

I What we've learned about angular momentum

Lect. 25

II Find the angular momentum eigenfunctions

I. $L_z = xP_y - yP_x$ etc.

$$L_{\pm} = L_x \pm iL_y$$

$$[L_x, L_y] = i\hbar L_z \text{ and } \mathcal{Q}$$

$$[L^2, L_z] = 0 \text{ and } x \text{ and } y$$

$$[L_z, L_{\pm}] = \pm \hbar L_{\pm}$$

We found

$$L^2 = L_z^2 + L_{\pm}^2 \mp \hbar L_z$$

and

$$L^2 f_l^m = \hbar^2 l(l+1) f_l^m$$

$$L_z f_l^m = \hbar m f_l^m$$

where

$$l = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$$

$$m = -l, -l+1, \dots, l-1, l.$$

II Classically $\vec{L} = \vec{r} \times \vec{p}$. As an operator

$$\hat{L} = \frac{\hbar}{i} \vec{r} \times \vec{\nabla}$$

In spherical coords (natural for ang. momentum and rotations)

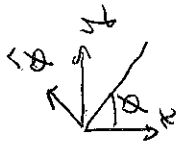
$$\vec{\nabla} = \hat{r} \frac{\partial}{\partial r} + \hat{\theta} \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{\phi} \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}$$

Cartesian components will

also be useful

$$\hat{\theta} = \cos\phi \hat{x} + \sin\phi \hat{y} - \sin\theta \hat{z}$$

$$\hat{\phi} = -\sin\phi \hat{x} + \cos\phi \hat{y}$$



So,

$$\vec{L} = \frac{\hbar}{i} [(-\sin\phi \hat{x} + \cos\phi \hat{y}) \frac{\partial}{\partial \theta} - (\cos\phi \hat{x} + \sin\phi \hat{y} - \sin\theta \hat{z}) \frac{\partial}{\partial \phi}]$$

$$L_{\pm} = L_x \pm iL_y$$

$$= \frac{\hbar}{i} [(-\sin\phi \pm i\cos\phi) \frac{\partial}{\partial \theta} - (\cos\phi \pm i\sin\phi) \cot\theta \frac{\partial}{\partial \phi}]$$

$$= \pm \hbar e^{\pm i\phi} \left(\frac{\partial}{\partial \theta} \pm i \cot\theta \frac{\partial}{\partial \phi} \right)$$

From which

$$L_+ L_- = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot\theta \frac{\partial}{\partial \theta} + \cot^2\theta \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial \phi^2} \right)$$

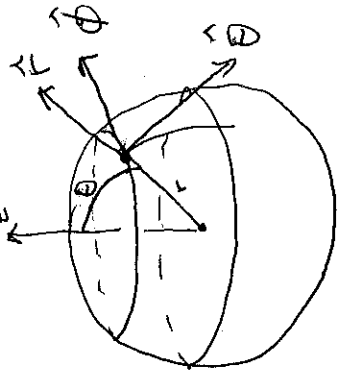
and

$$L_- L_+ = -\hbar^2 \left[\frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial \phi^2} + \left(\frac{\partial}{\partial \theta} \right) \cot\theta \left(\frac{\partial}{\partial \theta} \right) + \frac{\partial^2}{\partial \phi^2} \right]$$

Now, $\vec{r} = r \hat{r}$, so

$$\vec{L} = \frac{\hbar}{i} \left[r (\hat{x} \hat{r}) \frac{\partial}{\partial r} + (\hat{r} \times \hat{r}) \frac{\partial}{\partial \theta} + \frac{(\hat{r} \times \hat{\phi})}{\sin\theta} \frac{\partial}{\partial \phi} \right]$$

$$= \frac{\hbar}{i} \left[\hat{\phi} \frac{\partial}{\partial \theta} - \hat{\theta} \frac{\partial}{\partial \phi} \right]$$



Then

$$L_z = \frac{\hbar}{i} \theta \frac{\partial}{\partial \theta}$$

while

$$L_x = \frac{\hbar}{i} \left(-\sin\phi \frac{\partial}{\partial \theta} - \cot\theta \cos\phi \frac{\partial}{\partial \phi} \right)$$

$$L_y = \frac{\hbar}{i} \left(\cos\phi \frac{\partial}{\partial \theta} - \cot\theta \sin\phi \frac{\partial}{\partial \phi} \right)$$

The raising and lowering operators are slightly simpler

Now, $L^2 f_a^m = k^2 l(l+1) f_a^m$
 Dividing by Θ and multiplying by $\frac{1}{\sin^2 \theta}$ gives

$$\frac{1}{\sin^2 \theta} \left[\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) \right] + \frac{1}{\sin^2 \theta} \frac{d^2 \Phi}{d\phi^2} = -l(l+1) \frac{\Theta}{\sin^2 \theta}$$

or

$$\left\{ \frac{1}{\sin^2 \theta} \left[\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) \right] + l(l+1) \frac{\Theta}{\sin^2 \theta} \right\} + \frac{1}{\sin^2 \theta} \frac{d^2 \Phi}{d\phi^2} = 0$$

But then $\left\{ \dots \right\}$ and $\frac{1}{\sin^2 \theta} \frac{d^2 \Phi}{d\phi^2}$ must each equal a constant

Eg. (2) is more complicated

$$\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left[l(l+1) \sin^2 \theta - m^2 \right] \Theta = 0$$

and has solution

$$\Theta(\theta) = A P_l^m(\cos \theta)$$

where P_l^m is the "associated Legendre function"

$$P_l^m(x) = (1-x^2)^{|m|/2} P_l(x)$$

where $f_a^m = f_a^m(\theta, \phi)$. Let's suppose (separation of variables)

$$f_a^m(\theta, \phi) = \Theta(\theta) \Phi(\phi)$$

to find

$$-k^2 \left[\frac{1}{\sin^2 \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \frac{1}{\sin^2 \theta} \frac{d^2 \Phi}{d\phi^2} \right] = k^2 l(l+1) \Theta \Phi$$

and $\frac{1}{\sin^2 \theta} \frac{d^2 \Phi}{d\phi^2} = -m^2$ call it (1)

$$\left\{ \dots \right\} = m^2 \quad (2)$$

The first is easy to solve

$$\Phi(\phi) = e^{im\phi}$$

The "boundary" condition $\Phi(\phi + 2\pi) = \Phi(\phi)$

yields $e^{im(\phi + 2\pi)} = e^{im\phi} \Rightarrow e^{im2\pi} = 1 \Rightarrow m = 0, \pm 1, \pm 2, \dots$

and $P_\ell(x)$ is the ℓ^{th} Legendre Polynomial,
and is defined by

$$P_\ell(x) = \frac{1}{2^\ell \ell!} \left(\frac{d}{dx} \right)^\ell (x^2 - 1)^\ell$$

This is called the Rodrigues formula.