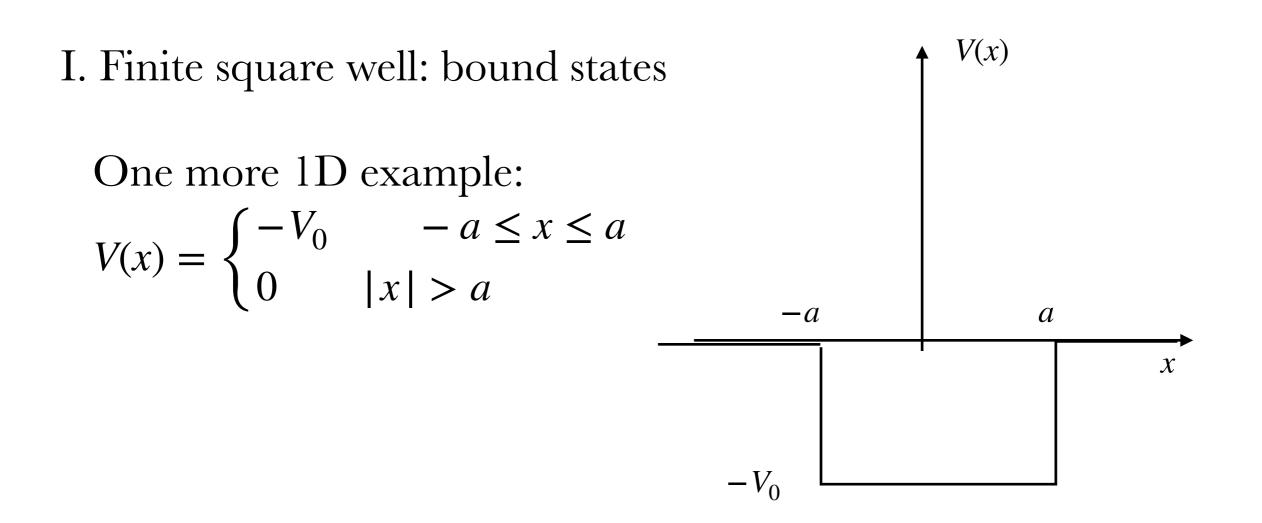
## <u>Today</u>

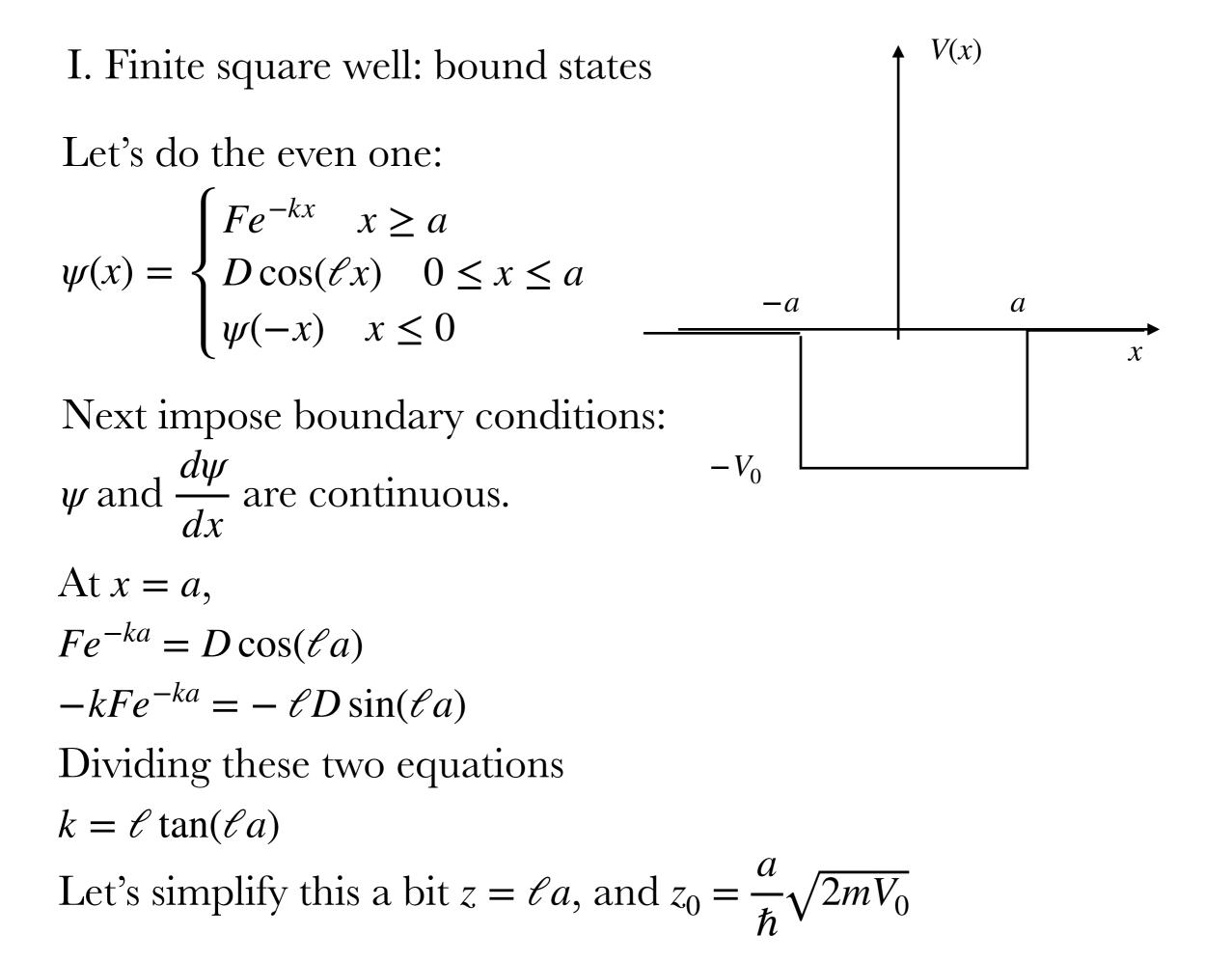
- I. Last Time
- II. Two-Dimensional Quantum Theory
- III. 2D Infinite Square Well
- IV. The Circular Billiard and Angular Momentum
- I. Last time
- \* Worked out the even solutions for the bound states of the finite square well.
- \* To find the energies we had to solve a transcendental equation, which we did numerically, by plotting.

