits bounded



$u_1 < 0$

unbounded-

(scattering)



orbital plane

P4/4

Case 1 (orbits)  $u_1 > 0$

$$I(u) = (u - u_1)(u_2 - u)$$

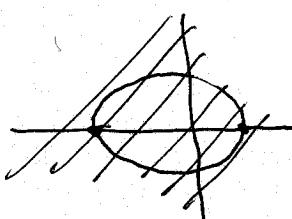
$$\Rightarrow \frac{du}{d\phi} = \sqrt{(u - u_1)(u_2 - u)}$$

From table,

$$\int \frac{du}{\sqrt{(u - u_1)(u_2 - u)}} = \sin^{-1}\left(\frac{2u - u_2 - u_1}{u_2 - u_1}\right)$$

$$\begin{aligned} \Rightarrow \Phi &= \sin^{-1}\left(\frac{u_2 - u_1}{u_2 - u_1}\right) - \sin^{-1}\left(\frac{u_1 - u_2}{u_2 - u_1}\right) \\ &= \sin^{-1}(1) - \sin^{-1}(-1) = \frac{\pi}{2} - \left(-\frac{\pi}{2}\right) = \pi \end{aligned}$$

Orbit is an ellipse with origin at one focus



orb.  
plane

