

Classical
Mechanics

0. Review of Newtonian Mechanics

P1/5

Day 1

0. Review Newtonian Mechanics

I. Why are simple harmonic oscillators everywhere?

II The standard Guess

$$F = ma = m \ddot{x}$$

"frequently in this course"

Generally

$$\dot{x} = \frac{dx}{dt} = v, \quad \ddot{x} = \frac{d^2x}{dt^2} = a$$

n times
 $x = \frac{d^n x}{dt^n}$

That's our whole review of

Newtonian mechanics. Why?
All of you are missing different pieces of Newtonian mechanics.
I would prefer to address these gaps with you individually.
Review chapters 1-4 and ask me ^{and each other} questions. We have plenty of new things to learn.

I. Why begin with oscillations?
Our world is permeated by oscillations, from the yielding sway of tree branches to the bumpy ride of the Bard Shuttle. The mathematics of oscillations runs even deeper than the mechanical examples

that come immediately to mind.

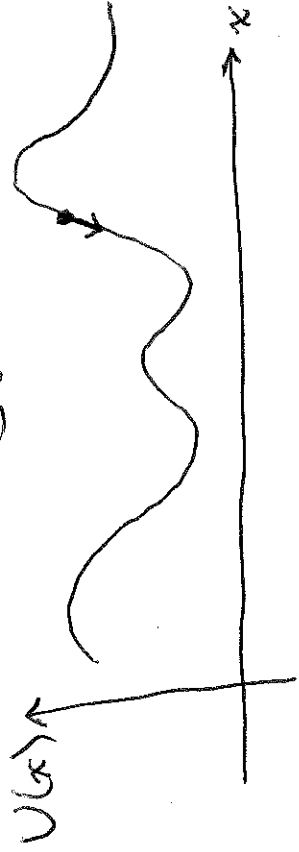
In summary:

- Physical examples surround us.

- Mathematical machinery is invaluable through physics:

from Electronics to Quantum Field Theory.

We can see a force as arising from a "desire" to minimize potential energy



Mathematically the force is captured by $F = - \frac{dU}{dx}$

Why are (1D) oscillations so generic? P2/5

Physical systems are often

well described by a potential energy: $U(x)$

This potential is closely related conceptually to forces because...

Equilibrium is when there is no net force or when

$$F = 0 = \frac{dU}{dx}$$

This is also the condition

for an extremum (max, min or inflection) of the



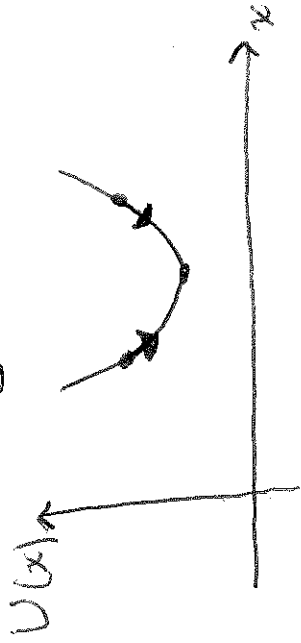
A maximum of the potential energy is an unstable equilibrium. Find 'em by

$$\frac{d^2U}{dx^2} < 0 \quad \left(\begin{array}{l} \text{end} \\ \frac{dU}{dx} = 0 \end{array} \right)$$

A minimum is a Stable equilibrium. Find 'em by

$$\frac{d^2U}{dx^2} > 0$$

a restoring force.

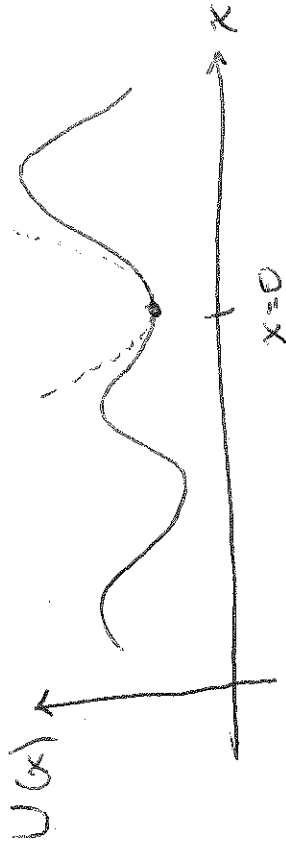


We can say more, Taylor expand the potential near an equilibrium at $x=0$

IF $\frac{d^2U}{dx^2} = 0$

the second derivative test fails.