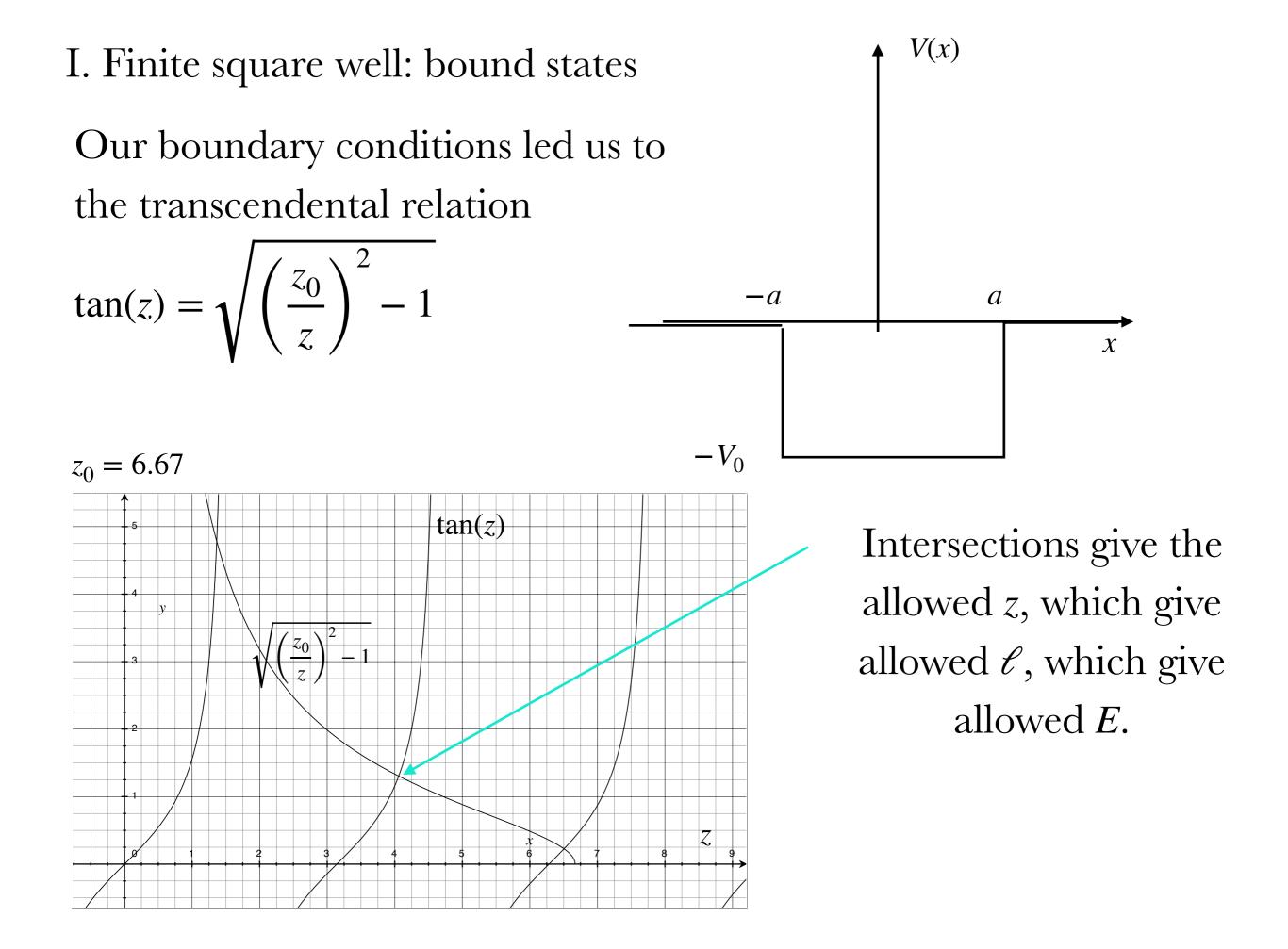


But, since the potential is even, we can look for even or odd solutions —a general solution is built out of these as a superposition.

Let's do the even one:

$$\psi(x) = \begin{cases} Fe^{-kx} & x > a \\ D\cos(\ell x) & 0 < x < a \\ \psi(-x) & x < 0 \end{cases}$$



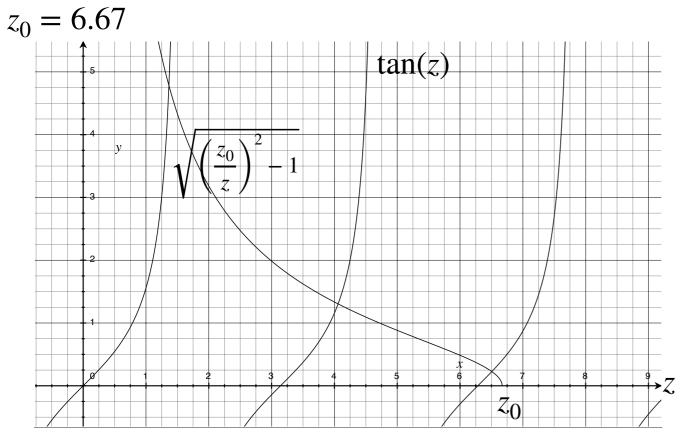


Limiting cases: For a wide, deep well this should be related to the infinite square well.

$$z_{int} \approx z_n = \frac{n\pi}{2}$$

then, the allowed energies are:

$$z_n = \ell_n a = \frac{a\sqrt{2m(E_n + V_0)}}{\hbar} = \frac{n\pi}{2}$$



Or

 $-V_0$ 

-a

$$E_n + V_0 = \frac{n^2 \pi^2 \hbar^2}{2m(2a)^2}$$

These are the square well solutions above  $V_0$ , but only works for finitely many n.

