#### MATH 2270: Written Assignment 5 Due: Wednesday, November 14, 2018

Show all appropriate work.

- 1. Problems from the book: (Again, a scan of the problems are attached to the end of this pdf.)
  - (a) Section 3.2: 18, 28, 31.
  - (b) Section 3.3: 2, 10, 12, 19.
  - (c) Section 3.4: 1, 6, 10, 11, 16, 24.
  - (d) Section 3.6: 1, 3, 9, 11, 23, 24.
- 2. Write MATLAB code that solves  $A\mathbf{x} = \mathbf{b}$ , for A an  $n \times n$  invertible matrix using the LU factorization with forward and backward substitution.

**3.2 B** Find the special solutions and describe the *complete solution* to Ax = 0 for

$$A_1 = \left[ \begin{array}{cccc} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \qquad A_2 = \left[ \begin{array}{ccc} 3 & 6 \\ 1 & 2 \end{array} \right] \qquad A_3 = \left[ \begin{array}{cccc} A_2 & A_2 \end{array} \right]$$

Which are the pivot columns? Which are the free variables? What is R in each case?

**Solution**  $A_1x = \mathbf{0}$  has four special solutions. They are the columns  $s_1, s_2, s_3, s_4$  of the 4 by 4 identity matrix. The nullspace is all of  $\mathbf{R}^4$ . The complete solution to  $A_1x = \mathbf{0}$  is any  $x = c_1s_1 + c_2s_2 + c_3s_3 + c_4s_4$  in  $\mathbf{R}^4$ . There are no pivot columns; all variables are free; the reduced R is the same zero matrix as  $A_1$ .

 $A_2x = 0$  has only one special solution s = (-2, 1). The multiples x = cs give the complete solution. The first column of  $A_2$  is its pivot column, and  $x_2$  is the free variable. The row reduced matrices  $R_2$  for  $A_2$  and  $R_3$  for  $A_3 = \begin{bmatrix} A_2 & A_2 \end{bmatrix}$  have 1's in the pivot:

$$A_2 = \begin{bmatrix} 3 & 6 \\ 1 & 2 \end{bmatrix} \to R_2 = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \qquad \begin{bmatrix} A_2 & A_2 \end{bmatrix} \to R_3 = \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Notice that  $R_3$  has only one pivot column (the first column). All the variables  $x_2, x_3, x_4$  are free. There are three special solutions to  $A_3 x = 0$  (and also  $R_3 x = 0$ ):

$$s_1 = (-2, 1, 0, 0)$$
  $s_2 = (-1, 0, 1, 0)$   $s_3 = (-2, 0, 0, 1)$  Complete  $x = c_1 s_1 + c_2 s_2 + c_3 s_3$ .

With r pivots, A has n-r free variables. Ax = 0 has n-r special solutions.

#### Problem Set 3.2

Questions 1-4 and 5-8 are about the matrices in Problems 1 and 5.

1 Reduce these matrices to their ordinary echelon forms U:

(a) 
$$A = \begin{bmatrix} 1 & 2 & 2 & 4 & 6 \\ 1 & 2 & 3 & 6 & 9 \\ 0 & 0 & 1 & 2 & 3 \end{bmatrix}$$
 (b)  $B = \begin{bmatrix} 2 & 4 & 2 \\ 0 & 4 & 4 \\ 0 & 8 & 8 \end{bmatrix}$ .

Which are the free variables and which are the pivot variables?

- 2 For the matrices in Problem 1, find a special solution for each free variable. (Set the free variable to 1. Set the other free variables to zero.)
- By combining the special solutions in Problem 2, describe every solution to Ax = 0 and Bx = 0. The nullspace contains only x = 0 when there are no \_\_\_\_\_.
- By further row operations on each U in Problem 1, find the reduced echelon form R. True or false: The nullspace of R equals the nullspace of U.
- By row operations reduce each matrix to its echelon form U. Write down a 2 by 2 lower triangular L such that B = LU.

(b) 
$$B = \begin{bmatrix} -1 & 3 & 5 \\ -2 & 6 & 7 \end{bmatrix}$$

- For the same A and B, find the special solutions to Ax = 0 and Bx = 0. For an m by 6 n matrix, the number of pivot variables plus the number of free variables is  $_{\perp}$
- In Problem 5, describe the nullspaces of A and B in two ways. Give the equations 7 for the plane or the line, and give all vectors x that satisfy those equations as combinations of the special solutions.
- Reduce the echelon forms U in Problem 5 to R. For each R draw a box around the 8 identity matrix that is in the pivot rows and pivot columns.

