

Today's Outline

Lecture 13
April 1st, 2012

I Wrap up Central Force Problem

P/4

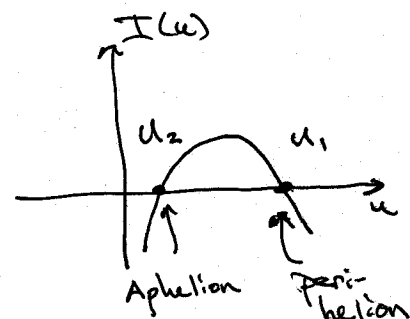
I Wrap up Central Force Problem

II Schwarzschild: Energy & Effective potential

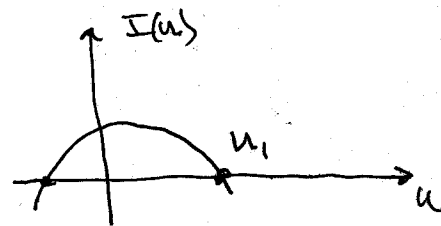
III Precession

Two Cases:

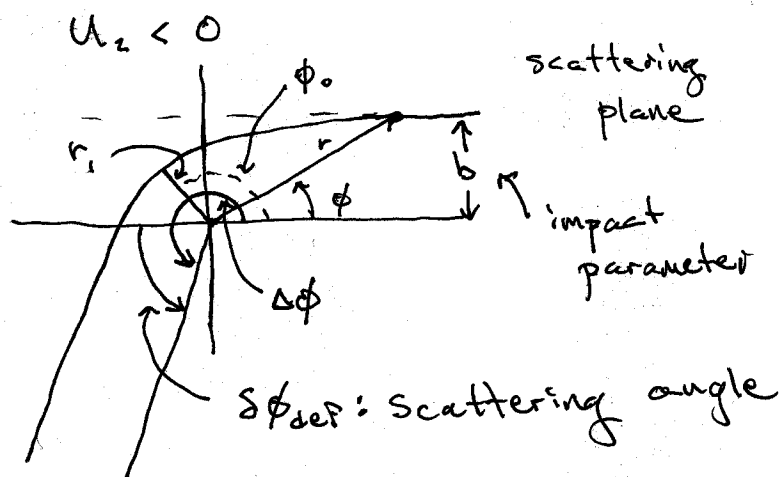
$u_2 > 0$
orbits bounded



$u_2 < 0$
 u_1 bounded
(scattering)



We did case 1, let's do case 2:



$$\frac{du}{d\phi} = \sqrt{I(u)} = \sqrt{(u-u_2)(u_1-u)}$$

$$\Rightarrow \Delta\phi = 2\phi_0 = 2 \int_0^{u_1} \frac{du}{\sqrt{(u-u_2)(u_1-u)}}$$

$$= 2 \left[\sin^{-1} \left(\frac{u_1-u_2}{u_1-u_2} \right) - \sin^{-1} \left(\frac{-u_1-u_2}{u_1-u_2} \right) \right]$$

$$= 2 \left[\sin^{-1}(1) + \sin^{-1} \left(\frac{u_1+u_2}{u_1-u_2} \right) \right]$$

$$= \pi + 2 \sin^{-1} \left(\frac{u_1+u_2}{u_1-u_2} \right)$$

But $\delta\phi_{\text{def}} = \Delta\phi - \pi,$

$\Rightarrow \delta\phi_{\text{def}} = 2 \sin^{-1} \left(\frac{u_1 + u_2}{u_1 - u_2} \right)$

or

$$\boxed{\sin \left(\frac{\delta\phi_{\text{def}}}{2} \right) = \frac{u_1 + u_2}{u_1 - u_2}}$$

Plug in $E|_0 = \frac{1}{2} m v^2$ and $L = m v b$ to find u_1, u_2 and classical scattering result

$$\cot \left(\frac{\delta\phi_{\text{def}}}{2} \right) = \frac{b v^2}{G M}$$

for constant t and r , one generator is ϕ -translations, i.e.

$\eta^\alpha = (0, 0, 0, 1)$ is a killing vector.

To study geodesics we'll use the conserved quantities arising from these symmetries,

$$e \equiv -\dot{\gamma} \cdot \underline{u} = -g_{\alpha\beta} \dot{\gamma}^\alpha u^\beta$$

$$= -g_{00} \dot{\gamma}^0 u^0 = \left(1 - \frac{2M}{r}\right) \frac{dt}{d\tau}$$

conserved
Energy per
unit
test mass

II Schwarzschild: Energy & Effective Potential P2/4

Sch. spacetime has two important symmetries:

$$ds^2 = -\left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$$

It is static, i.e. independent of time, and hence

$\xi^\alpha = (1, 0, 0, 0)$ is a killing vector.

It is also spherically symmetric

$$l \equiv \underline{\eta} \cdot \underline{u} = g_{\alpha\beta} \eta^\alpha u^\beta$$

$$= g_{33} \eta^3 u^3 = r^2 \sin^2 \theta \frac{d\phi}{d\tau}$$

Ang. Mom.
per
unit rest
mass

If initially $\dot{\phi} = \frac{d\phi}{d\tau} = 0$ then ϕ is always zero and motion stays in the "plane" $\phi=0$.

