

Today

Math Methods

P1/5

I last time

Day 6

I • Found

II More examples of integral curves

$$\frac{d\vec{r}}{dt} = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$$

III Vector derivatives I:

The Gradient

• Introduced vector fields, e.g. $\vec{E}(x, y, z)$ or $\vec{v}(x, y, z)$

• Found the integral curve of a velocity vector field

Using

$$\frac{d\vec{r}}{dt} = \vec{v} \Rightarrow \vec{r} = \int \vec{v} dt.$$

II But, more generally, what defines an integral curve?

Def: An integral curve of a vector field is a curve

whose tangent vectors agree with the given vector field.

First important point: an integral curve need not be parametrized by time. We don't usually think of an electric field line as being traversed in time. To emphasize this point we will often take the parameter of an integral curve to be λ , which has no interpretational

amounts to solving this Eq. for $\vec{r}(\lambda)$.

and finding the integral curve amounts to solving this Eq. for $\vec{r}(\lambda)$.

this can be written

$$\frac{d\vec{r}}{d\lambda} = \vec{u}$$

overlays.

Let's do some examples. Coordinates actually furnish a nice example.

EX. Find the coordinate curves of the Cartesian basis $\{\hat{x}, \hat{y}\}$ of \mathbb{R}^2 .

The basis vector \hat{x} is a vector field.

It doesn't depend on position. The integral curve condition is (recall

$$\vec{r} = x\hat{x} + y\hat{y} \quad \text{in this case}$$

$$\frac{d\vec{r}}{d\lambda} = \hat{u} = \hat{x}$$

$$\text{or } \frac{dx}{d\lambda} \hat{x} + \frac{dy}{d\lambda} \hat{y} = \hat{x}$$

Another nice example is the electric field of a point charge:

$$\vec{E} = k \frac{q}{r^2} \hat{r}, \quad \text{with } k \equiv \frac{1}{4\pi\epsilon_0}$$

Here it is convenient to work in spherical polar coordinates (r, θ, ϕ) .

Again we have

$$\frac{d\vec{r}}{dt} = \vec{E}$$

and by symmetry the integral curves must have $\theta = \text{const.} = C_1$, $\phi = \text{const.} = C_2$

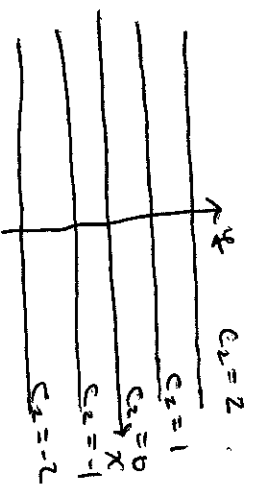
Working with the component r^2 equations, this is

$$\frac{dx}{d\lambda} = 1 \quad \text{and} \quad \frac{dy}{d\lambda} = 0$$

$$\text{or } x = \lambda + C_1 \quad \text{and} \quad y = C_2$$

Choosing $\lambda=0$ at $x=0$ sets $C_1=0$ and for different values of C_2 we get the curves:

A similar treatment of \hat{y} gives the vertical coord. curves.



So, this is just, $\vec{r} = r\hat{r}$ and

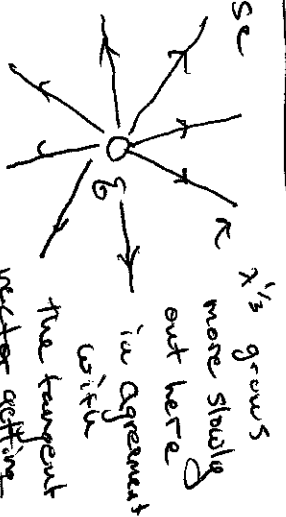
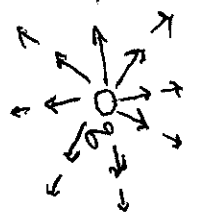
$$\frac{dr}{d\lambda} = k \frac{q}{r^2} \Rightarrow r^2 dr = kq d\lambda$$

