<u>Today</u>

I. Last Time

II. Algebraic Theory of Angular Momentum ContinuedIII. Angular Momentum Eigenvalues

- I. Last time
- * Intro'd all three angular momentum operators
- * Found $[L_x, L_y] = i\hbar L_z$
- * This means that we cannot simultaneously measure L_x and L_y .
- * [A, BC] = B[A, C] + [A, B]C
- * Notation: I've begun to drop hats everywhere.

I. Algebraic Theory of Angular Momentum

First classically:
$$\vec{L} = \vec{r} \times \vec{p} = \det \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x & y & z \\ p_x & p_y & p_z \end{vmatrix}$$
, let's focus on 3D

today: $L_x = yp_z - zp_y$, $L_y = zp_x - xp_z$, $L_z = xp_y - yp_x$.

To go from the classical to the quantum theory, we introduce hats

$$L_x \longrightarrow \hat{L}_x \equiv \hat{y}\hat{p}_z - \hat{z}\hat{p}_y = \frac{\hbar}{i}\left(y\frac{\partial}{\partial z} - z\frac{\partial}{\partial y}\right)$$

 $L_y \longrightarrow \hat{L}_y \equiv \hat{z}\hat{p}_x - \hat{x}\hat{p}_z = \frac{\hbar}{i}\left(z\frac{\partial}{\partial x} - x\frac{\partial}{\partial z}\right)$
 $L_z \longrightarrow \hat{L}_z \equiv \hat{x}\hat{p}_y - \hat{y}\hat{p}_x = \frac{\hbar}{i}\left(x\frac{\partial}{\partial y} - y\frac{\partial}{\partial x}\right).$

For the rest of today, I'll drop hats. You'll remember they're operators.

$$L_{x} \longrightarrow \hat{L}_{x} \equiv \hat{y}\hat{p}_{z} - \hat{z}\hat{p}_{y} = \frac{\hbar}{i}\left(y\frac{\partial}{\partial z} - z\frac{\partial}{\partial y}\right)$$
$$L_{y} \longrightarrow \hat{L}_{y} \equiv \hat{z}\hat{p}_{x} - \hat{x}\hat{p}_{z} = \frac{\hbar}{i}\left(z\frac{\partial}{\partial x} - x\frac{\partial}{\partial z}\right)$$
$$L_{z} \longrightarrow \hat{L}_{z} \equiv \hat{x}\hat{p}_{y} - \hat{y}\hat{p}_{x} = \frac{\hbar}{i}\left(x\frac{\partial}{\partial y} - y\frac{\partial}{\partial x}\right).$$

Do these operators commute? [A, B + C] = [A, B] + [A, C] [A, BC] = [A, B]C + B[A, C] $[L_x, L_y] = [yp_z - zp_y, zp_x - xp_z] = [yp_z, zp_x - xp_z] - [zp_y, zp_x - xp_z]$ $= [yp_{z}, zp_{x}] - [yp_{z}, xp_{z}] - [zp_{y}, zp_{x}] + [zp_{y}, xp_{z}]$ $= y[p_{z}, zp_{x}] + x[z, p_{z}]p_{y}$ $= y[p_{z}, z]p_{x} + yz[p_{z}, p_{x}] + x[z, p_{z}]p_{y}$ $= y[p_{z}, z]p_{x} + x[z, p_{z}]p_{y} = -y[z, p_{z}]p_{x} + x[z, p_{z}]p_{y} = i\hbar(-yp_{x} + xp_{y})$ $=i\hbar L_{\tau}$

Conclusion(!): $[L_x, L_y] = i\hbar L_z$, $[L_y, L_z] = i\hbar L_x$ and cyclic permutations.

II. Conclusion(!): $[L_x, L_y] = i\hbar L_z$, $[L_y, L_z] = i\hbar L_x$ and cyclic permutations. If two operators don't commute, then there's always an uncertainty relation for them:

$$\sigma_A^2 \sigma_B^2 \ge \left(\frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2.$$

Let's apply this to the case of angular momentum:

$$\sigma_{L_x}\sigma_{L_y} \geq \left| \left(\frac{1}{2i} \langle i\hbar L_z \rangle \right) \right| = \frac{\hbar}{2} |\langle L_z \rangle|.$$

There's a way out of this complicated situation (really only a partial way out). We want to try and find some quantity that does commute with the components of \vec{L} . The idea is to turn to the magnitude of \vec{L} , $L^2 = \vec{L} \cdot \vec{L} = L_x^2 + L_y^2 + L_z^2$. Let's compute $[L^2, L_z] = [L_x^2 + L_y^2 + L_z^2, L_z] = [L_x^2, L_z] + [L_y^2, L_z] + [L_z^2, L_z]$

$$[L^{2}, L_{z}] = [L_{x}^{2} + L_{y}^{2} + L_{z}^{2}, L_{z}] = [L_{x}^{2}, L_{z}] + [L_{y}^{2}, L_{z}] + [L_{z}^{2}, L_{z}]$$

$$= [L_{x}^{2}, L_{z}] + [L_{y}^{2}, L_{z}]$$

$$= L_{x}[L_{x}, L_{z}] + [L_{x}, L_{z}]L_{x} + L_{y}[L_{y}, L_{z}] + [L_{y}, L_{z}]L_{y}$$

$$= -i\hbar L_{x}L_{y} - i\hbar L_{y}L_{x} + L_{y}(i\hbar L_{x}) + i\hbar L_{x}L_{y}$$

$$= 0.\checkmark$$

Then, because none of the directions is special, we expect $[L^2, \vec{L}] = 0!$

So, L_z and L^2 are compatible observables. Let's find their eigenvalues.

III. Let's call the eigenvalues μ and λ respectively. More concretely $L_z f = \mu f$ and $L^2 f = \lambda f$. (1)

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$$L_z f = \mu f$$
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We'll try to copy what we did for the oscillator:

$$L_{\pm} \equiv L_x \pm iL_y.$$

Then,

$$[L_z, L_{\pm}] = [L_z, L_x] \pm i[L_z, L_y]$$
$$= i\hbar L_y \pm i(-i\hbar L_x)$$

So,

$$[L_z, L_{\pm}] = \pm \hbar (L_x \pm i L_y) = \pm \hbar L_{\pm}.$$
$$[L^2, L_{\pm}] = 0.$$

<u>Claim</u>: If *f* satisfies Eq. (1), then so does $L_{\pm}f$, except with $L_z(L_{\pm}f) = (\mu \pm \hbar)(L_{\pm}f)$. <u>Pf</u>: $L^2(L_{\pm}f) = L_{\pm}(L^2f) = L_{\pm}(\lambda f) = \lambda(L_{\pm}f)$. \checkmark $L_z(L_{\pm}f) = (L_zL_{\pm} - L_{\pm}L_z)f + L_{\pm}L_zf = \pm \hbar L_{\pm}f + \mu L_{\pm}f = (\mu \pm \hbar)L_{\pm}$. \checkmark