## Ouestions 9-17 are about free variables and pivot variables.

- True or false (with reason if true or example to show it is false): 9
  - (a) A square matrix has no free variables.
  - (b) An invertible matrix has no free variables.
  - (c) An m by n matrix has no more than n pivot variables.
  - (d) An m by n matrix has no more than m pivot variables.
- Construct 3 by 3 matrices A to satisfy these requirements (if possible): 10
  - (a) A has no zero entries but U = I.
  - (b) A has no zero entries but R = I.
  - (c) A has no zero entries but R = U.
  - (d) A = U = 2R.
- Put as many 1's as possible in a 4 by 7 echelon matrix U whose pivot columns are
  - (a) 2, 4, 5
  - (b) 1, 3, 6, 7
  - (c) 4 and 6.
- Put as many 1's as possible in a 4 by 8 reduced echelon matrix R so that the free 12 columns are
  - (a) 2, 4, 5, 6
  - (b) 1, 3, 6, 7, 8.
- Suppose column 4 of a 3 by 5 matrix is all zero. Then  $x_4$  is certainly a \_\_\_\_\_ 13 variable. The special solution for this variable is the vector  $x = \underline{\hspace{1cm}}$ .
- Suppose the first and last columns of a 3 by 5 matrix are the same (not zero). Then 14 is a free variable. Find the special solution for this variable.

- Suppose an m by n matrix has r pivots. The number of special solutions is \_\_\_\_\_. The nullspace contains only x = 0 when r =\_\_\_\_\_. The column space is all of  $\mathbf{R}^m$  when r =\_\_\_\_\_.
- The nullspace of a 5 by 5 matrix contains only x = 0 when the matrix has \_\_\_\_\_ pivots. The column space is  $\mathbb{R}^5$  when there are \_\_\_\_\_ pivots. Explain why.
- The equation x 3y z = 0 determines a plane in  $\mathbb{R}^3$ . What is the matrix A in this equation? Which are the free variables? The special solutions are (3, 1, 0) and
- (Recommended) The plane x 3y z = 12 is parallel to the plane x 3y z = 0 in Problem 17. One particular point on this plane is (12, 0, 0). All points on the plane have the form (fill in the first components)

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

19 Prove that U and A = LU have the same nullspace when L is invertible:

If Ux = 0 then LUx = 0. If LUx = 0, how do you know Ux = 0?

Suppose column 1 + column 3 + column 5 = 0 in a 4 by 5 matrix with four pivots. Which column is sure to have no pivot (and which variable is free)? What is the special solution? What is the nullspace?

Questions 21–28 ask for matrices (if possible) with specific properties.

- Construct a matrix whose nullspace consists of all combinations of (2, 2, 1, 0) and (3, 1, 0, 1).
- 22 Construct a matrix whose nullspace consists of all multiples of (4, 3, 2, 1).
- Construct a matrix whose column space contains (1, 1, 5) and (0, 3, 1) and whose nullspace contains (1, 1, 2).
- Construct a matrix whose column space contains (1, 1, 0) and (0, 1, 1) and whose nullspace contains (1, 0, 1) and (0, 0, 1).
- Construct a matrix whose column space contains (1, 1, 1) and whose nullspace is the line of multiples of (1, 1, 1, 1).
- 26 Construct a 2 by 2 matrix whose nullspace equals its column space. This is possible.
- 27 Why does no 3 by 3 matrix have a nullspace that equals its column space?
- 28 If AB = 0 then the column space of B is contained in the \_\_\_\_\_ of A. Give an example of A and B.

The reduced form R of a 3 by 3 matrix with randomly chosen entries is almost sure to be \_\_\_\_\_. What R is virtually certain if the random A is 4 by 3?

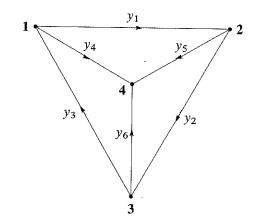
- 30 Show by example that these three statements are generally false:
  - (a) A and  $A^{T}$  have the same nullspace.
  - (b) A and  $A^{T}$  have the same free variables.
  - (c) If R is the reduced form  $\mathbf{rref}(A)$  then  $R^T$  is  $\mathbf{rref}(A^T)$ .
- If the nullspace of A consists of all multiples of x = (2, 1, 0, 1), how many pivots appear in U? What is R?
- 32 If the special solutions to Rx = 0 are in the columns of these N, go backward to find the nonzero rows of the reduced matrices R:

$$N = \begin{bmatrix} 2 & 3 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{and} \quad N = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{and} \quad N = \begin{bmatrix} \end{bmatrix} \text{ (empty 3 by 1)}.$$

- (a) What are the five 2 by 2 reduced echelon matrices R whose entries are all 0's and 1's?
  - (b) What are the eight 1 by 3 matrices containing only 0's and 1's? Are all eight of them reduced echelon matrices R?
- **34** Explain why A and -A always have the same reduced echelon form R.

## **Challenge Problems**

- If A is 4 by 4 and invertible, describe all vectors in the nullspace of the 4 by 8 matrix  $B = [A \ A]$ .
- How is the nullspace N(C) related to the spaces N(A) and N(B), if  $C = \begin{bmatrix} A \\ B \end{bmatrix}$ ?
- Kirchhoff's Law says that current in = current out at every node. This network has six currents  $y_1, \ldots, y_6$  (the arrows show the positive direction, each  $y_i$  could be positive or negative). Find the four equations Ay = 0 for Kirchhoff's Law at the four nodes. Find three special solutions in the nullspace of A.



