

Outline

Classical

P1/3

I Driven damped oscillator

Mechanics

I We found the E.O.M.:

Day 4

call it →
(driven)

$$\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = f(t) \equiv \frac{F(t)}{m}$$

Decided to focus on drive

$$f(t) = f_0 \cos(\omega t)$$

Recall, $\omega_0 =$ natural freq.

$\omega =$ driving freq.

So to solve (driven) we focus on finding a particular soln. Do this by hook or by crook!

$$\ddot{x} + 2\beta \dot{x} + \omega_0^2 x = f_0 \cos(\omega t)$$

Exponentials are nice, so view this as the real part of

$$\ddot{z} + 2\beta \dot{z} + \omega_0^2 z = f_0 e^{i\omega t}$$

where $z(t) \equiv x(t) + iy(t)$.

We realized

$$\begin{aligned} \mathcal{D}(x_h + x_p) &= \mathcal{D}x_h + \mathcal{D}x_p \\ &= 0 + f(t) \end{aligned}$$

where

$$\mathcal{D} = \frac{d^2}{dt^2} + 2\beta \frac{d}{dt} + \omega_0^2$$

$x_h =$ general soln. of inhomo. eqn.

$x_p =$ "particular soln."

[On the homework you will show it doesn't matter what x_p you use.]

Then the imaginary part is

$$\ddot{y} + 2\beta\dot{y} + \omega_0^2 y = f_0 \sin \omega t.$$

Try to guess a particular soln

$$z_p = C e^{i\omega t}$$

Physically this says that if we drive an osc. at freq. ω we might expect it to respond at the same freq. ω . Then

$$\begin{aligned} \text{Recall, } |e^{i\theta}|^2 &= e^{i\theta} \cdot e^{-i\theta} = 1 \\ \text{So, } |A|^2 &= |C|^2 = C \cdot C^* \text{ (complex conj.)} \\ &= \frac{f_0}{(\omega_0^2 - \omega^2) + 2\beta i \omega} \cdot \frac{f_0}{(\omega_0^2 - \omega^2) - 2\beta i \omega} \\ &= \frac{f_0^2}{(\omega_0^2 - \omega^2)^2 + 4\beta^2 \omega^2} \end{aligned}$$

This implies that

$$z_p = i \omega C e^{i\omega t} \quad \text{and } z = -\omega^2 C e^{i\omega t} / 3.$$

$$\begin{aligned} \text{and } -C \omega^2 e^{i\omega t} + 2\beta i \omega C e^{i\omega t} + \omega_0^2 C e^{i\omega t} \\ = f_0 e^{i\omega t} \end{aligned}$$

so,

$$C = \frac{f_0}{\omega_0^2 - \omega^2 + 2\beta i \omega}$$

We got a particular soln! We'll simplify it next. Nice to write

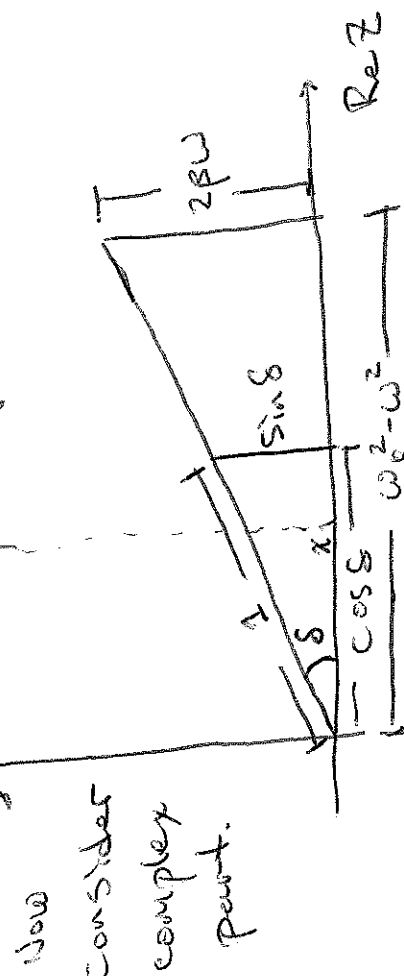
$$z_p = C e^{i\omega t} = A e^{-i\delta} e^{i\omega t}$$

\mathcal{R} real

$$A = \frac{f_0}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\beta^2 \omega^2}}$$

$\text{Im } z \uparrow$ $\mathcal{L} z$

Now consider complex point.



So, $C = Ae^{-i\delta}$ gives

$$i\delta = \frac{A}{C} (\omega_0^2 - \omega^2 + 2\beta i\omega)$$

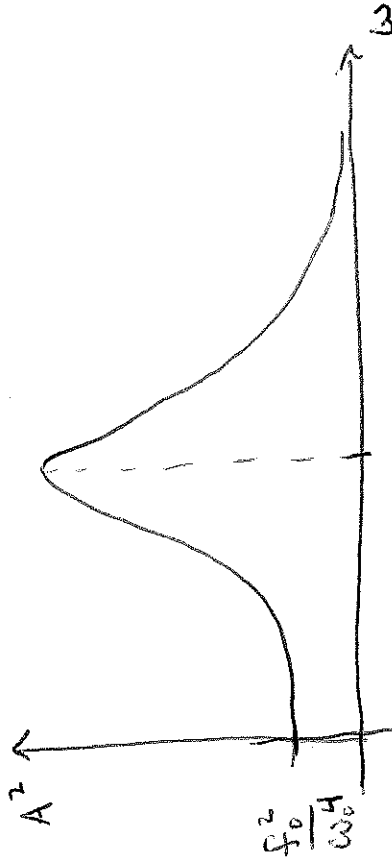
From the diagram

$$\tan \delta = \frac{2\beta\omega}{\omega_0^2 - \omega^2}$$

This gives us a way to find δ .

So our general solution is (Real part)
not arbitrary

$$x(t) = A \cos(\omega t - \delta) + C_1 e^{r_1 t} + C_2 e^{r_2 t}$$



$$A_{\max}^2 \approx \frac{f_0^2}{4\beta^2\omega_0^2} \approx \omega_0^2 \quad \left. \begin{array}{l} \text{Show this:} \\ \approx \omega_0^2 \end{array} \right\}$$

A^2 is max when the denominator is minimized, so it is near $\omega = \omega_0$, but

with the latter both $\beta \ll 1$
exponentially damped transients.
After transients have died out
the motion is independent of
initial conditions and the
 $A \cos(\omega t - \delta)$ term is called an
attractor.

II Resonance: Analyze the

$$\text{amplitude } A: A^2 = \frac{f_0^2}{(\omega_0^2 - \omega^2)^2 + 4\beta^2\omega^2}$$

Let's calculate it:

$$\frac{d}{d\omega} \left((\omega_0^2 - \omega^2)^2 + 4\beta^2\omega^2 \right) = 0$$

$$\Rightarrow 2(\omega_0^2 - \omega^2) \cdot (-2\omega) + 8\beta^2\omega = 0$$

$$\Rightarrow \omega^2 - \omega_0^2 + 2\beta^2 = 0 \quad \left\{ \begin{array}{l} \text{call it} \\ \omega_2 \end{array} \right.$$

$$\Rightarrow \omega = \sqrt{\omega_0^2 - 2\beta^2} \equiv \omega_2$$

Indeed, for small β

$$\omega_2 \approx \omega_0$$