Oscillations arise around stable equilibria! A small displacement (in either direction) pushes the system back towards the equilibrium position — there's



0 at equilib.

$$U(x) = U(0) + U'(0)(x) + \frac{1}{2} U''(0)x^2 + \dots$$

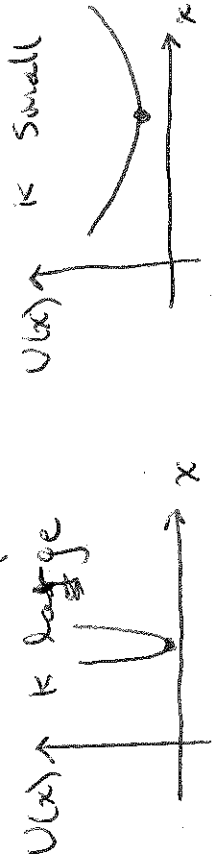
If we shift $U(0)$ to zero we have

$$U(x) = \frac{1}{2} U''(0)x^2 + \dots$$

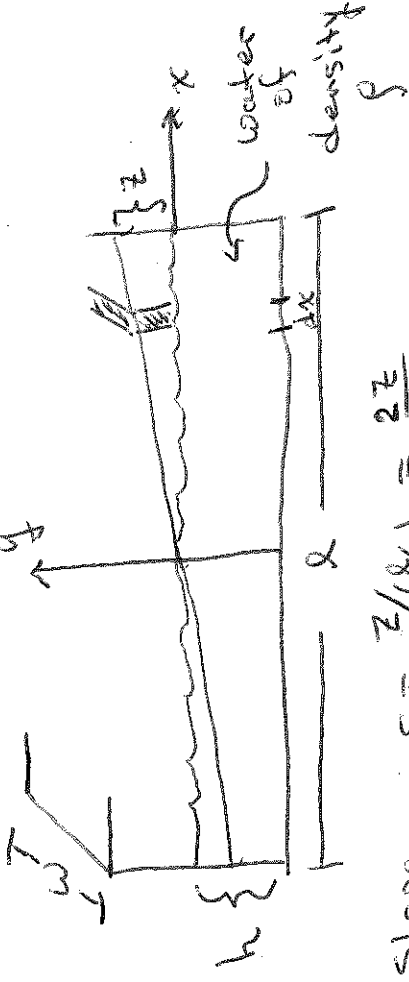
Compare this to the potential energy of a spring

$$U(x) = \frac{1}{2} k x^2$$

What does the spring constant tell us geometrically? The width of the potential



Example: Consider water sloshing in a large tub.



slope $s = z/(L/2) = \frac{2z}{L}$

and so, $y = \frac{2z}{L} x$

We've shown that

$$k = U''(x_{equilib.})$$

for positive $U''(x_{equilib.})$.

No matter what shape your potential has it looks like a harmonic oscillator near its minima (as long as $U'' > 0$).

$$dm = \rho w y dx = \rho w \frac{2z}{L} x dx$$

The center of mass is at a height $y/2$ for this slab, so

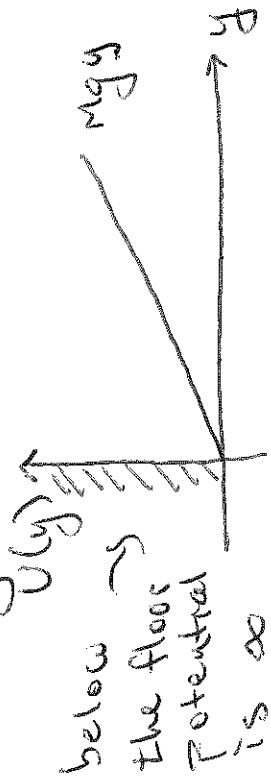
$$U(z) = \int_{-L/2}^{L/2} \rho w y \cdot \frac{y}{2} g dx$$

$$= \int_{-L/2}^{L/2} x^2 \left(\frac{1}{2} \rho w \left(\frac{2z}{L} \right)^2 \right) dx$$

$$= \frac{1}{6} \rho w g z^2 = \frac{1}{2} k z^2!$$

I hope to have convinced you that oscillations are everywhere.

Now, for a counter example: the bouncy ball



Can't do Taylor expansion because it's not differentiable.

Ordinary diff. eqn. (ODE): only

ordinary derivatives

Partial diff. eqn. (PDE): partial derivatives

Order of diff. eqn.: The highest deriv.

Most important method of solution is the "standard guess"

$$x(t) = e^{rt}$$

Change of perspective in this course PS/5

$$F = ma = -kx$$

$$\downarrow m \frac{d^2x}{dt^2} = -kx$$

$$\downarrow m \ddot{x} = -kx$$

We will learn many ~~techniques~~ techniques for writing down eqns. of motion but also for solving them.