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**3.3 C** Find the row reduced form R and the rank r of A and B (those depend on c). Which are the pivot columns of A? What are the special solutions and the matrix N?

Find special solutions  $A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 6 & 3 \\ 4 & 8 & c \end{bmatrix}$  and  $B = \begin{bmatrix} c & c \\ c & c \end{bmatrix}$ .

**Solution** The matrix A has rank r = 2 except if c = 4. The pivots are in columns 1 and 3. The second variable  $x_2$  is free. Notice the form of R:

$$c \neq 4 \quad R = \begin{bmatrix} \mathbf{1} & 2 & 0 \\ 0 & 0 & \mathbf{1} \\ 0 & 0 & 0 \end{bmatrix} \qquad c = 4 \quad R = \begin{bmatrix} \mathbf{1} & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Two pivots leave one free variable  $x_2$ . But when c=4, the only pivot is in column 1 (rank one). The second and third variables are free, producing two special solutions:

$$c \neq 4$$
 Special solution with  $x_2 = 1$  goes into  $N = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$ .

$$c=4$$
 Another special solution goes into  $N=\begin{bmatrix} -2 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$ .

The 2 by 2 matrix  $\begin{bmatrix} c & c \\ c & c \end{bmatrix}$  has rank r = 1 except if c = 0, when the rank is zero!

$$c \neq 0$$
  $R = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  and  $N = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$  Nullspace = line

The matrix has no pivot columns if c = 0. Then both variables are free:

$$c = 0$$
  $R = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$  and  $N = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  Nullspace  $= \mathbb{R}^2$ .

# Problem Set 3.3

- 1 Which of these rules gives a correct definition of the rank of A?
  - (a) The number of nonzero rows in R.
  - (b) The number of columns minus the total number of rows.
  - (c) The number of columns minus the number of free columns.
  - (d) The number of 1's in the matrix R.

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- 2 Find the reduced row echelon forms R and the rank of these matrices:
  - (a) The 3 by 4 matrix with all entries equal to 4.
  - (b) The 3 by 4 matrix with  $a_{ij} = i + j 1$ .
  - (c) The 3 by 4 matrix with  $a_{ij} = (-1)^j$ .
- 3 Find the reduced R for each of these (block) matrices:

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 3 \\ 2 & 4 & 6 \end{bmatrix} \quad B = \begin{bmatrix} A & A \end{bmatrix} \quad C = \begin{bmatrix} A & A \\ A & 0 \end{bmatrix}$$

Suppose all the pivot variables come *last* instead of first. Describe all four blocks in the reduced echelon form (the block B should be r by r):

$$R = \begin{bmatrix} A & B \\ C & D \end{bmatrix}.$$

What is the nullspace matrix N containing the special solutions?

- 5 (Silly problem) Describe all 2 by 3 matrices  $A_1$  and  $A_2$ , with row echelon forms  $R_1$  and  $R_2$ , such that  $R_1 + R_2$  is the row echelon form of  $A_1 + A_2$ . Is is true that  $R_1 = A_1$  and  $R_2 = A_2$  in this case? Does  $R_1 R_2$  equal  $\mathbf{rref}(A_1 A_2)$ ?
- If A has r pivot columns, how do you know that  $A^{T}$  has r pivot columns? Give a 3 by 3 example with different column numbers in pivcol for A and  $A^{T}$ .
- 7 What are the special solutions to Rx = 0 and  $y^T R = 0$  for these R?

$$R = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & 4 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \qquad R = \begin{bmatrix} 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Problems 8–11 are about matrices of rank r = 1.

8 Fill out these matrices so that they have rank 1:

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & & \\ 4 & & \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} & 9 & \\ 1 & & \\ 2 & 6 & -3 \end{bmatrix} \quad \text{and} \quad M = \begin{bmatrix} a & b \\ c & & \end{bmatrix}.$$

- If A is an m by n matrix with r = 1, its columns are multiples of one column and its rows are multiples of one row. The column space is a \_\_\_\_\_ in  $\mathbb{R}^m$ . The nullspace is a \_\_\_\_\_ in  $\mathbb{R}^n$ . The nullspace matrix N has shape \_\_\_\_\_.
- 10 Choose vectors  $\boldsymbol{u}$  and  $\boldsymbol{v}$  so that  $A = \boldsymbol{u}\boldsymbol{v}^{\mathrm{T}} = \text{column times row}$ :

$$A = \begin{bmatrix} 3 & 6 & 6 \\ 1 & 2 & 2 \\ 4 & 8 & 8 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 2 & 2 & 6 & 4 \\ -1 & -1 & -3 & -2 \end{bmatrix}.$$

 $A = uv^{T}$  is the natural form for every matrix that has rank r = 1.

11 If A is a rank one matrix, the second row of U is \_\_\_\_\_. Do an example.

- Suppose P contains only the r pivot columns of an m by n matrix. Explain why this m by r submatrix P has rank r.
- Transpose P in problem 13. Then find the r pivot columns of  $P^{T}$ . Transposing back, this produces an r by r invertible submatrix S inside P and A:

For 
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 4 & 7 \end{bmatrix}$$
 find  $P$  (3 by 2) and then the invertible  $S$  (2 by 2).

