

General Relativity

Todays

Mar 14th, 2016 PV3

I last time

Day 19

II Deriving the geodesic equations

III Example: Plane in polar coords

I Learned that we can drop the square root in the calculus of variations, provided we choose the proper parameters.

- Showed that the lagrangian for a general timelike geodesic is

$$L = -g_{\alpha\beta}(x)\dot{x}^\alpha\dot{x}^\beta, \quad \dot{x}^\alpha = \frac{dx^\alpha}{d\tau}.$$

in terms of the kronecker δ :

$$\delta^\alpha_\beta = \begin{cases} 1 & \text{if } \alpha = \beta \\ 0 & \text{if } \alpha \neq \beta. \end{cases}$$

This is reasonable since,

$$\frac{\partial x^1}{\partial x^1} = 1 \quad \text{and} \quad \frac{\partial x^0}{\partial x^1} = \frac{\partial x^1}{\partial x^0} = 0.$$

Taking these derivatives

$$-\frac{\partial g_{\alpha\beta}\dot{x}^\alpha}{\partial x^s} - \frac{1}{2}\frac{\partial}{\partial x^s}\left(-g_{\alpha\beta}S^P_\alpha\dot{x}^\beta - g_{\alpha\beta}\dot{x}^\alpha S^P_\beta\right) = 0 \quad \text{Kronecker } \delta's \text{ are particularly nice in sums, where they simply replace one index by another}$$

where we have expressed the derivative

$$\frac{\partial \dot{x}^\alpha}{\partial x^s} = S^{\alpha}_s$$

eg. $\sum \dot{x}^\alpha S_\alpha = \dot{x}^\alpha S_\alpha = \dot{x}^\beta$ prove it!

Returning to our EL equations:

$$\frac{\partial}{\partial t} \left(g_{\alpha\beta} x^\alpha x^\beta + g_{\alpha\beta} x^\alpha x^\beta \right) - \frac{\partial x^\alpha}{\partial e} g_{\alpha\beta} x^\beta = 0$$

Next we evaluate the τ -derivative, using the chain rule on $g_{\alpha\beta}(x)$,

$$\begin{aligned} & \frac{\partial}{\partial x^\alpha} \left(g_{\alpha\beta} x^\alpha x^\beta + g_{\alpha\beta} x^\alpha x^\beta \right) - \frac{\partial x^\alpha}{\partial e} g_{\alpha\beta} x^\beta \\ &= g_{\alpha\beta} x^\alpha + g_{\alpha\beta} x^\alpha + g_{\alpha\beta} x^\alpha - \frac{\partial x^\alpha}{\partial e} g_{\alpha\beta} x^\beta \end{aligned}$$

divide by 2 we get

$$g_{\alpha\beta} x^\alpha + \frac{1}{2} g_{\alpha\beta} x^\alpha - \frac{\partial x^\alpha}{\partial e} g_{\alpha\beta} x^\beta = 0$$

Finally, introduce $y^\alpha = x^\alpha$ (think of the metric inverse).

Then call this Γ^α_β "christoffel symbols", i.e. $\Gamma^\alpha_\beta = g^{\alpha\gamma} \frac{\partial g_{\gamma\beta}}{\partial x^\epsilon} + \frac{1}{2} g^{\alpha\gamma} \left(\frac{\partial g_{\gamma\beta}}{\partial x^\epsilon} - \frac{\partial g_{\beta\gamma}}{\partial x^\epsilon} \right)$

Let us return to our example of the plane in polar coords: we can

$$\frac{\partial}{\partial r} \left(\frac{x e}{g_{rr}} - \frac{x e}{g_{\theta\theta}} \right) + \frac{\partial}{\partial \theta} \left(\frac{x e}{g_{rr}} + \frac{x e}{g_{\theta\theta}} \right) = 0$$

where we have exploited our $\tau^{2/3}$ freedom to name a dummy index anything we want. The last term of the 2nd line are equal due to the symmetry of the metric and the dummy index renaming freedom. To use collect all the x^α terms and

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or

$$\ddot{x}^\alpha + \Gamma^\alpha_\beta \dot{x}^\beta \dot{x}^\alpha = 0.$$

Recall, $\dot{x}^\alpha = \frac{dx^\alpha}{d\tau} = u^\alpha$, so it is also nice to write

$$\frac{du^\alpha}{d\tau} + \Gamma^\alpha_\beta u^\beta u^\alpha = 0 \quad \text{Geodesic Eq}$$

Let us return to our timelike geodesics

Read off the components of the Christoffel symbols from the eqns of motion. First let's recall some analogies

Timeline

τ

$$u^r = \frac{dx^r}{ds}, \quad A=1,2$$

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$$u^r \cdot u^r = -1 \quad \rightarrow \quad \tilde{u} \cdot \tilde{u} = 1 \quad \leftarrow$$

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Because of spacetime \tilde{u} .

Spacelike

S arc length

$$u^A = \frac{dx^A}{ds}, \quad A=1,2$$

$$u^A \cdot u^B = -1 \quad \rightarrow \quad \tilde{u} \cdot \tilde{u} = 1 \quad \leftarrow$$

Because of spacetime \tilde{u} .

The general geodesic eqn $\frac{d^2x^\alpha}{ds^2} + \Gamma_{\beta\gamma}^\alpha \frac{dx^\beta}{ds} \frac{dx^\gamma}{ds} = 0$,

is, after these analogies,

$$\frac{d^2x^\alpha}{ds^2} + \Gamma_{\beta\gamma}^\alpha \frac{dx^\beta}{ds} \frac{dx^\gamma}{ds} = 0.$$

Compare this to our previous results

$$0 = \frac{d^2\phi}{ds^2} - r \cdot \text{eg. } \frac{d^2r}{ds^2} - r \frac{d\phi}{ds} \frac{d\phi}{ds} = 0$$

$$0 = \frac{d^2\phi}{ds^2} + \frac{1}{r} \frac{dr}{ds} \frac{d\phi}{ds} + \frac{1}{r} \frac{d\phi}{ds} \frac{d\phi}{ds} = 0$$

By looking at the appropriate $x^* = (x^1, x^2) = (r, \phi)$ we can read off the Christoffel symbols through this comparison:

$$\Gamma^r_{\phi\phi} = -r$$

$$g_{AB} = \begin{pmatrix} 1 & 0 \\ 0 & r^2 \end{pmatrix}, \quad (A, B=1, 2)$$

First the inverse metric is

$$g^{AB} = \begin{pmatrix} 1 & 0 \\ 0 & r^{-2} \end{pmatrix}, \quad \text{while } \Gamma^r_{rr} = \Gamma^r_{\phi\phi} = \Gamma^r_{\phi r} = 0.$$

$$\text{then } \Gamma^r_{\phi\phi} = \frac{1}{2} g^{AB} \left(\frac{\partial g_{AB}}{\partial r} - \frac{\partial g_{AB}}{\partial \phi} + \frac{\partial g_{AB}}{\partial \phi} - \frac{\partial g_{AB}}{\partial r} \right) = \frac{1}{2} g^{AB} \left(\frac{\partial g_{AB}}{\partial r} - \frac{\partial g_{AB}}{\partial \phi} \right) = -r$$

Compare how efficient this is to doing calculations using the direct computation using