Integrating gives

$$r^3/3 = kq\lambda + \text{const}$$

$$\text{or } r(\lambda) = (3kq\lambda + C_0)^{1/3}$$

This makes sense



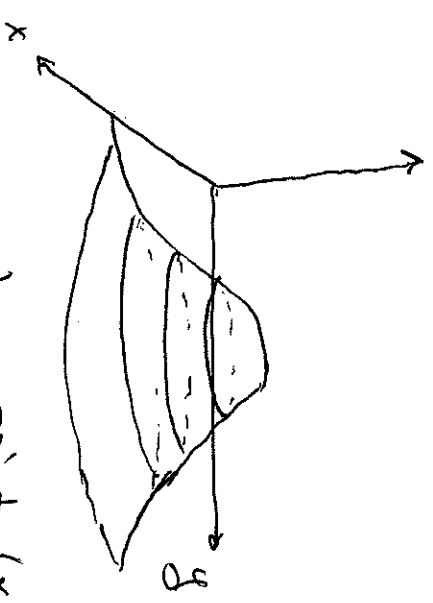
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III We're starting to appreciate how useful it is to take derivatives and integrals of vector fields.

I don't think you'll be surprised that there are more complicated differential and integral operations for vector fields. The simplest of these operators is the gradient.

Consider a scalar field $f(x, y)$,

Say the height of a mountain or the temperature of a metal sheet $f(x, y)$



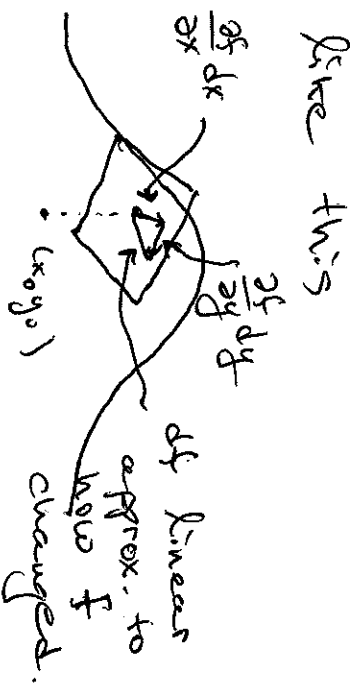
If we start at a point (x_0, y_0) of the xy -plane how does the height vary

as we move around the plane?

Well it depends. It depends on what direction we move in. In some directions the height doesn't change and in others we could have to climb steeply. The total derivative or differential of f captures this mathematically: height we have to climb if we move a little in the x -direction

$$df(x,y) = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

ditto for y -dir



In the limit of smaller and smaller displacements, this becomes exact.

Notice that we can write

$$df = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) \cdot (dx, dy)$$

$$\equiv \vec{\nabla} f \cdot d\vec{r}$$

The differential gives us how much we have to climb if we move in an arbitrary direction (a little in x , dx , and a little in y , dy). Why is it enough to just add these contributions?

It's because we're imagining the displacements are small enough that the hill can be approximated by a plane at (x_0, y_0) .

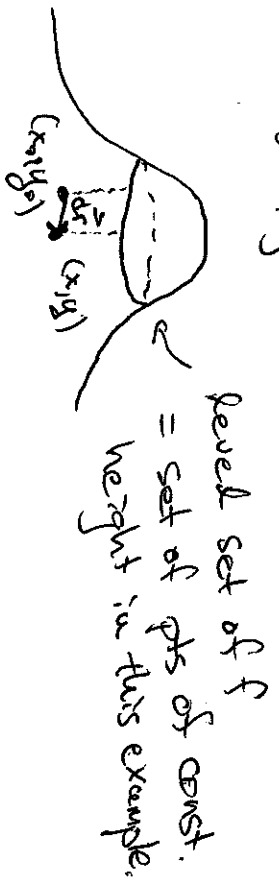
Here

$$\vec{\nabla} f \equiv \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)$$

is the gradient of f .

Now consider a level set of f , that is, the set of all pts (x,y) s.t.

$$f(x,y) = \text{const.}$$



What if we chose to move along a $d\vec{r}$ such that we remain on this level set? Then $df = d(\text{const.}) = 0$ and hence

$$\vec{\nabla}f \cdot d\vec{r} = 0 \quad \text{when } d\vec{r} \text{ along level set.}$$

Geometrically what does this imply?

That $\vec{\nabla}f$ is perpendicular to the level sets of f !