Problems 15–20 show that rank(AB) is not greater than rank(A) or rank(B).

15 Find the ranks of AB and AC (rank one matrix times rank one matrix):

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$
 and  $B = \begin{bmatrix} 2 & 1 & 4 \\ 3 & 1.5 & 6 \end{bmatrix}$  and  $C = \begin{bmatrix} 1 & b \\ c & bc \end{bmatrix}$ .

- The rank one matrix  $uv^T$  times the rank one matrix  $wz^T$  is  $uz^T$  times the number \_\_\_\_\_. This product  $uv^Twz^T$  also has rank one unless \_\_\_\_\_ = 0.
- 17 (a) Suppose column j of B is a combination of previous columns of B. Show that column j of AB is the same combination of previous columns of AB. Then AB cannot have new pivot columns, so  $\operatorname{rank}(AB) \leq \operatorname{rank}(B)$ .
  - (b) Find  $A_1$  and  $A_2$  so that  $rank(A_1B) = 1$  and  $rank(A_2B) = 0$  for  $B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ .
- Problem 17 proved that  $rank(AB) \le rank(B)$ . Then the same reasoning gives  $rank(B^TA^T) \le rank(A^T)$ . How do you deduce that  $rank(AB) \le rank(A^T)$ ?
- 19 (Important) Suppose A and B are n by n matrices, and AB = I. Prove from  $rank(AB) \le rank(A)$  that the rank of A is n. So A is invertible and B must be its two-sided inverse (Section 2.5). Therefore BA = I (which is not so obvious!).
- 20 If A is 2 by 3 and B is 3 by 2 and AB = I, show from its rank that  $BA \neq I$ . Give an example of A and B with AB = I. For m < n, a right inverse is not a left inverse.
- 21 Suppose A and B have the *same* reduced row echelon form R.
  - (a) Show that A and B have the same nullspace and the same row space.

**22** Express A and then B as the sum of two rank one matrices:

$$\mathbf{rank} = \mathbf{2} \qquad A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 4 \\ 1 & 1 & 8 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix}.$$

23 Answer the same questions as in Worked Example 3.3 C for

$$A = \begin{bmatrix} 1 & 1 & 2 & 2 \\ 2 & 2 & 4 & 4 \\ 1 & c & 2 & 2 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 - c & 2 \\ 0 & 2 - c \end{bmatrix}.$$

24 What is the nullspace matrix N (containing the special solutions) for A, B, C?

$$A = \begin{bmatrix} I & I \end{bmatrix}$$
 and  $B = \begin{bmatrix} I & I \\ 0 & 0 \end{bmatrix}$  and  $C = \begin{bmatrix} I & I \end{bmatrix}$ .

25 Neat fact Every m by n matrix of rank r reduces to (m by r) times (r by n):

$$A = (\text{pivot columns of } A) \text{ (first } r \text{ rows of } R) = (\text{COL})(\text{ROW}).$$

Write the 3 by 4 matrix A in equation (1) at the start of this section as the product of the 3 by 2 matrix from the pivot columns and the 2 by 4 matrix from R.

#### **Challenge Problems**

Suppose A is an m by n matrix of rank r. Its reduced echelon form is R. Describe exactly the matrix Z (its shape and all its entries) that comes from transposing the reduced row echelon form of R' (prime means transpose):

$$R = \operatorname{rref}(A)$$
 and  $Z = (\operatorname{rref}(R'))'$ .

27 Suppose R is m by n of rank r, with pivot columns first:

$$R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix}.$$

- (a) What are the shapes of those four blocks?
- (b) Find a right-inverse B with RB = I if r = m.
- (c) Find a left-inverse C with CR = I if r = n.
- (d) What is the reduced row echelon form of  $R^{T}$  (with shapes)?
- (e) What is the reduced row echelon form of  $R^{T}R$  (with shapes)?

Prove that  $R^TR$  has the same nullspace as R. Later we show that  $A^TA$  always has the same nullspace as A (a valuable fact).

Suppose you allow elementary *column* operations on A as well as elementary row operations (which get to R). What is the "row-and-column reduced form" for an m by n matrix of rank r?

## Problem Set 3.4

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(Recommended) Execute the six steps of Worked Example 3.4 A to describe the column space and nullspace of A and the complete solution to Ax = b:

$$A = \begin{bmatrix} 2 & 4 & 6 & 4 \\ 2 & 5 & 7 & 6 \\ 2 & 3 & 5 & 2 \end{bmatrix} \qquad b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \\ 5 \end{bmatrix}$$

Carry out the same six steps for this matrix A with rank one. You will find two conditions on  $b_1, b_2, b_3$  for Ax = b to be solvable. Together these two conditions put b into the \_\_\_\_\_ space (two planes give a line):

$$A = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \begin{bmatrix} 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 3 \\ 6 & 3 & 9 \\ 4 & 2 & 6 \end{bmatrix} \qquad b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 30 \\ 20 \end{bmatrix}$$

Questions 3–15 are about the solution of Ax = b. Follow the steps in the text to  $x_p$  and  $x_n$ . Use the augmented matrix with last column b.