V(x)

a

X

In the narrow, shallow limit there's only one solution, but it's there!

## II. 2D Quantum Theory

We've been generating more and more examples of quantum systems by changing the shape of the potential. There's another way to do it. That is, we can change the dimensions of space. Let's consider 2D.

What becomes of the Schroedinger equation? We just add an argument to  $\Psi$ , that is

 $\Psi(x,t) \to \Psi(x,y,t)$ 

[ (important) Aside on notation: We're lazy and write 2D:  $\Psi(x, y, t) = \Psi(\vec{r}, t)$ 

2D: 
$$\vec{r} = (x, y)$$

3D:  $\vec{r} = (x, y, z)$ 

Notice that this notation, while odd, is consistent:

2D: 
$$r = |\vec{r}| = \sqrt{x^2 + y^2}$$
 (polar radius)  
3D:  $r = |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$  (spherical radius)

II. 2D Quantum Theory We just add an argument to  $\Psi$ , that is  $\Psi(x,t) \rightarrow \Psi(x,y,t)$ [ (important) Aside on notation: We're lazy and write 2D:  $\Psi(x,y,t) = \Psi(\vec{r},t)$ 2D:  $\vec{r} = (x,y)$ 

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But, of course,  $r \neq \vec{r}$ . For integration it's convenient to intro:

2D: 
$$d^{2}\vec{r} = dxdy$$
  
 $\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}\right)$   
3D:  $d^{3}\vec{r} = dxdydz = r^{2}\sin\theta drd\theta d\phi$   
 $\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$ 

Schroedinger equation:

$$i\hbar\frac{\partial\Psi}{\partial t} = \hat{H}\Psi = -\frac{\hbar^2}{2m}\left(\frac{\partial^2\Psi}{\partial x^2} + \frac{\partial^2\Psi}{\partial y^2}\right) + V(x,y)\Psi = -\frac{\hbar^2}{2m}\nabla^2\Psi + V\Psi$$

What kind of differential equation is this? 2nd order, partial differential equation. (2nd order PDE.) We solve PDEs by separation of variables. Let's do it in stages, let's separate t first. We'll get a time-indep Sch.  $-\frac{\hbar^2}{2m} \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) + V\psi = E\psi, \text{ where } \psi = \psi(x, y). \text{ There's also a wiggle}$ 

factor:  $\varphi(t) = e^{-iEt/\hbar}$ . Let's separate the final variables, x and y:  $\psi(x, y) = X(x)Y(y)$  separation ansatz

$$-\frac{\hbar^2}{2m}\left(Y(y)\frac{d^2X}{\partial x^2} + X(x)\frac{\partial^2 Y}{\partial y^2}\right) + V\psi = EXY$$

Let's separate the final variables, x and y:  $\psi(x, y) = X(x)Y(y) \text{ separation ansatz}$   $-\frac{\hbar^2}{2m} \left( Y(y)\frac{d^2X}{dx^2} + X(x)\frac{d^2Y}{dy^2} \right) + VXY = EXY$ 

Dividing through by XY gives

$$-\frac{\hbar^2}{2m} \left( \frac{1}{X} \frac{d^2 X}{dx^2} + \frac{1}{Y} \frac{d^2 Y}{dy^2} \right) + V_x(x) + V_y(y) = E$$

This leads us to two separated equations  $-\frac{\hbar^2}{2m} \frac{1}{X} \frac{d^2 X}{dx^2} + V_x(x) = \text{const.} = E_x$   $-\frac{\hbar^2}{2m} \frac{1}{Y} \frac{d^2 Y}{dy^2} + V_y(y) = \text{const.} = E_y$ 

And  $E_x + E_y = E$ . These are just two copies of the 1D Sch. Eq. Then the full solutions is  $\psi(x, y) = X(x)Y(y)$ .