Reorient so that $\theta = \frac{\pi}{2}$ and $u^\theta = 0$

As always, we use

$$\underline{u} \cdot \underline{u} = -1$$

$$-1 = g_{\alpha\beta} u^\alpha u^\beta = -\left(1 - \frac{2M}{r}\right) (u^t)^2 + \left(1 - \frac{2M}{r}\right)^{-1} (u^r)^2 + r^2 (u^\phi)^2$$

$$\Rightarrow -\left(1 - \frac{2M}{r}\right)^{-1} e^2 + \left(1 - \frac{2M}{r}\right)^{-1} \left(\frac{dr}{d\tau}\right)^2 + \frac{l^2}{r^2} = -1$$

$$\Rightarrow -e^2 + \left(\frac{dr}{d\tau}\right)^2 + \frac{l^2}{r^2} \left(1 - \frac{2M}{r}\right) = -\left(1 - \frac{2M}{r}\right)$$

$$\Rightarrow e^2 = \left(\frac{dr}{d\tau}\right)^2 + \left(1 - \frac{2M}{r}\right) \left(1 + \frac{l^2}{r^2}\right)$$

Subtract 1 from each side and mult. by $\frac{1}{2}$,

$$\mathcal{E} \equiv \frac{e^2 - 1}{2} = \frac{1}{2} \left(\frac{dr}{d\tau}\right)^2 + \frac{1}{2} \left[\left(1 - \frac{2M}{r}\right) \left(1 + \frac{l^2}{r^2}\right) - 1 \right]$$

Can calculate r_{min} and r_{max} ,

$$r_{min}^{max} = \frac{l^2}{2M} \left[1 \pm \sqrt{1 - 12 \left(\frac{M}{l}\right)^2} \right]$$

Note that for $l < \sqrt{12} M$ extrema disappear.

Example: Stable Circular Orbits

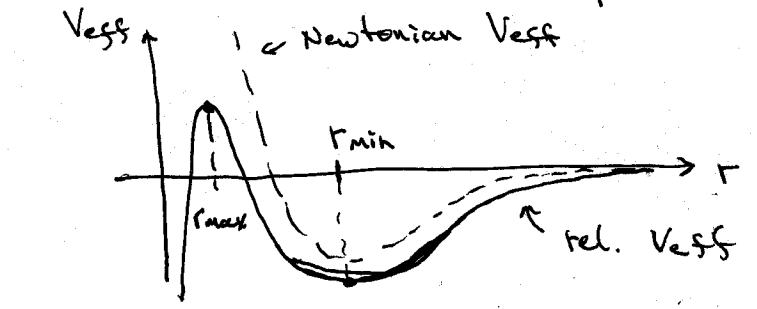
Circular orbits can occur at r_{min} and r_{max} but are only stable at r_{min}

This is now of the form

$$\mathcal{E} = \frac{1}{2} \left(\frac{dr}{d\tau}\right)^2 + V_{eff}(r)$$

(everything per unit mass) with

$$V_{eff} = -\frac{M}{r} + \frac{l^2}{2r^2} - \frac{Ml^2}{r^3}$$



For given l there's only one r_{min} but by varying l we can ask for the innermost stable circ. orbit (ISCO). The extrema coalesce and disappear when $l = \sqrt{12} M$ and hence

$$r_{ISCO} = \frac{12M^2}{2M} = 6M$$

Another calculation: What's $\Omega = \frac{d\phi}{dt}$ for circular orbits?

$$\Omega = \frac{d\phi}{dt} = \frac{d\phi/dz}{dt/dz} = \frac{1}{r^2} \left(1 - \frac{2M}{r}\right) \left(\frac{l}{e}\right)$$

Using r_{min} and $e^2 = \left(1 - \frac{2M}{r}\right) \left(1 + \frac{l^2}{r^2}\right)$
 some algebra gives,

$$\frac{l}{e} = (Mr)^{1/2} \left(1 - \frac{2M}{r}\right)^{-1} \quad \text{for circular orbits}$$

Then,
$$\Omega = \frac{(Mr)^{1/2}}{r^2}$$

$$\Rightarrow \boxed{\Omega^2 = \frac{M}{r^3}}$$

circular orbits
 in Sch. coords.

Four velocity, $u^\alpha = d\phi/dz$ 94/4

$$u^\alpha = u^t (1, 0, 0, \Omega)$$

$$\begin{aligned} \underline{u} \cdot \underline{u} &= -1 = g_{00} u^{t2} + g_{33} u^{t2} \Omega^2 \\ &= -\left(1 - \frac{2M}{r}\right) u^{t2} + r^2 \frac{M}{r^3} u^{t2} \end{aligned}$$

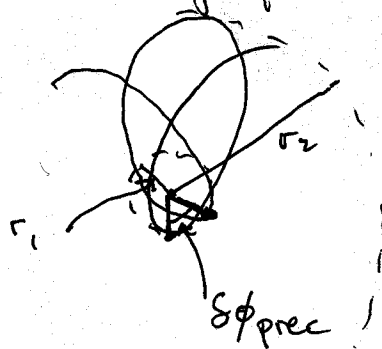
$$\Rightarrow u^{t2} \left(1 - \frac{2M}{r} - \frac{M}{r}\right) = 1$$

$$\Rightarrow \boxed{u^t = \left(1 - \frac{3M}{r}\right)^{-1/2}} \quad \text{circular orbits}$$

III Precession

Because of the relativistic correction $-\frac{Ml^2}{r^3}$
 bound orbits no longer close into ellipses!

Instead, they precess,



Just as before

$$\frac{dr}{dz} = \sqrt{2(\mathcal{E} - V_{eff})}$$

$$\Rightarrow \left| \frac{du}{d\phi} \right| = \frac{1}{l} \frac{dr}{dz} = \frac{\sqrt{2(\mathcal{E} - V_{eff})}}{l}$$

$$\Rightarrow I(u) = \frac{2}{l^2} (\mathcal{E} - V_{eff})$$

$$= \frac{2\mathcal{E}}{l^2} + \frac{2M}{l^2} u - \frac{l^2 \rightarrow 1}{l^2} u^2 + 2Mu^3$$