Write the complete solution as  $x_p$  plus any multiple of s in the nullspace:

$$x + 3y + 3z = 1$$
  

$$2x + 6y + 9z = 5$$
  

$$-x - 3y + 3z = 5.$$

4 Find the complete solution (also called the general solution) to

$$\begin{bmatrix} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}.$$

Under what condition on  $b_1, b_2, b_3$  is this system solvable? Include **b** as a fourth column in elimination. Find all solutions when that condition holds:

$$x + 2y - 2z = b_1$$
$$2x + 5y - 4z = b_2$$
$$4x + 9y - 8z = b_3.$$

What conditions on  $b_1, b_2, b_3, b_4$  make each system solvable? Find x in that case:

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 2 & 5 \\ 3 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 5 & 7 \\ 3 & 9 & 12 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}.$$

7 Show by elimination that  $(b_1, b_2, b_3)$  is in the column space if  $b_3 - 2b_2 + 4b_1 = 0$ .

$$A = \begin{bmatrix} 1 & 3 & 1 \\ 3 & 8 & 2 \\ 2 & 4 & 0 \end{bmatrix}.$$

What combination of the rows of A gives the zero row?

Which vectors  $(b_1, b_2, b_3)$  are in the column space of A? Which combinations of the 8 rows of A give zero?

(a) 
$$A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 6 & 3 \\ 0 & 2 & 5 \end{bmatrix}$$
 (b)  $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$ .

(b) 
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$$

- (a) The Worked Example 3.4 A reached  $[U \ c]$  from  $[A \ b]$ . Put the multipliers 9 into L and verify that LU equals A and Lc equals b.
  - (b) Combine the pivot columns of A with the numbers -9 and 3 in the particular solution  $x_p$ . What is that linear combination and why?
- Construct a 2 by 3 system Ax = b with particular solution  $x_p = (2, 4, 0)$  and 10 homogeneous solution  $x_n$  = any multiple of (1, 1, 1).
- 11 Why can't a 1 by 3 system have  $x_p = (2, 4, 0)$  and  $x_n =$ any multiple of (1, 1, 1)?
- 12 (a) If Ax = b has two solutions  $x_1$  and  $x_2$ , find two solutions to Ax = 0.
  - (b) Then find another solution to Ax = 0 and another solution to Ax = b.
- 13 Explain why these are all false:
  - (a) The complete solution is any linear combination of  $x_p$  and  $x_n$ .
  - (b) A system Ax = b has at most one particular solution.
  - (c) The solution  $x_p$  with all free variables zero is the shortest solution (minimum length ||x||). Find a 2 by 2 counterexample.
  - (d) If A is invertible there is no solution  $x_n$  in the nullspace.
- Suppose column 5 of U has no pivot. Then  $x_5$  is a \_\_\_\_\_ variable. The zero vector 14 (is) (is not) the only solution to Ax = 0. If Ax = b has a solution, then it has \_\_\_\_\_ solutions.
- Suppose row 3 of U has no pivot. Then that row is \_\_\_\_\_. The equation Ux = c15 is only solvable provided \_\_\_\_\_. The equation Ax = b (is) (is not) (might not be) solvable.

Questions 16–20 are about matrices of "full rank" r = m or r = n.

The largest possible rank of a 3 by 5 matrix is \_\_\_\_\_. Then there is a pivot in every 16 of U and R. The solution to Ax = b (always exists) (is unique). The column space of A is \_\_\_\_\_. An example is A =\_\_\_\_\_.

- The largest possible rank of a 6 by 4 matrix is \_\_\_\_\_. Then there is a pivot in every \_\_\_\_\_ of U and R. The solution to Ax = b (always exists) (is unique). The nullspace of A is \_\_\_\_\_. An example is  $A = _____$ .
- 18 Find by elimination the rank of A and also the rank of  $A^{T}$ :

$$^{\circ}A = \begin{bmatrix} 1 & 4 & 0 \\ 2 & 11 & 5 \\ -1 & 2 & 10 \end{bmatrix}$$
 and  $A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 1 & 1 & q \end{bmatrix}$  (rank depends on  $q$ ).

19 Find the rank of A and also of  $A^{T}A$  and also of  $AA^{T}$ :

$$A = \begin{bmatrix} 1 & 1 & 5 \\ 1 & 0 & 1 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}.$$

**20** Reduce A to its echelon form U. Then find a triangular L so that A = LU.

$$A = \begin{bmatrix} 3 & 4 & 1 & 0 \\ 6 & 5 & 2 & 1 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 2 & 2 & 0 & 3 \\ 0 & 6 & 5 & 4 \end{bmatrix}.$$

21 Find the complete solution in the form  $x_p + x_n$  to these full rank systems:

(a) 
$$x + y + z = 4$$
 (b)  $x + y + z = 4$   $x - y + z = 4$ .

