

# Intro Physics

Today 0. Review Exam, remind Q's, HW  
I best time

## II A Theory of Interactions: Momentum

I • First a families  
fact: We can choose any time to be  $t=0$  and any pt to be  $x=0, y=0$  (and  $z=0$ ); the rules of motion are the same, e.g.

$$y(t) = y_0 + v_{0y}t + \frac{1}{2}at^2$$

for constant acceleration.

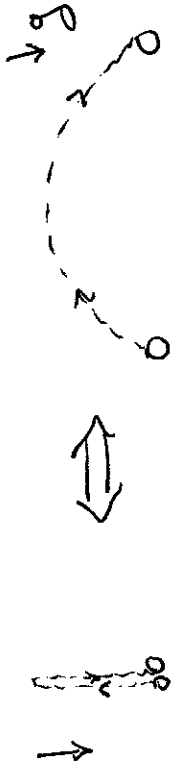
ex



This actually implies Galileo's principle of inertia: "Non-interacting objects maintain constant velocity" inertial

This is true in all frames (though the constant  $v$ 's may differ).

• More surprisingly: We can also choose any constant speed (inertial) frame to be  $v=0$ ! The motion in different frames looks different, but the rules are the same



• We found how to transform between frames

$$\vec{v}_{AC} = \vec{v}_{AB} + \vec{v}_{BC}$$

Here

A is frame A e.g. Ball's frame, boat's frame, bird's frame

B is frame B e.g. skateboarder's frame, river frame, wind frame

C is frame C e.g. ground frame

$\vec{v}_{AC}$  is the velocity of frame

A w.r.t. frame C and

Similarly for  $\vec{v}_{BC}$  and  $\vec{v}_{AB}$ .

For example, the velocity of the ball w.r.t. the ground.

Note that a choice of coordinates is essential, e.g. for sign  $\vec{v}_{AC}$ .

### • Principle of Galilean Relativity:

"The rules of motion are the same in all inertial frames."

This is a goal, but a nice one if possible. We'll have to see.

Most importantly, if we take this as a principle we can start to develop a theory of interactions.

### II Consider a simple interaction:

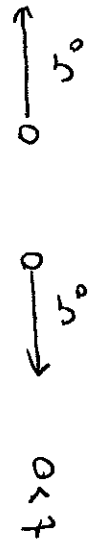
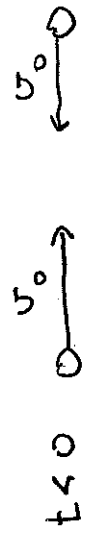
two identical objects moving toward each other at the same speed collide head on



What happens?

It turns out that there are three possibilities:

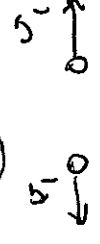
"Elastic collision"



reverses velocities

Idealized, but close to accurate for hard, elastic objects (billiard or bouncy balls)

"Realistic inelastic collision"



$v_1 < v_2$

Most realistic collisions

"Completely inelastic collision"



Let's reconsider these collisions from a frame moving  $\leftarrow v_0$  (add  $v_0$  to all vectors)

Elastic

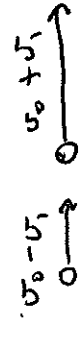
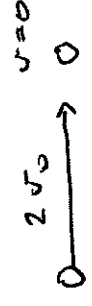


collision transfers, but preserves velocity.

Is velocity always preserved?

We see from the table above that velocity is not always preserved! But, the idea of looking for something that is preserved is

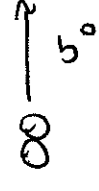
Inelastic



Before:  $2v_0$

After:  $v_0 - v_1 + (v_0 + v_1) = 2v_0$

Completely Inelastic



Velocity is

certainly not preserved!

Let's check if momentum is preserved: first elastic

P4/4

$$\vec{p}_{tot, i} = m(2\vec{v}_0) + m(0) = 2m\vec{v}_0$$

initial  $\nearrow$  zero speed  $\downarrow$

$$\text{and } \vec{p}_{tot, f} = m(0) + m(2\vec{v}_0) = 2m\vec{v}_0$$

Yes! it's preserved. Let's check the other two cases as well:

profound: The change in speed in the last example seems to be related to the doubling of the amount of stuff. This is correct and we characterize it quantitatively by the mass of the object. We introduce momentum

$$\text{momentum: } \vec{p} = m \cdot \vec{v}$$

mass  $\nearrow$  velocity  $\nwarrow$

Inelastic:

$$\vec{p}_{tot, i} = 2\vec{v}_0 m + 0 = 2m\vec{v}_0$$

$$\text{and } \vec{p}_{tot, f} = m(\vec{v}_0 - \vec{v}_1) + m(\vec{v}_0 + \vec{v}_1) = 2m\vec{v}_0 \quad \text{Yes!}$$

Completely inelastic:

$$\vec{p}_{tot, i} = m(2\vec{v}_0) + 0$$

$$\text{and } \vec{p}_{tot, f} = 2m(\vec{v}_0) = 2m\vec{v}_0$$

Yes, again!

This leads to our first theory of interactions: they preserve the total momentum in the system! We call this 'conservation of momentum' and it is a profound result.

We'll build up the rest of our results from this.