

Math Methods II

Day 2

Today

0. Discussion of "Hidden Value of Ignorance"
 I Last time

II Angular momentum & cross products

III 3D geometry with vectors

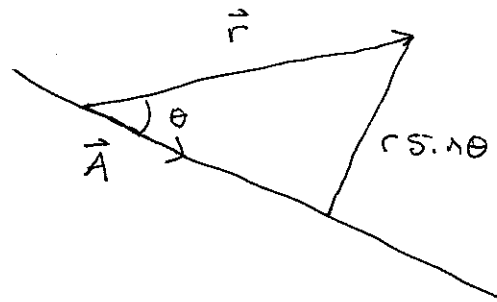
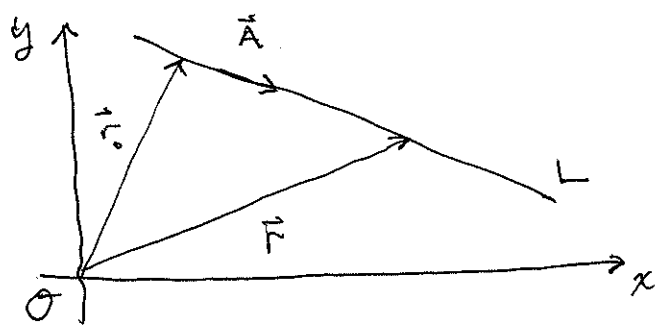
I. Reviewed vector Space axioms

• Found 3 forms for the eqn. of a line:

$$\vec{r} = \vec{r}_0 + t\vec{A}; \quad \vec{A} = (a_1, a_2) \text{ (vec.)}$$

$$y = mx + b; \quad m = \frac{a_2}{a_1}, \quad b = y_0 - \frac{a_2}{a_1}x_0 \text{ (Slope-Intercept)}$$

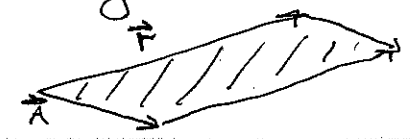
$$\frac{x-x_0}{a_1} = \frac{y-y_0}{a_2} \text{ (symmetric)}$$



$l = \text{mass} \times \text{speed} \times \text{perp. distance from } O \text{ to } L$

$\hat{l} = \text{into page (use right-hand rule)}$

(2) $l = \text{area of parallelogram spanned by } \vec{r} \text{ and } \vec{A} \times \text{mass}$



II What is the angular momentum of the ball w.r.t. O?

(1) $\vec{l} = \vec{r} \times \vec{p} = \vec{r} \times m\vec{v} = m(\vec{r} \times \vec{v})$

We noted last time $\vec{v} = \vec{A}$ (see vec),

so $\vec{l} = m(\vec{r} \times \vec{A}) \Rightarrow l = m r A \sin \theta$

(3) Descriptions (1) and (2) are good for interpretation. A good method for computation in components is

$$\vec{l} = m \det \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x & y & z \\ a_1 & a_2 & a_3 \end{vmatrix}$$

$$= m \left[(a_3 y - a_2 z) \hat{x} + (a_1 z - a_3 x) \hat{y} + (a_2 x - a_1 y) \hat{z} \right]$$

Given vectors $\vec{u}, \vec{v}, \vec{w} \in V$ their span is the set of all vectors that can be obtained as linear combos of these vectors.

A basis is a set of linearly independent vectors s.t.

$$\text{Span} \{ \hat{e}_1, \dots, \hat{e}_N \} = V.$$

The dimension of a vector space is

$$\dim V = \# \{ \hat{e}_1, \dots, \hat{e}_N \} (= N \text{ here}).$$

Aside: Vector space structure P2/2

Inner product: $\vec{A} \cdot \vec{B} = \sum_{i=1}^{\dim V} A_i B_i$

Norm: $A = \sqrt{\vec{A} \cdot \vec{A}} = \|\vec{A}\| = |\vec{A}|$

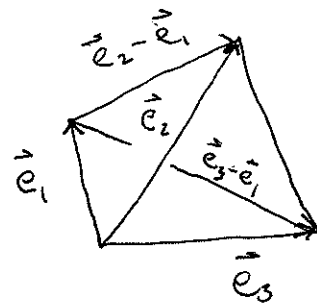
Cross product: $\vec{C} = \vec{A} \times \vec{B} = AB \sin \theta \hat{C}$ right hand rule

Basis: $\{ \hat{e}_1, \hat{e}_2, \dots, \hat{e}_N \}$ Kronecker delta

Orthonormal iff $\hat{e}_i \cdot \hat{e}_j = \delta_{ij}$

$$\delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

III In quantum gravity a classical model for a grain of space is a tetrahedron.



Suppose you are given 3 of its edge vectors. Construct the 4 vectors perpendicular to its faces