- 22 If Ax = b has infinitely many solutions, why is it impossible for Ax = B (new right side) to have only one solution? Could Ax = B have no solution?
- 23 Choose the number q so that (if possible) the ranks are (a) 1, (b) 2, (c) 3:

$$A = \begin{bmatrix} 6 & 4 & 2 \\ -3 & -2 & -1 \\ 9 & 6 & q \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 3 & 1 & 3 \\ q & 2 & q \end{bmatrix}.$$

- 24 Give examples of matrices A for which the number of solutions to Ax = b is
  - (a) 0 or 1, depending on  $\boldsymbol{b}$
  - (b)  $\infty$ , regardless of **b**
  - (c)  $0 \text{ or } \infty$ , depending on **b**
  - (d) 1, regardless of b.
- Write down all known relations between r and m and n if Ax = b has
  - (a) no solution for some b

- (b) infinitely many solutions for every b
- (c) exactly one solution for some b, no solution for other b
- (d) exactly one solution for every b.

Questions 26–33 are about Gauss-Jordan elimination (upwards as well as downwards) and the reduced echelon matrix  ${\it R}$ .

Continue elimination from U to R. Divide rows by pivots so the new pivots are all 1. Then produce zeros *above* those pivots to reach R:

$$U = \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad U = \begin{bmatrix} 2 & 4 & 4 \\ 0 & 3 & 6 \\ 0 & 0 & 5 \end{bmatrix}.$$

- 27 Suppose U is square with n pivots (an invertible matrix). Explain why R = I.
- Apply Gauss-Jordan elimination to Ux = 0 and Ux = c. Reach Rx = 0 and Rx = d:

$$\begin{bmatrix} U & \mathbf{0} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & \mathbf{0} \\ 0 & 0 & 4 & \mathbf{0} \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} U & \mathbf{c} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & \mathbf{5} \\ 0 & 0 & 4 & \mathbf{8} \end{bmatrix}.$$

Solve Rx = 0 to find  $x_n$  (its free variable is  $x_2 = 1$ ). Solve Rx = d to find  $x_p$  (its free variable is  $x_2 = 0$ ).

29 Apply Gauss-Jordan elimination to reduce to Rx = 0 and Rx = d:

$$\begin{bmatrix} U & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & \mathbf{0} \\ 0 & 0 & 2 & \mathbf{0} \\ 0 & 0 & 0 & \mathbf{0} \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} U & c \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & \mathbf{9} \\ 0 & 0 & 2 & \mathbf{4} \\ 0 & 0 & 0 & \mathbf{5} \end{bmatrix}.$$

Solve Ux = 0 or Rx = 0 to find  $x_n$  (free variable = 1). What are the solutions to Rx = d?

30 Reduce to Ux = c (Gaussian elimination) and then Rx = d (Gauss-Jordan):

$$Ax = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 1 & 3 & 2 & 0 \\ 2 & 0 & 4 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \\ 10 \end{bmatrix} = b.$$

Find a particular solution  $x_p$  and all homogeneous solutions  $x_n$ .

31 Find matrices A and B with the given property or explain why you can't:

(a) The only solution of 
$$Ax = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$
 is  $x = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

(b) The only solution of  $Bx = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  is  $x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ .

32 Find the LU factorization of A and the complete solution to Ax = b:

$$A = \begin{bmatrix} 1 & 3 & 1 \\ 1 & 2 & 3 \\ 2 & 4 & 6 \\ 1 & 1 & 5 \end{bmatrix} \quad \text{and} \quad b = \begin{bmatrix} 1 \\ 3 \\ 6 \\ 5 \end{bmatrix} \quad \text{and then} \quad b = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

33 The complete solution to  $Ax = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  is  $x = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . Find A.

#### **Challenge Problems**

- Suppose you know that the 3 by 4 matrix A has the vector  $\mathbf{s} = (2, 3, 1, 0)$  as the only special solution to  $A\mathbf{x} = \mathbf{0}$ .
  - (a) What is the rank of A and the complete solution to Ax = 0?
  - (b) What is the exact row reduced echelon form R of A?
  - (c) How do you know that Ax = b can be solved for all b?
- Suppose K is the 9 by 9 second difference matrix (2's on the diagonal, -1's on the diagonal above and also below). Solve the equation Kx = b = (10, ..., 10). If you graph  $x_1, ..., x_9$  above the points 1, ..., 9 on the x axis, I think the nine points fall on a parabola.
- Suppose Ax = b and Cx = b have the same (complete) solutions for every b. Is it true that A = C?

# ■ WORKED EXAMPLES

3.6 A Find bases and dimensions for all four fundamental subspaces if you know that

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 5 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 & 5 \\ 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix} = LU = E^{-1}R.$$

By changing only one number in R, change the dimensions of all four subspaces.

**Solution** This matrix has pivots in columns 1 and 3. Its rank is r = 2.

Row space Basis (1,3,0,5) and (0,0,1,6) from R. Dimension 2.

Column space Basis (1, 2, 5) and (0, 1, 0) from  $E^{-1}$  (and A). Dimension 2.

Nullspace Basis (-3, 1, 0, 0) and (-5, 0, -6, 1) from R. Dimension 2.

Nullspace of  $A^{T}$  Basis (-5, 0, 1) from row 3 of E. Dimension 3-2=1.

We need to comment on that left nullspace  $N(A^T)$ . EA = R says that the last row of E combines the three rows of A into the zero row of R. So that last row of E is a basis vector for the left nullspace. If R had *two* zero rows, then the last *two* rows of E would be a basis. (Just like elimination,  $y^TA = \mathbf{0}^T$  combines rows of E to give zero rows in E.)

To change all these dimensions we need to change the rank r. One way to do that is to change an entry (any entry) in the zero row of R.

**3.6 B** Put four 1's into a 5 by 6 matrix of zeros, keeping the dimension of its *row space* as small as possible. Describe all the ways to make the dimension of its *column space* as small as possible. Describe all the ways to make the dimension of its *nullspace* as small as possible. How to make the *sum of the dimensions of all four subspaces small*?

**Solution** The rank is 1 if the four 1's go into the same row, or into the same column. They can also go into *two rows and two columns* (so  $a_{ii} = a_{ij} = a_{ji} = a_{jj} = 1$ ). Since the column space and row space always have the same dimensions, this answers the first two questions: Dimension 1.

The nullspace has its smallest possible dimension 6-4=2 when the rank is r=4. To achieve rank 4, the 1's must go into four different rows and columns.

You can't do anything about the sum r + (n - r) + r + (m - r) = n + m. It will be 6 + 5 = 11 no matter how the 1's are placed. The sum is 11 even if there aren't any 1's...

If all the other entries of A are 2's instead of 0's, how do these answers change?

# Problem Set 3.6

1 (a) If a 7 by 9 matrix has rank 5, what are the dimensions of the four subspaces? What is the sum of all four dimensions?

- (b) If a 3 by 4 matrix has rank 3, what are its column space and left nullspace?
- **2** Find bases and dimensions for the four subspaces associated with A and B:

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 5 & 8 \end{bmatrix}.$$

3 Find a basis for each of the four subspaces associated with A:

$$A = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 4 & 6 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

- 4 Construct a matrix with the required property or explain why this is impossible:
  - (a) Column space contains  $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ , row space contains  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ 5 \end{bmatrix}$ .
  - (b) Column space has basis  $\begin{bmatrix} 1\\1\\3 \end{bmatrix}$ , nullspace has basis  $\begin{bmatrix} 3\\1\\1 \end{bmatrix}$ .
  - (c) Dimension of nullspace = 1 + dimension of left nullspace.
  - (d) Left nullspace contains  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ , row space contains  $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ .
  - (e) Row space = column space, nullspace  $\neq$  left nullspace.
- 5 If V is the subspace spanned by (1, 1, 1) and (2, 1, 0), find a matrix A that has V as its row space. Find a matrix B that has V as its nullspace.
- 6 Without elimination, find dimensions and bases for the four subspaces for

$$A = \begin{bmatrix} 0 & 3 & 3 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}.$$

- Suppose the 3 by 3 matrix A is invertible. Write down bases for the four subspaces for A, and also for the 3 by 6 matrix  $B = \begin{bmatrix} A & A \end{bmatrix}$ .
- What are the dimensions of the four subspaces for A, B, and C, if I is the 3 by 3 identity matrix and 0 is the 3 by 2 zero matrix?

$$A = \begin{bmatrix} I & 0 \end{bmatrix}$$
 and  $B = \begin{bmatrix} I & I \\ 0^T & 0^T \end{bmatrix}$  and  $C = \begin{bmatrix} 0 \end{bmatrix}$ .

- **9** Which subspaces are the same for these matrices of different sizes?
  - (a)  $\begin{bmatrix} A \end{bmatrix}$  and  $\begin{bmatrix} A \\ A \end{bmatrix}$  (b)  $\begin{bmatrix} A \\ A \end{bmatrix}$  and  $\begin{bmatrix} A & A \\ A & A \end{bmatrix}$ .

Prove that all three of those matrices have the same rank r.

- 10 If the entries of a 3 by 3 matrix are chosen randomly between 0 and 1, what are the most likely dimensions of the four subspaces? What if the matrix is 3 by 5?
- 11 (Important) A is an m by n matrix of rank r. Suppose there are right sides b for which Ax = b has no solution.
  - (a) What are all inequalities (< or  $\le$ ) that must be true between m, n, and r?
    - (b) How do you know that  $A^{T}y = 0$  has solutions other than y = 0?
- 12 Construct a matrix with (1,0,1) and (1,2,0) as a basis for its row space and its column space. Why can't this be a basis for the row space and nullspace?
- 13 True or false (with a reason or a counterexample):
  - (a) If m = n then the row space of A equals the column space.
  - (b) The matrices A and -A share the same four subspaces.
  - (c) If A and B share the same four subspaces then A is a multiple of B.
- 14 Without computing A, find bases for its four fundamental subspaces:

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix}.$$

- If you exchange the first two rows of A, which of the four subspaces stay the same? If v = (1, 2, 3, 4) is in the left nullspace of A, write down a vector in the left nullspace of the new matrix.
- **16** Explain why v = (1, 0, -1) cannot be a row of A and also in the nullspace.
- 17 Describe the four subspaces of  $\mathbb{R}^3$  associated with

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad I + A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

18 (Left nullspace) Add the extra column b and reduce A to echelon form:

$$\begin{bmatrix} A & \mathbf{b} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 4 & 5 & 6 & b_2 \\ 7 & 8 & 9 & b_3 \end{bmatrix} \quad \rightarrow \quad \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & 0 & 0 & b_3 - 2b_2 + b_1 \end{bmatrix}.$$

A combination of the rows of A has produced the zero row. What combination is it? (Look at  $b_3 - 2b_2 + b_1$  on the right side.) Which vectors are in the nullspace of  $A^T$  and which are in the nullspace of A?

Following the method of Problem 18, reduce A to echelon form and look at zero rows. The b column tells which combinations you have taken of the rows:

(a) 
$$\begin{bmatrix} 1 & 2 & b_1 \\ 3 & 4 & b_2 \\ 4 & 6 & b_3 \end{bmatrix}$$
 (b) 
$$\begin{bmatrix} 1 & 2 & b_1 \\ 2 & 3 & b_2 \\ 2 & 4 & b_3 \\ 2 & 5 & b_4 \end{bmatrix}$$

From the **b** column after elimination, read off m-r basis vectors in the left nullspace. Those y's are combinations of rows that give zero rows.

20 (a) Check that the solutions to Ax = 0 are perpendicular to the rows:

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 4 & 1 \end{bmatrix} \begin{bmatrix} 4 & 2 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} = ER.$$

- (b) How many independent solutions to  $A^{T}y = 0$ ? Why is  $y^{T}$  the last row of  $E^{-1}$ ?
- 21 Suppose A is the sum of two matrices of rank one:  $A = uv^{T} + wz^{T}$ .
  - (a) Which vectors span the column space of A?
  - (b) Which vectors span the row space of A?
    - (c) The rank is less than 2 if \_\_\_\_\_ or if \_\_\_\_.
    - (d) Compute A and its rank if u = z = (1, 0, 0) and v = w = (0, 0, 1).
- Construct  $A = uv^T + wz^T$  whose column space has basis (1, 2, 4), (2, 2, 1) and whose row space has basis (1, 0), (1, 1). Write A as (3 by 2) times (2 by 2).
- 23 Without multiplying matrices, find bases for the row and column spaces of A:

$$A = \begin{bmatrix} 1 & 2 \\ 4 & 5 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} 3 & 0 & 3 \\ 1 & 1 & 2 \end{bmatrix}.$$

How do you know from these shapes that A cannot be invertible?

- (Important)  $A^{T}y = d$  is solvable when d is in which of the four subspaces? The solution y is unique when the \_\_\_\_\_ contains only the zero vector.
- 25 True or false (with a reason or a counterexample):
  - (a) A and  $A^{T}$  have the same number of pivots.
  - (b) A and  $A^{T}$  have the same left nullspace.
  - (c) If the row space equals the column space then  $A^{T} = A$ .
  - (d) If  $A^{T} = -A$  then the row space of A equals the column space.

- **26** (Rank of AB) If AB = C, the rows of C are combinations of the rows of \_\_\_\_\_. So the rank of C is not greater than the rank of \_\_\_\_\_. Since  $B^TA^T = C^T$ , the rank of C is also not greater than the rank of \_\_\_\_\_.
- 27 If a, b, c are given with  $a \neq 0$ , how would you choose d so that  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$  has rank 1? Find a basis for the row space and nullspace. Show they are perpendicular!
- Find the ranks of the 8 by 8 checkerboard matrix B and the chess matrix C:

The numbers r, n, b, q, k, p are all different. Find bases for the row space and left nullspace of B and C. Challenge problem: Find a basis for the nullspace of C.

Can tic-tac-toe be completed (5 ones and 4 zeros in A) so that rank (A) = 2 but neither side passed up a winning move?

## **Challenge Problems**

- 30 If  $A = uv^T$  is a 2 by 2 matrix of rank 1, redraw Figure 3.5 to show clearly the Four Fundamental Subspaces. If B produces those same four subspaces, what is the exact relation of B to A?
- 31 M is the space of 3 by 3 matrices. Multiply every matrix X in M by

$$A = \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}. \text{ Notice: } A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

- (a) Which matrices X lead to AX = zero matrix?
- (b) Which matrices have the form AX for some matrix X?
- (a) finds the "nullspace" of that operation AX and (b) finds the "column space". What are the dimensions of those two subspaces of M? Why do the dimensions add to (n-r)+r=9?
- Suppose the m by n matrices A and B have the same four subspaces. If they are both in row reduced echelon form, prove that F must equal G:

$$A = \left[ \begin{array}{cc} I & F \\ 0 & 0 \end{array} \right] \qquad B = \left[ \begin{array}{cc} I & G \\ 0 & 0 \end{array} \right].$$